NCAP-KAR-DR-21-11 NEW CAR ASSESSMENT PROGRAM (NCAP) DYNAMIC ROLLOVER RESISTANCE TEST

VOLKSWAGEN AG GERMANY

2021 VOLKSWAGEN ID.4 BEV RWD 5-DOOR MPV

PREPARED BY: APPLUS IDIADA KARCO ENGINEERING, LLC. 9270 HOLLY ROAD ADELANTO, CA 92301



JUNE 23, 2021

FINAL REPORT

PREPARED FOR: U.S. DEPARTMENT OF TRANSPORTATION NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION NEW CAR ASSESSMENT PROGRAM MAIL CODE: NRM-110 1200 NEW JERSEY AVE, SE WASHINGTON, D.C. 20590 The United States Government assumes no liability for the contents of this report or use thereof. If trade or manufacturers' names or products are mentioned, it is only because they are considered essential to the object of the publication and should not be construed as an endorsement. The United States Government does not endorse products or manufacturers.

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Date: <u>June 23, 2021</u>

TECHNICAL REPORT DOCUMENTATION PAGE

A Title and Subtitle Final Report of New Car Assessment Program Dynamic Rollover Resistance Maneuver (Fishhock) Test of a 2021 Volkswagen ID.4 BEV RWD 5-Door MPV Authors Mr. Bernat Ferrer, Program Manager, Applus+ IDIADA KARCO Engineering Mr. Eduard Lucas, Project Engineer, Applus+ IDIADA KARCO Engineering Mr. Eduard Lucas, Project Engineer, Applus+ IDIADA KARCO Engineering Mr. Eduard Lucas, Project Engineering, LLC. 9270 Holly Rd. Adelanto, CA 92301 10. Work Unit No. 9270 Holly Rd. Adelanto, CA 92301 12. Sponsoring Agency Name and Address U. S. Department of Transportation National Highway Traffic Safety Administration New Car Assessment Program 1200 New Jersey Ave., SE Washington, D.C. 20590 15. Supplementary Notes 16. Abstract An NCAP Dynamic Rollover Maneuver (Fishhock) Test was conducted on a 2021 Volkswagen ID.4 BEV RWD 5-Door MPV b Applus+ IDIADA KARCO Engineering, LLC. on June 16, 2021. The vehicle did not experience two-wheel lift. The vehicle's steering angle at 0.3 g lateral acceleration at 50 mph was 25.9 degrees. 17. Key Words New Car Assessment Program (NCAP) NCAP Rollover Resistance Ratings Fishhook Test	1. Report No.	2. Government Accession No.	3. Recipient's Catal	og No.	
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SECTION I

The National Highway Traffic Safety Administration (NHTSA) has engaged Applus+ IDIADA KARCO Engineering, LLC to conduct dynamic rollover testing and gather data from that testing as part of NHTSA's New Car Assessment Program (NCAP).

The purpose of the testing reported herein was to determine if a 2021 Volkswagen ID.4 BEV RWD 5-Door MPV would experience tip-up, defined as simultaneous two-wheel lift of two inches or more at an entry speed of 50 mph or less in the Dynamic Rollover Test Procedure developed by NHTSA. This procedure may be found at www.regulations.gov, docket item NHTSA-2006-26555-0136.

The testing reported herein was accomplished under contract 693JJ920D000011.

SECTION II VEHICLE PREPARATION

A. TEST VEHICLE

The test vehicle was new or in as-new condition, meaning the vehicle had been driven no more than 500 miles prior to the start of dynamic rollover testing. It was acquired through a commercial rental/leasing company. Details of the test vehicle are given in Table 1.

B. TIRES

All tires used were new, and of the same make, model, size, and DOT specification of those installed on the vehicle when purchased new. Tire inflation pressures were in accordance with the recommendations indicated on each vehicle's identification placard. To further reduce the possibility of tire debeading, the tires were mounted to the rims without the use of tire mounting lubricant. Tire specifications are listed in Table 2.

C. VEHICLE LOADING

The multi-passenger load, described in the Fishhook Procedure, was used for all tests. The load and positioning of the load in the vehicle are listed in Table 3.

In addition to water dummies, the loading included instrumentation, a steering machine, and outriggers. Test vehicle bumper assemblies were removed for outrigger installation. The reduction in vehicle weight due to the removal of the bumpers was offset by the additional weight of the outriggers and their mounting system. The outrigger system typically outweighs the bumper assemblies.

	General	Data				
Model year, make, model	2021 Volkswagen ID.4 BEV					
VIN	WVGRMF	PE29MP02x	xxx			
Body style	MPV					
Number of doors	5					
Trim level	-					
Seating positions	Front:	2 nd row	3 rd row	4 th row	5 th row	
	2	3				
Electronic stability control	Yes		1			
4-Wheel ABS (Yes/No)	Yes					
Power steering (Yes/No)	Yes					
Major optional equipment	-					
Odometer at start of testing	60 miles	60 miles				
	Drivetra	ain				
Engine cylinder arrangement	N/A	N/A				
Engine displacement	N/A	N/A				
Transmission type	Automatic	Automatic				
Drive arrangement	RWD	RWD				
	Chass	is				
Track width	F: 66.3 in	(1685 mm)	, R: 65.2 in	(1655 mm)		
Wheelbase	109.0 in (2	109.0 in (2770 mm)				
Curb weight	4593 lb (2083.5 kg)					
Certific	ation Data fror	n Vehicle's	Label			
Vehicle manufactured by	Volkswagen AG Germany					
Date of manufacture	03/21					
GVWR	5644 lb	(2560 kg)				
GAWR Front	2491 lb	(1130 kg)				
GAWR Rear	3263 lb	(1480 kg)				

Table 1. Test Vehicle Data

Tire Manufacturer	Hankook
Tire Model	Kinergy AS x EV
Tire Size	Front: 235/55R19 Rear: 255/50R19
Load rating	Front: 105 Rear: 107
Speed rating	Front: T Rear: T
Treadwear grade	Front: 500 Rear: 500
Traction grade	Front: A Rear: A
Temperature grade	Front: A Rear: A
Location of "Recommended Tire Pressure" label	Driver's door jamb
Recommended cold tire pressure	Front: 42 psi, (290 kPa) Rear: 42 psi, (290 kPa)
DOT code (8 last digits)	Front: 9UH0 2220 Rear: 9UH0 4120

Table 2. Tire Information

Table 3. Vehicle Loading

Water dummy and other loading	Multi-Passenger Configuration 3 water dummies in second row			
Water dummy weight	132 lb (60 kg)			
Fuel level	N/A			
Weight as Tested				
Left front	1251 lb (567.5 kg)			
Right front	1274 lb (578.0 kg)			
Left rear	1367 lb (620.0 kg)			
Right rear	1311 lb (594.5 kg)			
Total weight	5203 lb (2360.0 kg)			

D. STEERING CONTROLLER

Precise steering control is accomplished using a steering machine designed and constructed by ABD. It can provide up to 45 ft-lb torque and at rates over 1000 deg/sec. The integrated angle encoder has an unlimited range with a resolution of 0.25 degrees and an accuracy of ± 0.25 degrees. The steering motor is controlled by RC8 software from ABD, which also acts as the data acquisition system.

E. REAL-TIME CONTROLLER AND DATA ACQUISITION

Data acquisition is achieved using a MOSES Meas X, which also serves as the real-time system for the steering controller. Data from the OXTS, including Longitudinal, Lateral, and Vertical Acceleration, Roll, Yaw, and Pitch Rate, Forward and Lateral Velocity, Roll and Pitch Angle, are sent over Ethernet to the MOSES MeasX. The Oxford IMUs are calibrated per the manufacturer's recommended schedule (Table 5).

Two video cameras were used to record the Fishhook runs. They were positioned nominally as shown in Figure 1. The recorded video was reviewed after the Fishhook runs to check for any two-wheel lift. If any two-wheel lift was observed, four infrared distance measuring sensors for measurement of wheel lift (two sensors at each wheel) were then mounted for use in subsequent confirmation Fishhook tests.

F. EQUIPMENT WEIGHT

Table 4 lists the equipment and associated weights outlined in the NHTSA Laboratory Test Procedure for Dynamic Rollover and the equipment at Applus+ IDIADA KARCO Engineering, LLC used for this specific test program.

Equipment	Location	Equipment Weight (Ib)		
		NHTSA*	IDIADA	
Data Acquisition System	Front passenger seat	58	35	
GPS Inertial unit	At the chassis in a flat and rigid surface		7	
Steering Machine	Handwheel	31	51	
Steering Machine Electronics Box	Passenger row foot well behind the front passenger seat. If vehicle does not have a rear passenger row foot well, the Electronics Box should be placed in the front passenger seat footwell.	39	39	
	Total	128	132	

Table 4. Weight of In-Cab Test Equipment

* Table A.1 from US DOT NHTSA - Laboratory Test Procedure for Dynamic Rollover - The Fishhook Maneuver Test Procedure - New Car Assessment Program (NCAP) - March 2013

G. SENSORS

A list of the sensors is given in Table 5.

H. OTHER VEHICLE PREPARATION

In addition to installation and preparation discussed above, the test vehicle was prepared as follows:

- Front and rear bumpers were removed.
- Outrigger mounts were installed in the bumper locations and titanium outriggers were fastened to these mounts.
- Airbags were removed or otherwise disabled.

Photographs of the vehicle tested are given in Appendix A.

Table 5. Sensor Specifications

Туре	Measured Variable	Sensor	Range	Resolutio n	Accuracy	Specifics	Serial Number	Calibration	Unit
Multi-Axis Inertial Sensing System Distance Measuring System Radar Speed Sensor Data Flag (Roll Rate Flag)	Longitudinal speed Lateral speed Longitudinal acc. Lateral acc. Roll angle Pitch angle Yaw angle Roll rate Pitch rate Yaw rate	GPS inertial unit	- ±100 ±100 ±100 ±100 ±100 ±100 ±100 ±10	0.01 ^o /s 0.01 m/s2	$\begin{array}{c} \pm 0.1 \\ \pm 0.1 \\ \pm 0.1 \\ \pm 0.1 \\ \pm 0.05 \\ \pm 0.05 \\ \pm 0.1 \end{array}$	OXTS (RT)	1611	By: IDIADA Date: 6/16/2020 Due: 6/16/2022	km/h km/s² m/s² o o o o/s o/s o/s o/s
Angle Encoder ¹ Data Flag (Handwheel Command Flag)	Steering angle Steering torque	Steering wheel robot	>1000 60	0.25 deg	±0.20 ±0.25	ABD	769/17	By: IDIADA Date: 8/01/2019 Due: 8/01/2021	∘ Nm
Infrared Distance Measuring System	Tire wheel lift	Height sensors	300- 700	0.01 mm	±0.8	OPTImess	OMS 4140- 3098 OMS 4140- 4506 OMS 4140- 4508 OMS 4140- 4509	By: IDIADA Date: 7/7/2020 Due: 7/7/2021	mm
Load Cell	Brake Pedal Force	Load Cell	±600	-	±0.5	Novatech	48305	By: IDIADA Date: 3/27/2020 Due: 3/27/2021	N
Acquisition system	-	Acquisition system	200	-	-	IDIADA Moses MEAS X	180749	By: IDIADA Date: 05/21/2020 Due: 05/21/2022	-

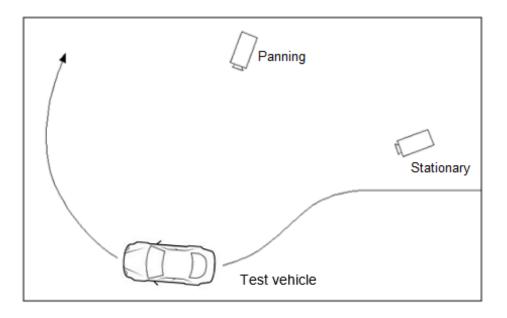


Figure 1. Nominal Position of Video Cameras for Fishhook Tests

SECTION III TEST PROCEDURES

A. TEST PROCEDURE OVERVIEW

This test was conducted in accordance with NHTSA's NCAP Rollover Resistance Test Procedure (Fishhook) as described in the Federal Register (68 FR 59250). Detailed descriptions of the test procedure, pass/fail criteria, and data acquisition specifications may be found at docket NHTSA-2001-9663.

There are two major components of the test procedure, the Slowly Increasing Steer (SIS) pre-test and the Fishhook test.

The Slowly Increasing Steer (SIS) maneuver was used to characterize the steady state lateral dynamics of each vehicle, and is based on the "Constant Speed, Variable Steer" test defined in SAE J266. The maneuver is used to determine the handwheel angle that produces a lateral acceleration of 0.3 g at 50 mph. This handwheel angle is then used to determine the magnitude of steering to be used for the NHTSA Fishhook maneuver.

SIS tests were performed at a constant speed of 50 mph. Handwheel angle was input at a rate of 13.5 deg/sec, from 0 to an angle that provided at least 0.55 g. Three tests were conducted in each direction, and the data for the six runs were averaged to obtain the handwheel angle that produced 0.3 g at 50 mph.

The Fishhook test is a programmed steering maneuver that is implemented via the steering controller. The vehicle was initially steered in one direction and then the steering was reversed. The timing, magnitude and rate of the steering were prescribed by the Fishhook Procedure.

To begin the maneuver, the vehicle was driven in a straight line at a speed slightly greater than the desired entrance speed. The driver then released the throttle. When the vehicle was at the target speed, the steering controller automatically initiated the steering maneuver. Following completion of the steering reversal, the handwheel position was maintained for 3 seconds, and then returned to zero angle in 2 seconds.

The tests were conducted in both left-right and right-left directions. The "Default" test series used a handwheel angle equal to 6.5 times the handwheel angle that produced 0.3 g at 50 mph in the SIS tests, and initial vehicle speeds beginning at 35 mph and concluding up to 50 mph (if no two-wheel lift occurs). Supplemental tests were also done, as specified in the Fishhook Procedure.

A. TEST CONDITIONS

1. Test Surface

The tests were conducted on the Vehicle Dynamics Area (VDA) at HONDA Proving Center facility, located in Cantil, California, on 6/16/2021. The VDA has a smooth, flat (slope less than 0.5% throughout) asphaltic concrete surface. Its dimensions are as shown in Figure 2. The test was accomplished using an ASTM E1136 tire with an inflation pressure of 35 (\pm 0.5) psi at a test speed of 40 (\pm 0.5) mph. The net slip angle of the test tire for each test run was 7.5 deg. The surface friction measurement results are shown in Table 6.

Table 6. Lateral Surface Friction

Date of surface friction measurements	6/16/2021
Average lateral friction coefficient	0.92
Date of peak braking friction measurements	11/9/2020
Peak braking coefficient	0.92

2. Fishhook Handwheel Angles

The 0.3 g handwheel angle obtained from the SIS tests and the handwheel angles used in the Fishhook tests are shown in Table 7.

0.3 g handwheel angle (from SIS tests at 50 mph)	25.9°
5.5 scalar handwheel angle for Fishhook Test	142.5°
6.5 scalar handwheel angle for Fishhook Test	168.4°

Table	7.	Handwheel	Angles
-------	----	-----------	--------

3. Weather Conditions

The weather conditions, recorded at the end of testing, are shown in Table 8.

Ambient temperature	99.4 °F (37.4 °C)
Wind Speed	2.2 mph (1.0 m/s)
Wind Direction	E

Table 8. Weather Conditions

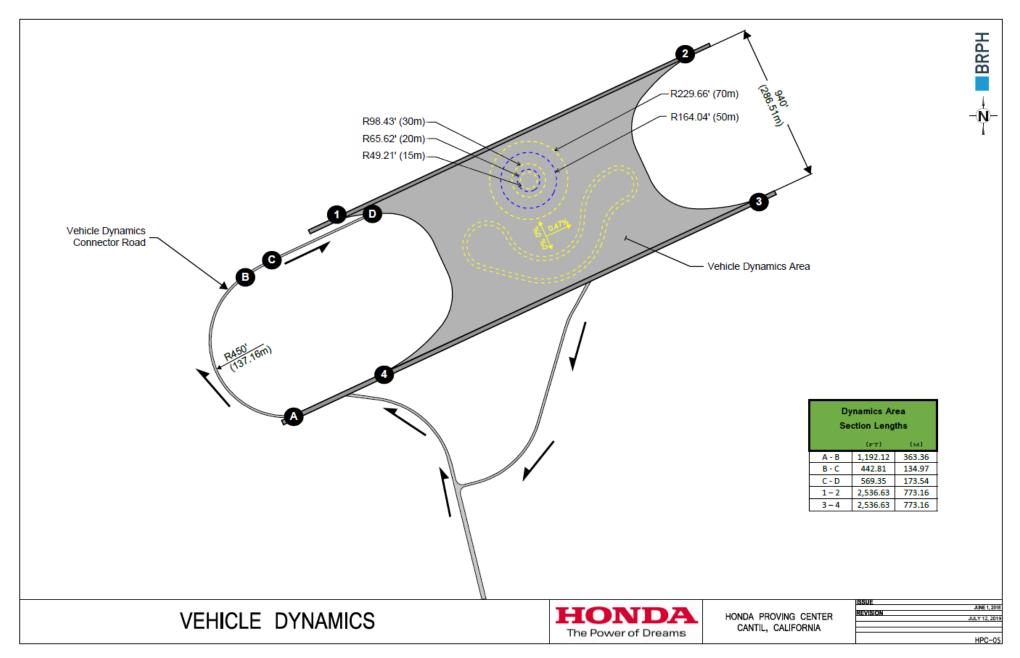


Figure 2. Vehicle Dynamics Area at Honda Proving Center

SECTION IV

RESULTS

There is Appendix A with the photographic documentation. The test run log is given in Appendix B. A summary of the Slowly Increasing Steer Test is given in Appendix C. Appendix D contains time history plots for the 50 mph runs and any runs which resulted in two-wheel lift. For the 2021 Volkswagen ID.4 BEV RWD 5-Door MPV, there was no two-wheel lift at any test condition.

APPENDIX A PHOTOGRAPHS

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Figure A8	Instrumentation in Test Vehicle	A-8
Figure A9	Steering Controller and Computer	A-9
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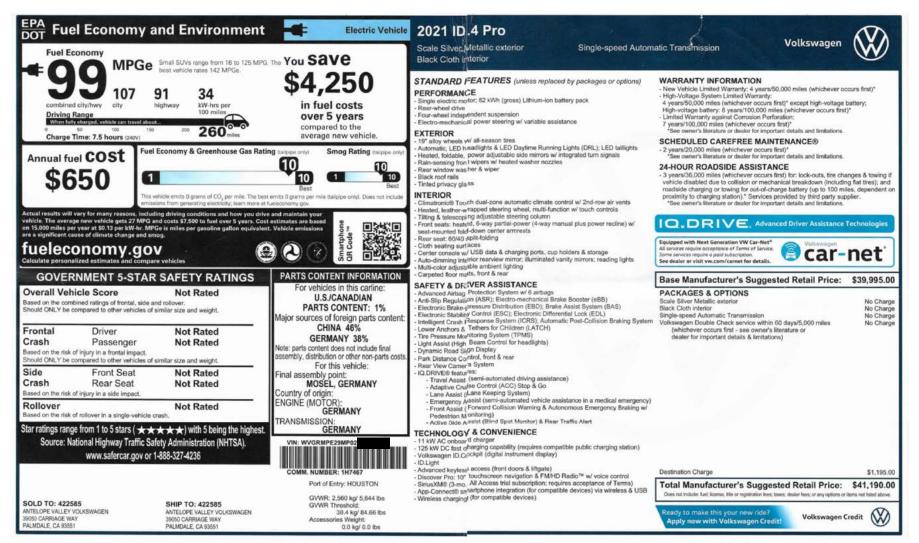


Figure A1. Monroney Label



Figure A2. Right Front View, Test Vehicle As-Delivered



Figure A3. Left Rear View, Test Vehicle As-Delivered



Figure A4. Left Front View, Test Vehicle in Test Condition



Figure A5. Right Rear View, Test Vehicle in Test Condition

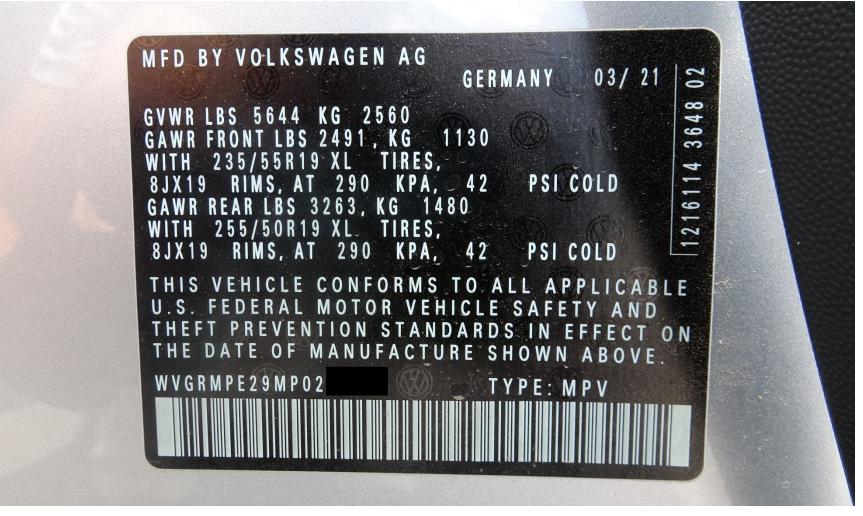


Figure A6. Vehicle's Certification Label

	REINSEIGINEMEIN	ING INFORMATION	T LE CHARGEMENT	*
THE COMB E POIDS TOTAL	INED WEIGHT OF OCCUPANTS AN	MBRE DE PLACES ¦TOTAL 5 A ND CARGO SHOULD NEVER EXCEED Ement ne doit Jamais Depasser	RONT/ 2 REAR/ 3 VANT 2 ARRIERE 3 430 KG OR 948 BS KG OU 948 BS	0 000 C
TIRE PNEU	SIZE DIMENSIONS	COLD TIRE PRESSURE PRESSION DE PNEUS A FROID	SEE OWNER'S MANUAL	1A 010
FRONT/AVANT	235/55 R19 105T XL	290 KPA / 42 PSI	FOR ADDITIONAL INFORMATION	*
REAR/ARRIERE	255/50 R19 107T XL	290 KPA / 42 PSI	VOIR LE MANUEL DE	-
SPARE/DE SECOURS	NONE	NONE	L'USAGER POUR PLUS DE RENSEIGNEMENTS	

Figure A7. Vehicle's Tire Information Placard

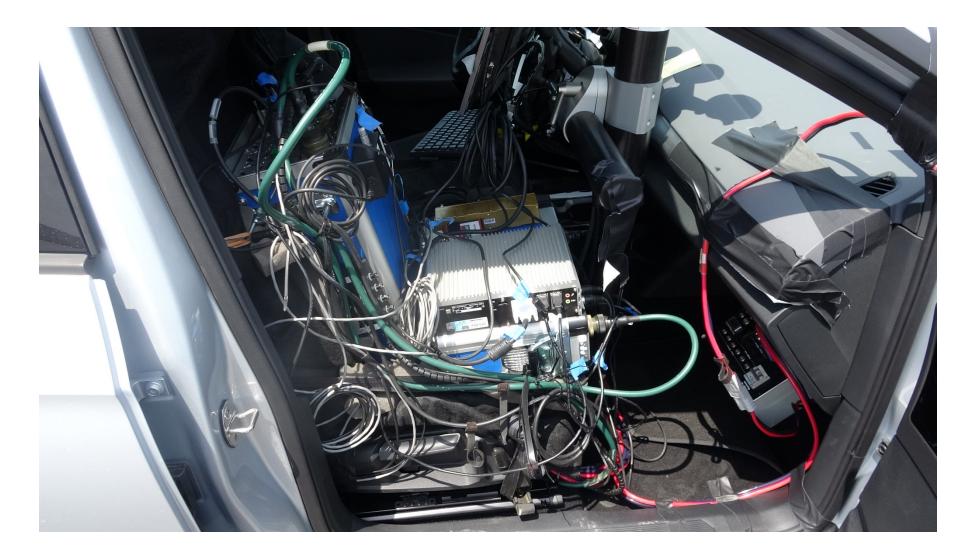


Figure A8. Instrumentation in Test Vehicle

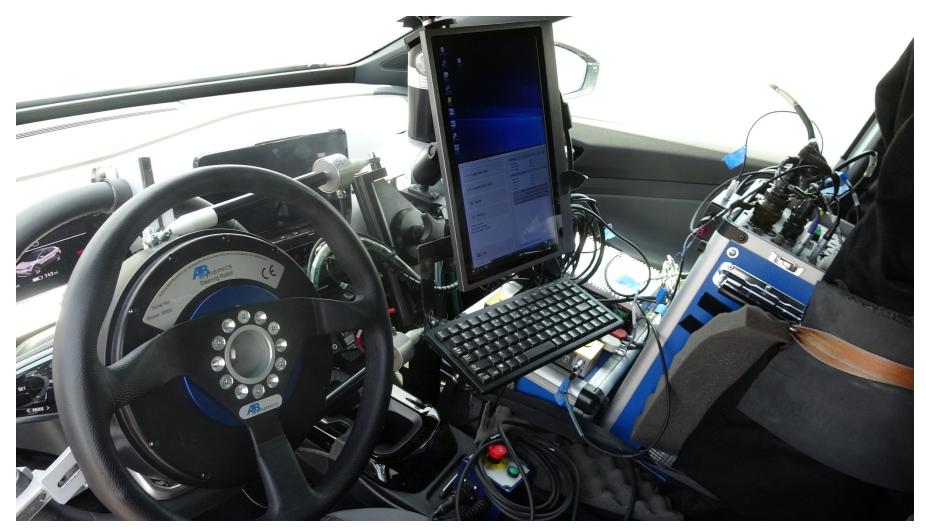


Figure A9. Steering Controller and Computer



Figure A10. Ballast Condition

APPENDIX B TEST RUN LOG

Vehicle: 2021 VOLKSWAGEN ID.4 BEV RWD 5-DOOR MPV

Driver: Omar Gonzalez

Date: 6/16/2021

Run Number	Test Type	Speed (mph)	Handwheel Angle (deg)	Dir. of First Steer	2 Wheel Lift	Notes
1	Tire Warm-Up	35	30.0	Left	N/A	Resulted in $ay = 0.23g$
2	"	"	56.5	"	"	Resulted in ay = 0.40g
3	"	"	"	"	"	
4	11	"	"	"	"	
5	2x SWA last cycle	"	113.0	=	=	2x SWA last cycle
6	Static	0	0	N/A	N/A	
7	Steady State	50	0	N/A	N/A	
8	Slowly Increasing Steer	50	30.0	Left	N/A	
9	Ш	"	37.1	Left	"	HW angle at 0.3 g = -26.6
10	Ш	"	"	Left	"	HW angle at 0.3 g = -26.8
11	Ш	"	"	Left	"	HW angle at 0.3 g = -26.5
12	Ш	"	"	Right	"	HW angle at 0.3 g = 25.1
13	Ш	"	"	Right	"	HW angle at 0.3 g = 25.2
14	п	"	"	Right	"	HW angle at 0.3 g = 25.4
						Average = 25.9
15	Fishhook 6.5 Scalar	35	168.4	Left	No	
16	"	40	"	"	"	
17	II	45	II	=	=	
18	II	47.5	"	"	"	
19	II	50	"	н	"	
20	Fishhook 6.5 Scalar	35	168.4	Right	No	
21	II	40	"	"	"	
22	n	45	"	"	"	

Vehicle: 2021 VOLKSWAGEN ID.4 BEV RWD 5-DOOR MPV

Driver: Omar Gonzalez

Date: 6/16/2021

Run Number	Test Type	Speed (mph)	Handwheel Angle (deg)	Dir. of First Steer	2 Wheel Lift	Notes
23	"	47.5	"	"	=	
24	II	50	"	"	=	
25	Fishhook 5.5 Scalar	45	142.5	Left	No	
26	11	47.5	"	"	-	
27	II	50	=	"	=	
28	Fishhook 5.5 Scalar	45	142.5	Right	No	
29	Η	47.5	II	I	=	
30	Π	50	"	"	"	

APPENDIX C SLOWLY INCREASING STEER TEST WORKSHEET

2021 Volkswagen ID.4 RWD 5-Door MPV, Multi-Passenger Configuration, Test Date: 6/16/2021



Slowly Increasing Steer



Vehicle: 2021 Volkswagen ID.4 Test Date: 06/16/2021 Analysis Date: 06/16/2021 Analysed by: EL Executed by: OG Configuration: ESC on Weight Condition: Test condition Test Track: Dynamic Platform Test Speed: 50 mph

Run	Dir	Start	End	Speed	Index	HW angle	ay [g]	6.5x HW	Ramp	5.5x HW	Ramp	R2	Zero	Zero
	of	speed	speed	red	of ay	[deg]	0.3g	angle	time [sec]	angle	time [sec]		Begin	End
	Steer	[mph]	[mph]	[%]		at 0.3g	index	[deg]	at 6.5x	[deg]	at 5.5x		index	index
sis_002	L	50.0	0.1	99.8	602	-26.6	-0.300	-172.8	-0.2399	-146.2	-0.2030	0.9699	0	166
sis_003	L	50.1	-0.1	100.2	594	-26.8	-0.300	-174.2	-0.2419	-147.4	-0.2047	0.9966	0	172
sis_004	L	49.8	0.0	99.9	594	-26.5	-0.300	-172.1	-0.2391	-145.6	-0.2023	0.9918	0	155
sis_005	R	50.1	0.4	99.3	577	25.1	0.300	163.0	0.2264	137.9	0.1916	0.9981	0	141
sis_006	R	50.0	-0.0	100.1	577	25.2	0.300	163.8	0.2275	138.6	0.1925	0.9868	0	133
sis_007	R	50.1	0.0	99.9	595	25.4	0.300	165.4	0.2297	139.9	0.1943	0.9786	0	167

Mean:

25.9

Steering Controller Input values

Scalar 6.5 values:	
Initial HW angle:	168.4 deg
Reversal HW angle:	-168.4 deg
Scalar 5.5 values:	
Initial HW angle:	142.5 deg
Reversal HW angle:	-142.5 deg

APPENDIX D TIME HISTORY PLOTS

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Figure D16	Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph	D-16

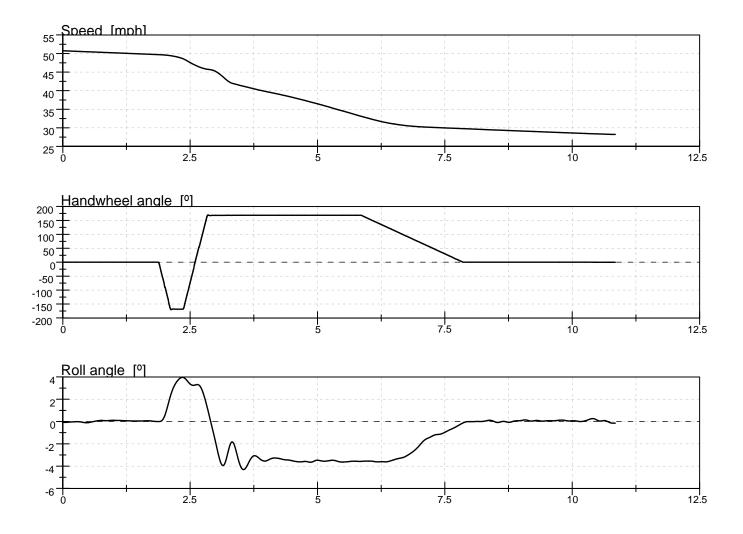


Figure D1. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, L-R, 50 mph

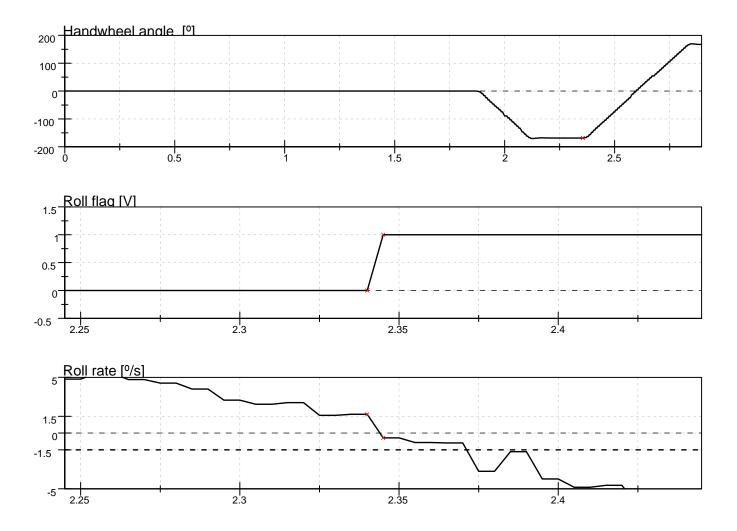


Figure D2. Steering Machine Operation Time History Plots for Default Test Series, L-R, 50 mph

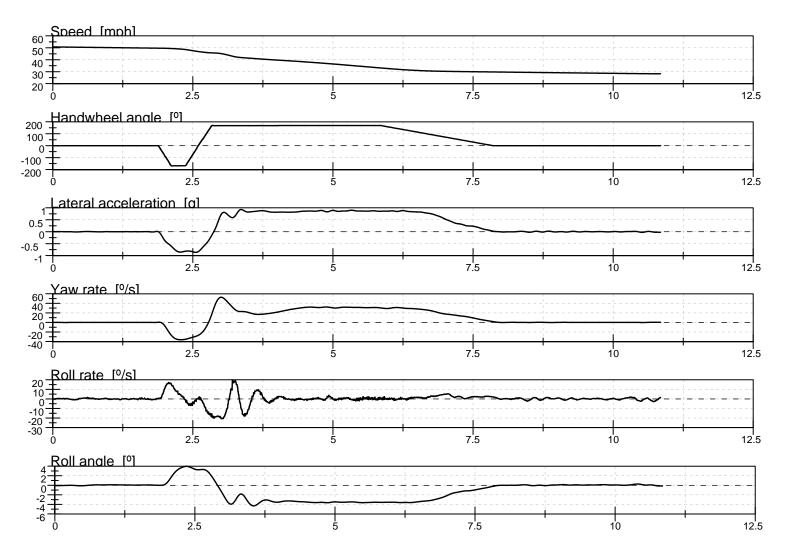


Figure D3. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots For Default Test Series, L-R, 50 mph

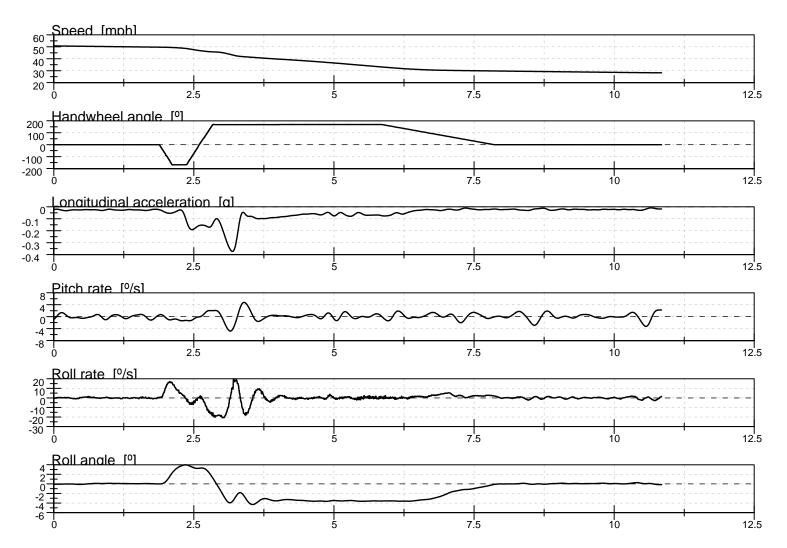


Figure D4. Pitch Rate and Longitudinal Acceleration Time History Plots for Default Test Series, L-R, 50 mph

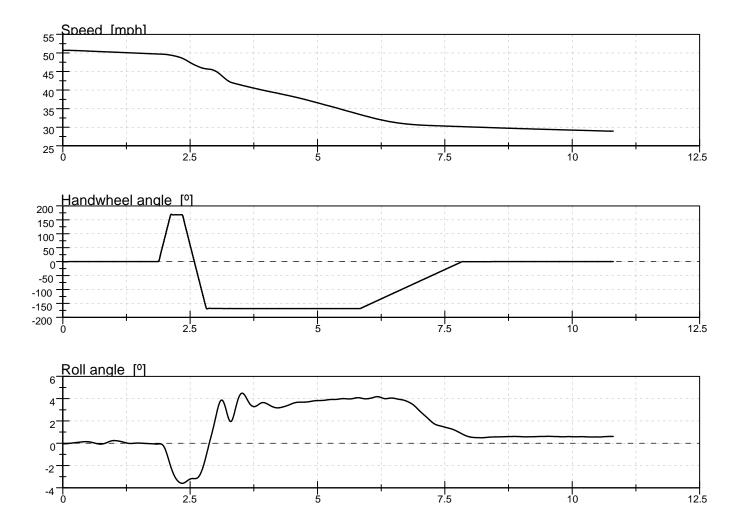


Figure D5. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, R-L, 50 mph

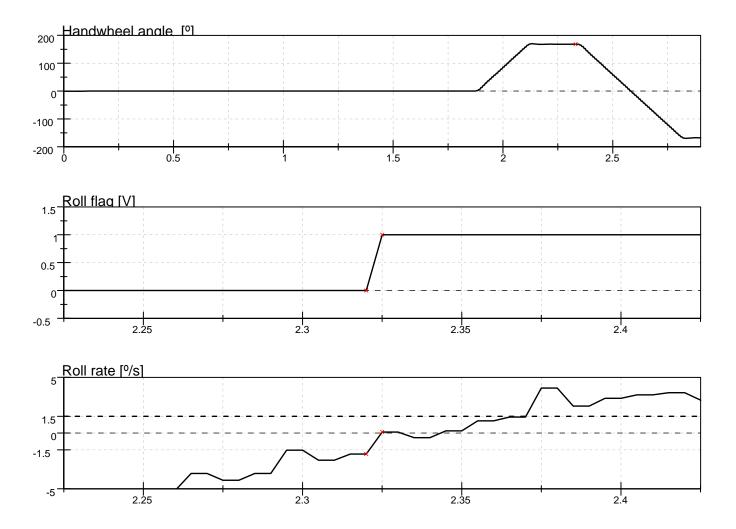


Figure D6. Steering Machine Operation Time History Plots for Default Test Series, R-L, 50 mph

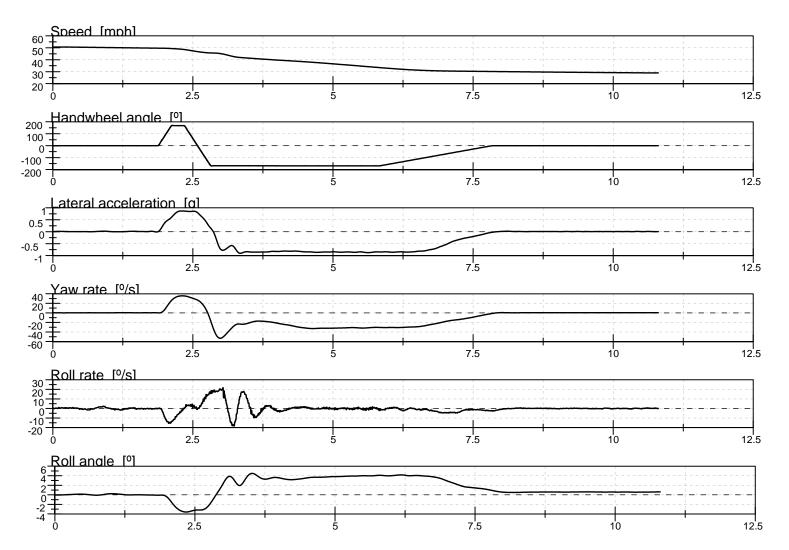


Figure D7. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Default Test Series, R-L, 50 mph

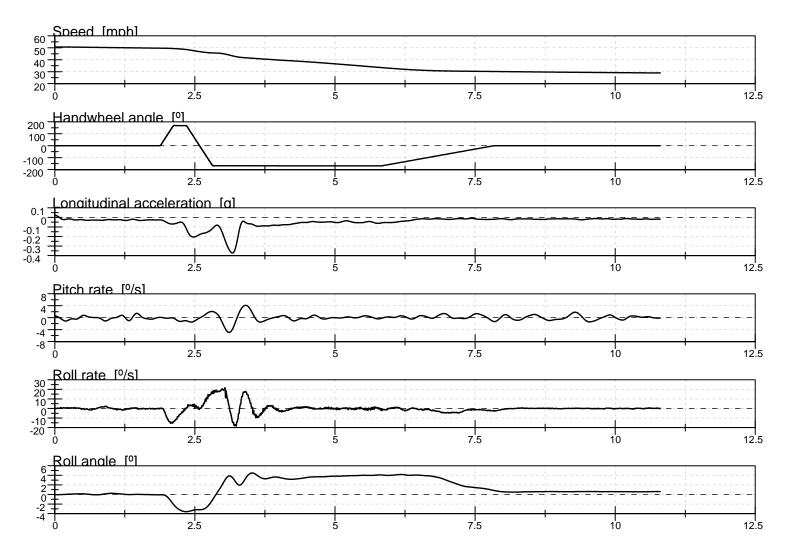


Figure D8. Pitch Rate and Longitudinal Acceleration Time History Plots or Default Test Series, R-L, 50 mph

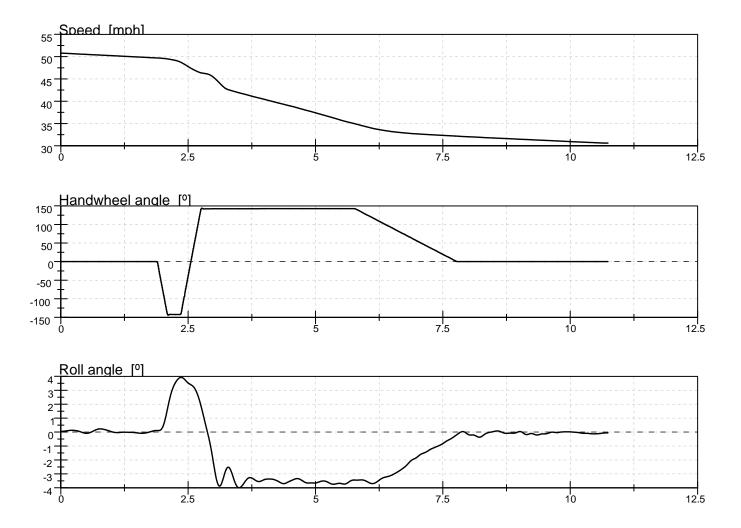


Figure D9. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

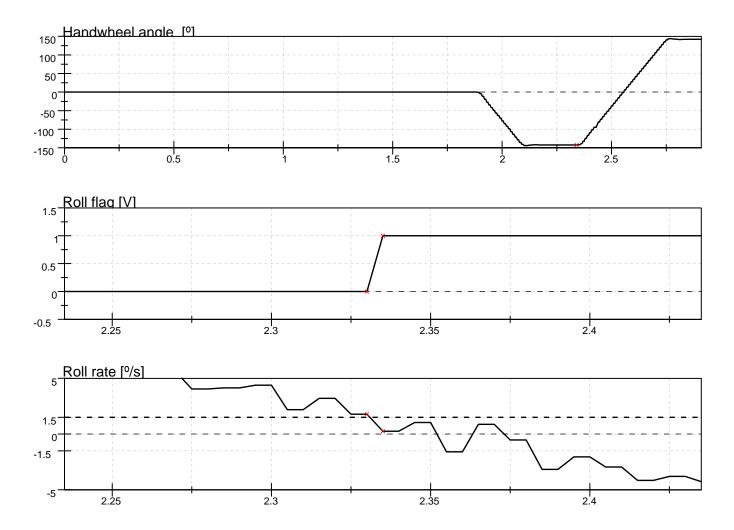


Figure D10. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

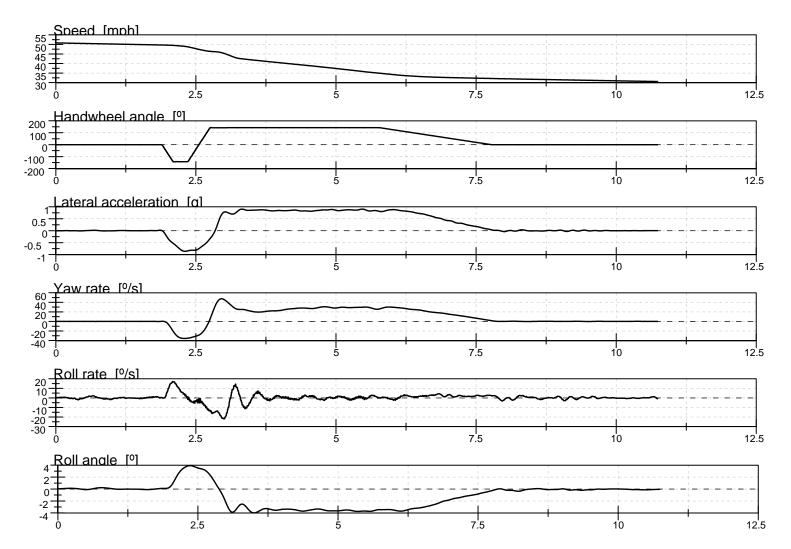


Figure D11. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

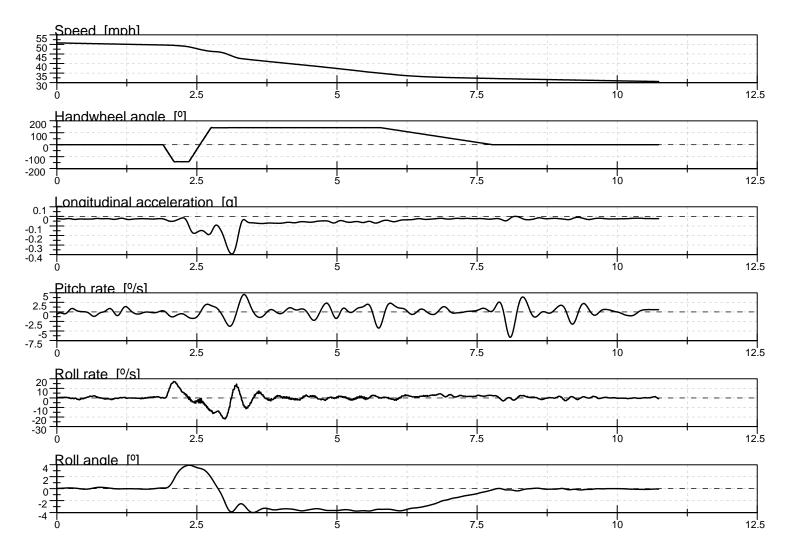


Figure D12. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

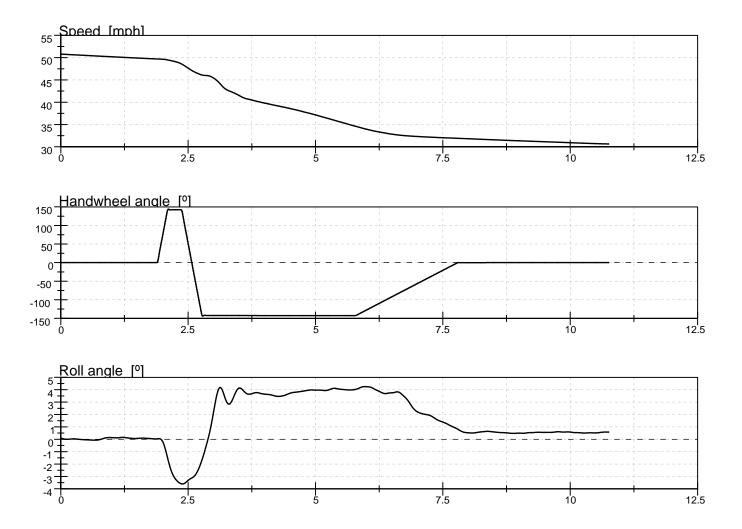


Figure D13. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

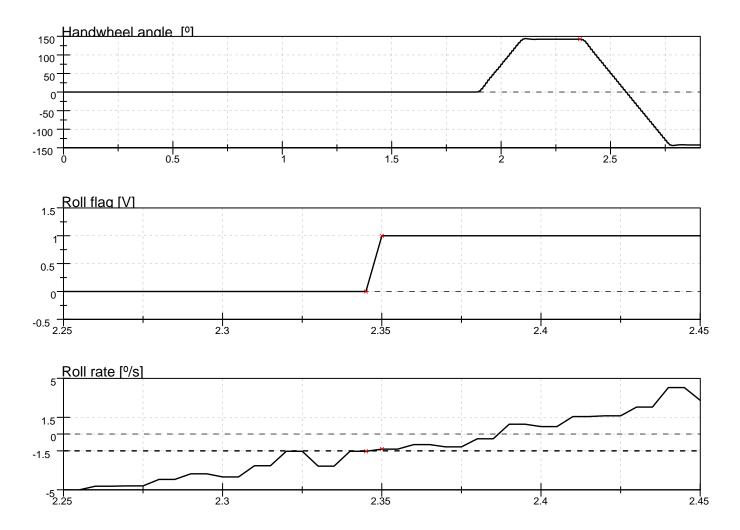


Figure D14. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

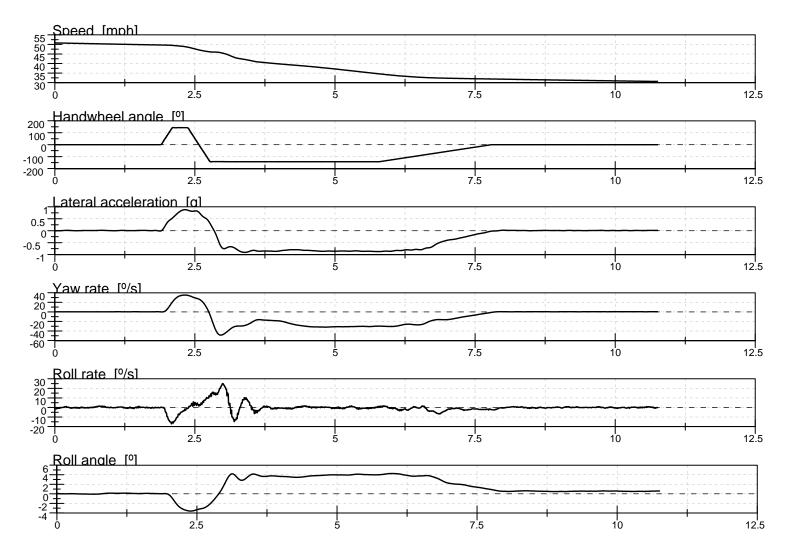


Figure D15. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

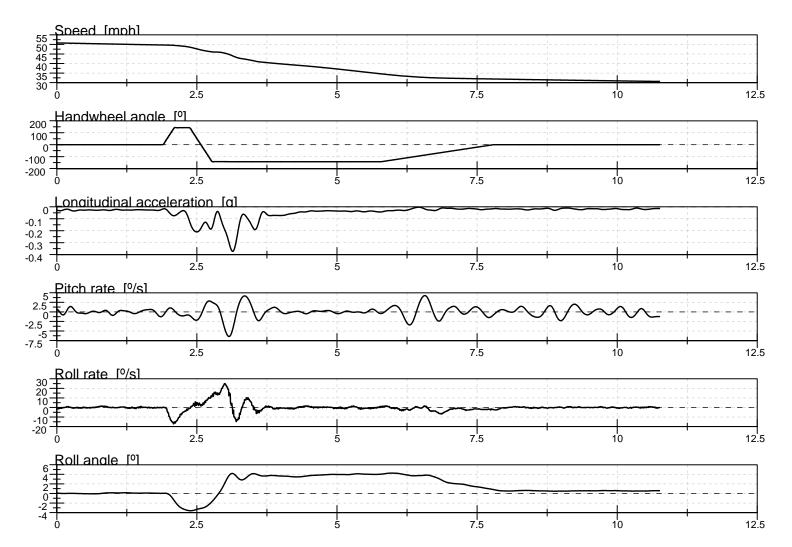


Figure D16. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph