

NCAP-KAR-DR-21-02
NEW CAR ASSESSMENT PROGRAM (NCAP)
DYNAMIC ROLLOVER RESISTANCE TEST

KIA MOTORS MANUFACTURING GEORGIA, INC.

2021 KIA SORENTO FWD 5-DOOR SUV

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FINAL REPORT

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| 16. Abstract An NCAP Dynamic Rollover Maneuver (Fishhook) Test was conducted on a 2021 Kia Sorento FWD 5-Door SUV by Applus+ IDIADA KARCO Engineering, LLC. on February 5, 2021. The vehicle did not experience two-wheel lift. The vehicle's steering angle at 0.3 g lateral acceleration at 50 mph was 27.7 degrees | | | |
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SECTION I

INTRODUCTION

The National Highway Traffic Safety Administration (NHTSA) has engaged Applus+ IDIADA KARCO Engineering, LLC to conduct dynamic rollover testing and gather data from that testing as part of NHTSA's New Car Assessment Program (NCAP).

The purpose of the testing reported herein was to determine if a 2021 Kia Sorento FWD 5-Door SUV would experience tip-up, defined as simultaneous two-wheel lift of two inches or more at an entry speed of 50 mph or less in the Dynamic Rollover Test Procedure developed by NHTSA. This procedure may be found at www.regulations.gov, docket item NHTSA-2006-26555-0136.

The testing reported herein was accomplished under contract 693JJ920D000011.

SECTION II

VEHICLE PREPARATION

A. TEST VEHICLE

The test vehicle was new or in as-new condition, meaning the vehicle had been driven no more than 500 miles prior to the start of dynamic rollover testing. It was acquired through a commercial rental/leasing company. Details of the test vehicle are given in Table 1.

B. TIRES

All tires used were new, and of the same make, model, size, and DOT specification of those installed on the vehicle when purchased new. Tire inflation pressures were in accordance with the recommendations indicated on each vehicle's identification placard. To further reduce the possibility of tire debanding, the tires were mounted to the rims without the use of tire mounting lubricant. Tire specifications are listed in Table 2.

C. VEHICLE LOADING

The multi-passenger load, described in the Fishhook Procedure, was used for all tests. The load and positioning of the load in the vehicle are listed in Table 3.

In addition to water dummies, the loading included instrumentation, a steering machine, and outriggers. Test vehicle bumper assemblies were removed for outrigger installation. The reduction in vehicle weight due to the removal of the bumpers was offset by the additional weight of the outriggers and their mounting system. The outrigger system typically outweighs the bumper assemblies.

Table 1. Test Vehicle Data

| General Data | | | | | |
|---|--|---------------------|---------------------|---------------------|---------------------|
| Model year, make, model | 2021 Kia Sorento | | | | |
| VIN | 5XYRL4LC5MG02xxxx | | | | |
| Body style | SUV | | | | |
| Number of doors | 5 | | | | |
| Trim level | S | | | | |
| Seating positions | Front: | 2 nd row | 3 rd row | 4 th row | 5 th row |
| | 2 | 3 | | | |
| Electronic stability control | Yes | | | | |
| 4-Wheel ABS (Yes/No) | Yes | | | | |
| Power steering (Yes/No) | Yes | | | | |
| Major optional equipment | - | | | | |
| Odometer at start of testing | 9 miles | | | | |
| Drivetrain | | | | | |
| Engine cylinder arrangement | Inline 4 | | | | |
| Engine displacement | 2.5 L | | | | |
| Transmission type | Automatic | | | | |
| Drive arrangement | FWD | | | | |
| Chassis | | | | | |
| Track width | F: 68.5 in (1740 mm), R: 68.8 in (1747 mm) | | | | |
| Wheelbase | 111.0 in (2820 mm) | | | | |
| Curb weight | 3778 lb (1713.5 kg) | | | | |
| Certification Data from Vehicle's Label | | | | | |
| Vehicle manufactured by | Kia Motors Manufacturing Georgia, Inc. | | | | |
| Date of manufacture | DEC/16/20 | | | | |
| GVWR | 5357 lb (2430 kg) | | | | |
| GAWR Front | 2866 lb (1300 kg) | | | | |
| GAWR Rear | 2976 lb (1350 kg) | | | | |

Table 2. Tire Information

| | |
|---|---|
| Tire Manufacturer | Continental |
| Tire Model | Cross Contact |
| Tire Size | Front: 235/60R18 Rear: 235/60R18 |
| Load rating | Front: 103 Rear: 103 |
| Speed rating | Front: H Rear: H |
| Treadwear grade | Front: 480 Rear: 480 |
| Traction grade | Front: A Rear: A |
| Temperature grade | Front: A Rear: A |
| Location of "Recommended Tire Pressure" label | Driver's door jamb |
| Recommended cold tire pressure | Front: 35 psi, (240 kPa) Rear: 35 psi, (240 kPa) |
| DOT code (8 first digits) | Front: 1HW 03HCF Rear: 1HW 03HCF |

Table 3. Vehicle Loading

| | |
|-------------------------------|--|
| Water dummy and other loading | Multi-Passenger Configuration 1 dummy in second row, 2 dummies in third row |
| Water dummy weight | 525.1 lb (238.2 kg) |
| Fuel level | Full |
| Weight as Tested | |
| Left front | 1262 lb (572.5 kg) |
| Right front | 1206 lb (547.0 kg) |
| Left rear | 1230 lb (558.0 kg) |
| Right rear | 1203 lb (545.5 kg) |
| Total weight | 4901 lb (2223.0 kg) |

D. STEERING CONTROLLER

Precise steering control is accomplished using a steering machine designed and constructed by ABD. It can provide up to 45 ft-lb torque and at rates over 1000 deg/sec. The integrated angle encoder has an unlimited range with a resolution of 0.25 degrees and an accuracy of ± 0.25 degrees. The steering motor is controlled by RC8 software from ABD, which also acts as the data acquisition system.

E. REAL-TIME CONTROLLER AND DATA ACQUISITION

Data acquisition is achieved using a MOSES Meas X, which also serves as the real-time system for the steering controller. Data from the OXTS, including Longitudinal, Lateral, and Vertical Acceleration, Roll, Yaw, and Pitch Rate, Forward and Lateral Velocity, Roll and Pitch Angle, are sent over Ethernet to the MOSES MeasX. The Oxford IMUs are calibrated per the manufacturer's recommended schedule (Table 5).

Two video cameras were used to record the Fishhook runs. They were positioned nominally as shown in Figure 1. The recorded video was reviewed after the Fishhook runs to check for any two-wheel lift. If any two-wheel lift was observed, four infrared distance measuring sensors for measurement of wheel lift (two sensors at each wheel) were then mounted for use in subsequent confirmation Fishhook tests.

F. EQUIPMENT WEIGHT

Table 4 lists the equipment and associated weights outlined in the NHTSA Laboratory Test Procedure for Dynamic Rollover and the equipment at Applus+ IDIADA KARCO Engineering, LLC used for this specific test program.

Table 4. Weight of In-Cab Test Equipment

| Equipment | Location | Equipment Weight (lb) | |
|----------------------------------|--|-----------------------|------------|
| | | NHTSA* | IDIADA |
| Data Acquisition System | Front passenger seat | 58 | 35 |
| GPS Inertial unit | At the chassis in a flat and rigid surface | | 7 |
| Steering Machine | Handwheel | 31 | 51 |
| Steering Machine Electronics Box | Passenger row foot well behind the front passenger seat. If vehicle does not have a rear passenger row foot well, the Electronics Box should be placed in the front passenger seat footwell. | 39 | 39 |
| | Total | 128 | 132 |

* Table A.1 from US DOT NHTSA - Laboratory Test Procedure for Dynamic Rollover - The Fishhook Maneuver Test Procedure - New Car Assessment Program (NCAP) - March 2013

G. SENSORS

A list of the sensors is given in Table 5.

H. OTHER VEHICLE PREPARATION

In addition to installation and preparation discussed above, the test vehicle was prepared as follows:

- Front and rear bumpers were removed.
- Outrigger mounts were installed in the bumper locations and titanium outriggers were fastened to these mounts.
- Airbags were removed or otherwise disabled.

Photographs of the vehicle tested are given in Appendix A.

Table 5. Sensor Specifications

| Type | Measured Variable | Sensor | Range | Resolution | Accuracy | Specifics | Serial Number | Calibration | Unit |
|---|---|----------------------|--|-----------------------------------|--|---------------------|--|---|--|
| <i>Multi-Axis Inertial Sensing System</i> <i>Distance Measuring System</i> <i>Radar Speed Sensor</i> <i>Data Flag (Roll Rate Flag)</i> | Longitudinal speed Lateral speed Longitudinal acc. Lateral acc. Roll angle Pitch angle Yaw angle Roll rate Pitch rate Yaw rate | GPS inertial unit | - - ±100 ±100 ±100 ±100 ±100 ±100 ±100 ±100 | 0.01 %/s 0.01 m/s ² | ±0.1 ±0.1 ±0.1 ±0.1 ±0.05 ±0.05 ±0.1 ±0.1 ±0.1 | OXTS (RT) | 1611 | By: IDIADA Date: 6/16/2020 Due: 6/16/2022 | km/h km/h m/s ² ° ° ° %/s %/s %/s |
| <i>Angle Encoder¹</i> <i>Data Flag (Handwheel Command Flag)</i> | Steering angle Steering torque | Steering wheel robot | >1000 60 | 0.25 deg | ±0.20 ±0.25 | ABD | 769/17 | By: IDIADA Date: 8/01/2019 Due: 8/01/2021 | ° Nm |
| <i>Infrared Distance Measuring System</i> | Tire wheel lift | Height sensors | 300-700 | 0.01 mm | ±0.8 | OPTImess | OMS 4140-3098 OMS 4140-4506 OMS 4140-4508 OMS 4140-4509 | By: IDIADA Date: 7/7/2020 Due: 7/7/2021 | mm |
| <i>Load Cell</i> | Brake Pedal Force | Load Cell | ±600 | - | ±0.5 | Novatech | 48305 | By: IDIADA Date: 3/27/2020 Due: 3/27/2021 | N |
| <i>Acquisition system</i> | - | Acquisition system | 200 | - | - | IDIADA Moses MEAS X | 180749 | By: IDIADA Date: 05/21/2020 Due: 05/21/2022 | - |

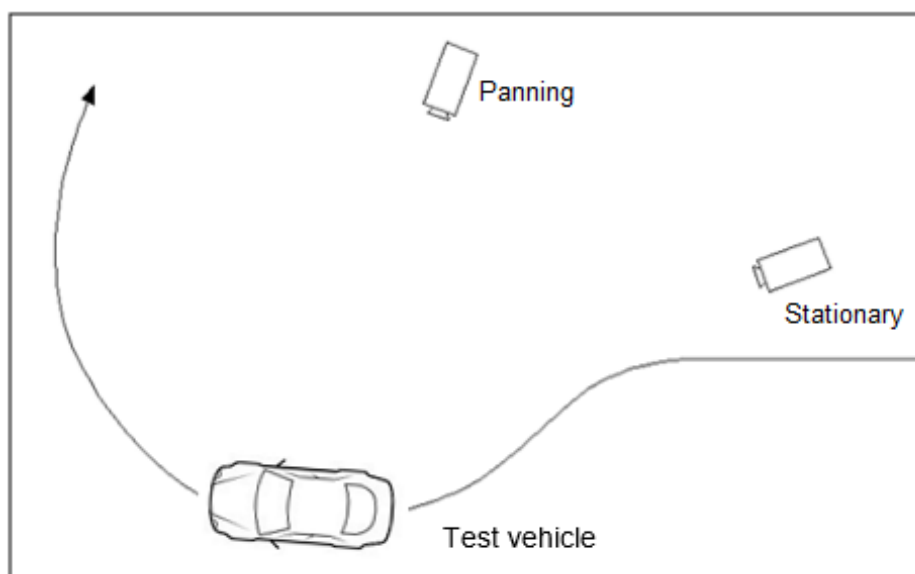


Figure 1. Nominal Position of Video Cameras for Fishhook Tests

SECTION III

TEST PROCEDURES

A. TEST PROCEDURE OVERVIEW

This test was conducted in accordance with NHTSA's NCAP Rollover Resistance Test Procedure (Fishhook) as described in the Federal Register (68 FR 59250). Detailed descriptions of the test procedure, pass/fail criteria, and data acquisition specifications may be found at docket NHTSA-2001-9663.

There are two major components of the test procedure, the Slowly Increasing Steer (SIS) pre-test and the Fishhook test.

The Slowly Increasing Steer (SIS) maneuver was used to characterize the steady state lateral dynamics of each vehicle, and is based on the "Constant Speed, Variable Steer" test defined in SAE J266. The maneuver is used to determine the handwheel angle that produces a lateral acceleration of 0.3 g at 50 mph. This handwheel angle is then used to determine the magnitude of steering to be used for the NHTSA Fishhook maneuver.

SIS tests were performed at a constant speed of 50 mph. Handwheel angle was input at a rate of 13.5 deg/sec, from 0 to an angle that provided at least 0.55 g. Three tests were conducted in each direction, and the data for the six runs were averaged to obtain the handwheel angle that produced 0.3 g at 50 mph.

The Fishhook test is a programmed steering maneuver that is implemented via the steering controller. The vehicle was initially steered in one direction and then the steering was reversed. The timing, magnitude and rate of the steering were prescribed by the Fishhook Procedure.

To begin the maneuver, the vehicle was driven in a straight line at a speed slightly greater than the desired entrance speed. The driver then released the throttle. When the vehicle was at the target speed, the steering controller automatically initiated the steering maneuver. Following completion of the steering reversal, the handwheel position was maintained for 3 seconds, and then returned to zero angle in 2 seconds.

The tests were conducted in both left-right and right-left directions. The “Default” test series used a handwheel angle equal to 6.5 times the handwheel angle that produced 0.3 g at 50 mph in the SIS tests, and initial vehicle speeds beginning at 35 mph and concluding up to 50 mph (if no two-wheel lift occurs). Supplemental tests were also done, as specified in the Fishhook Procedure.

A. TEST CONDITIONS

1. Test Surface

The tests were conducted on the Vehicle Dynamics Area (VDA) at HONDA Proving Center facility, located in Cantil, California, on 2/5/2021. The VDA has a smooth, flat (slope less than 0.5% throughout) asphaltic concrete surface. Its dimensions are as shown in Figure 2. The test was accomplished using an ASTM E1136 tire with an inflation pressure of 35 (± 0.5) psi at a test speed of 40 (± 0.5) mph. The net slip angle of the test tire for each test run was 7.5 deg. The surface friction measurement results are shown in Table 6.

Table 6. Lateral Surface Friction

| | |
|---------------------------------------|----------|
| Date of surface friction measurements | 2/5/2021 |
| Average lateral friction coefficient | 0.92 |
| Peak braking coefficient | 0.92 |

2. Fishhook Handwheel Angles

The 0.3 g handwheel angle obtained from the SIS tests and the handwheel angles used in the Fishhook tests are shown in Table 7.

Table 7. Handwheel Angles

| | |
|--|--------|
| 0.3 g handwheel angle (from SIS tests at 50 mph) | 27.7° |
| 5.5 scalar handwheel angle for Fishhook Test | 180.1° |
| 6.5 scalar handwheel angle for Fishhook Test | 152.4° |

3. Weather Conditions

The weather conditions, recorded at the end of testing, are shown in Table 8.

Table 8. Weather Conditions

| | |
|---------------------|-------------------|
| Ambient temperature | 58.8 °F (14.9 °C) |
| Wind Speed | 1.2 mph (0.5 m/s) |
| Wind Direction | NNE |

SECTION IV

RESULTS

There is Appendix A with the photographic documentation. The test run log is given in Appendix B. A summary of the Slowly Increasing Steer Test is given in Appendix C. Appendix D contains time history plots for the 50 mph runs and any runs which resulted in two-wheel lift. For the 2021 Kia Sorento FWD 5-Door SUV, there was no two-wheel lift at any test condition.

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Figure A2. Right Front View, Test Vehicle As-Delivered



Figure A3. Left Rear View, Test Vehicle As-Delivered



Figure A4. Left Front View, Test Vehicle in Test Condition



Figure A5. Right Rear View, Test Vehicle in Test Condition

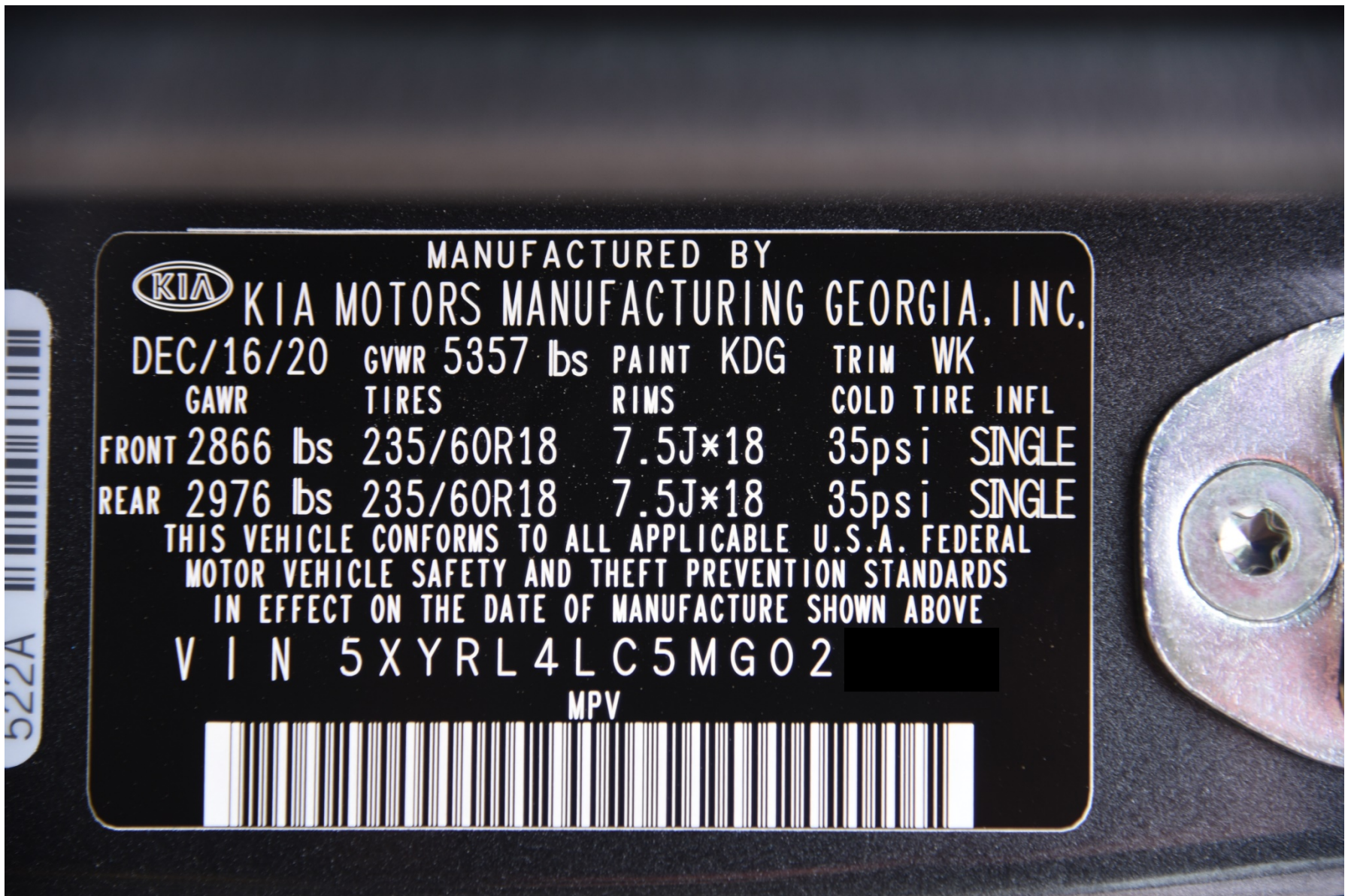


Figure A6. Vehicle's Certification Label



TIRE AND LOADING INFORMATION RENSEIGNEMENTS SUR LES PNEUS ET LE CHARGEMENT

SEATING CAPACITY
NOMBRE DE PLACES

TOTAL 7

FRONT
AVANT 2

REAR
ARRIÈRE 5

The combined weight of occupants and cargo should never exceed **546** kg or **1204** lbs.
Le poids total des occupants et du chargement ne doit jamais dépasser **546** kg ou **1204** lb.

| TIRE PNEU | SIZE DIMENSIONS | COLD TIRE PRESSURE PRESSION DES PNEUS À FROID | SEE OWNER'S MANUAL FOR ADDITIONAL INFORMATION VOIR LE MANUEL DE L'USAGER POUR PLUS DE RENSEIGNEMENTS |
|---------------------|--------------------|---|---|
| FRONT AVANT | 235/60R18 | 240kPa, 35psi | |
| REAR ARRIÈRE | 235/60R18 | 240kPa, 35psi | |
| SPARE DE SECOURS | T135/90D17 | 420kPa, 60psi | |



522A

Figure A7. Vehicle's Tire Information Placard

Photograph Not Available

Figure A8. Instrumentation in Test Vehicle



Figure A9. Steering Controller and Computer



Figure A10. Ballast Condition

APPENDIX B
TEST RUN LOG

| Run Number | Test Type | Speed (mph) | Handwheel Angle (deg) | Dir. of First Steer | 2 Wheel Lift | Notes |
|------------|--------------------------------|-------------|-----------------------|---------------------|--------------|---------------------------|
| 1 | Tire Warm-Up | 35 | 30.0 | Left | N/A | Resulted in ay = 0.19g |
| 2 | " | " | 56.3 | " | " | Resulted in ay = 0.33g |
| 3 | " | " | " | " | " | |
| 4 | " | " | " | " | " | |
| 5 | 2x SWA last cycle | " | 112.6 | " | " | 2x SWA last cycle |
| | | | | | | |
| 6 | Static | 0 | 0 | N/A | N/A | |
| 7 | Steady State | 50 | 0 | N/A | N/A | |
| | | | | | | |
| 8 | Slowly Increasing Steer | 50 | 30.0 | Left | N/A | |
| 9 | " | " | 38.9 | Left | " | HW angle at 0.3 g = -27.0 |
| 10 | " | " | " | Left | " | HW angle at 0.3 g = -27.4 |
| 11 | " | " | " | Left | " | HW angle at 0.3 g = -27.9 |
| 12 | " | " | " | Right | " | HW angle at 0.3 g = 27.4 |
| 13 | " | " | " | Right | " | HW angle at 0.3 g = 28.4 |
| 14 | " | " | " | Right | " | HW angle at 0.3 g = 28.2 |
| | | | | | | Average = 27.7 |
| | | | | | | |
| 15 | Fishhook 6.5 Scalar | 35 | 180.1 | Left | No | |
| 16 | " | 40 | " | " | " | |
| 17 | " | 45 | " | " | " | |
| 18 | " | 47.5 | " | " | " | |
| 19 | " | 50 | " | " | " | |
| | | | | | | |
| 20 | Fishhook 6.5 Scalar | 35 | 180.1 | Right | No | |
| 21 | " | 40 | " | " | " | |
| 22 | " | 45 | " | " | " | |

| Run Number | Test Type | Speed (mph) | Handwheel Angle (deg) | Dir. of First Steer | 2 Wheel Lift | Notes |
|------------|----------------------------|-------------|-----------------------|---------------------|--------------|-------|
| 23 | " | 47.5 | " | " | " | |
| 24 | " | 50 | " | " | " | |
| | | | | | | |
| 25 | Fishhook 5.5 Scalar | 45 | 152.4 | Left | No | |
| 26 | " | 47.5 | " | " | " | |
| 27 | " | 50 | " | " | " | |
| | | | | | | |
| 28 | Fishhook 5.5 Scalar | 45 | 152.4 | Right | No | |
| 29 | " | 47.5 | " | " | " | |
| 30 | " | 50 | " | " | " | |

APPENDIX C
SLOWLY INCREASING STEER TEST WORKSHEET

2021 Kia Sorento FWD 5-Door SUV, Multi-Passenger Configuration,
Test Date: 2/5/2021



Slowly Increasing Steer



Vehicle: 2021 Kia Sorento

Test Date: 2/5/2021

Analysis Date: 2/5/2021

Analysed by: EL

Executed by: OG

Weight Condition: Test condition

Test Track: Dynamic Platform

Test Speed: 50 mph

| Run | Dir of Steer | Start speed [mph] | End speed [mph] | Speed red [%] | Index of ay | HW angle [deg] at 0.3g | ay [g] 0.3g index | 6.5x HW angle [deg] | Ramp time [sec] at 6.5x | 5.5x HW angle [deg] | Ramp time [sec] at 5.5x | R2 | Zero Begin index | Zero End index |
|---------|--------------------|-------------------------|-----------------------|---------------------|----------------|------------------------------|-------------------------|---------------------------|-------------------------------|---------------------------|-------------------------------|--------|------------------------|----------------------|
| sis_001 | L | 50.7 | 0.3 | 99.5 | 1005 | -27.0 | -0.300 | -175.7 | -0.2440 | -148.6 | -0.2065 | 0.9972 | 362 | 562 |
| sis_002 | L | 49.8 | 0.2 | 99.6 | 1013 | -27.4 | -0.300 | -178.2 | -0.2475 | -150.8 | -0.2094 | 0.9975 | 362 | 562 |
| sis_003 | L | 49.7 | -0.2 | 100.4 | 1015 | -27.9 | -0.300 | -181.2 | -0.2517 | -153.3 | -0.2130 | 0.9968 | 364 | 564 |
| sis_004 | R | 50.5 | 0.5 | 99.1 | 1011 | 27.4 | 0.300 | 178.4 | 0.2478 | 151.0 | 0.2097 | 0.9976 | 367 | 567 |
| sis_005 | R | 49.7 | 0.1 | 99.8 | 1021 | 28.4 | 0.300 | 184.7 | 0.2565 | 156.3 | 0.2170 | 0.9966 | 376 | 576 |
| sis_006 | R | 49.8 | -0.2 | 100.5 | 1027 | 28.2 | 0.300 | 183.0 | 0.2542 | 154.9 | 0.2151 | 0.9981 | 370 | 570 |

Mean: 27.7

Steering Controller Input values

Scalar 6.5 values:

Initial HW angle: 180.1 deg

Reversal HW angle: -180.1 deg

Scalar 5.5 values:

Initial HW angle: 152.4 deg

Reversal HW angle: -152.4 deg

APPENDIX D
TIME HISTORY PLOTS

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FILENAME: FH005

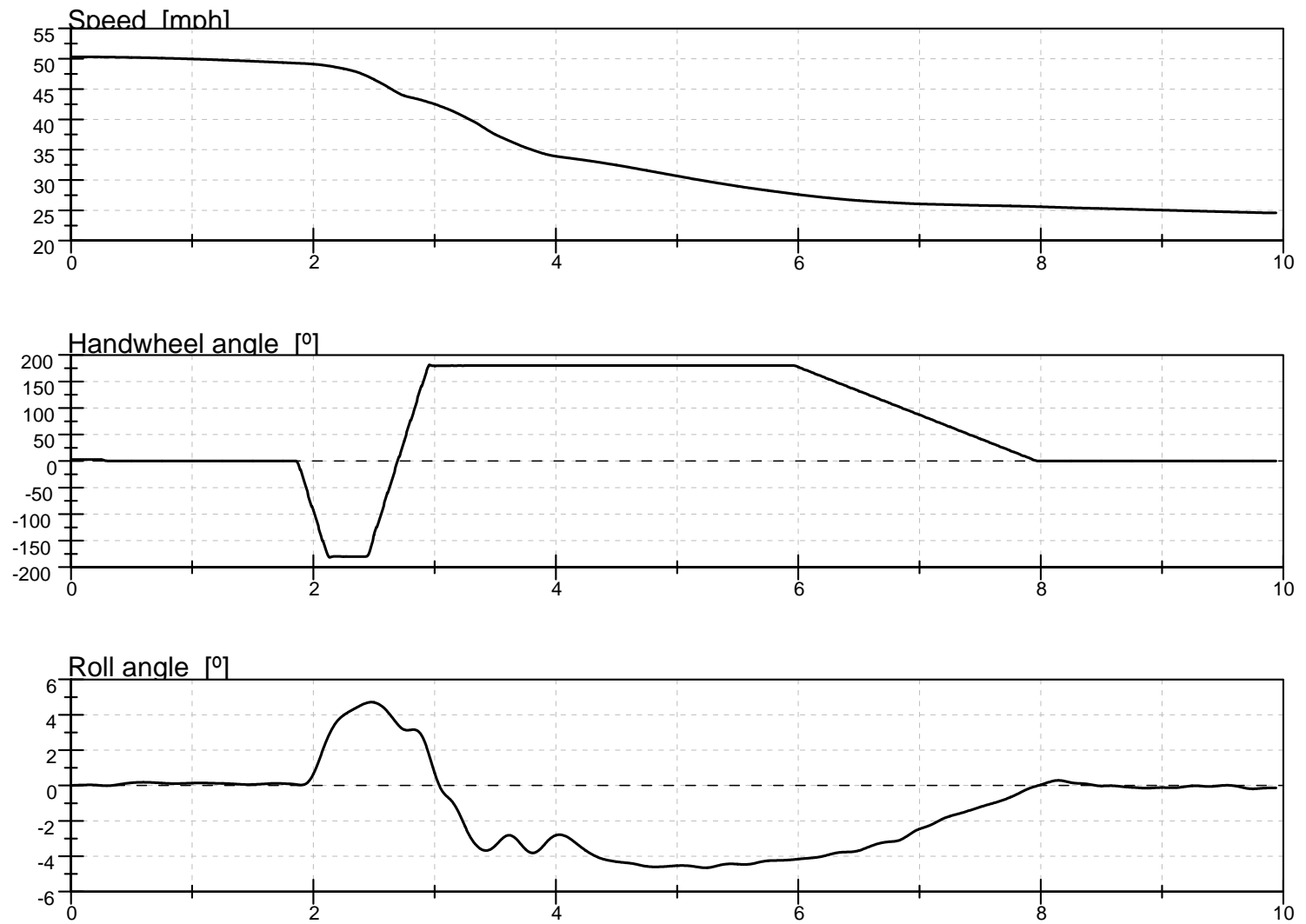


Figure D1. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, L-R, 50 mph

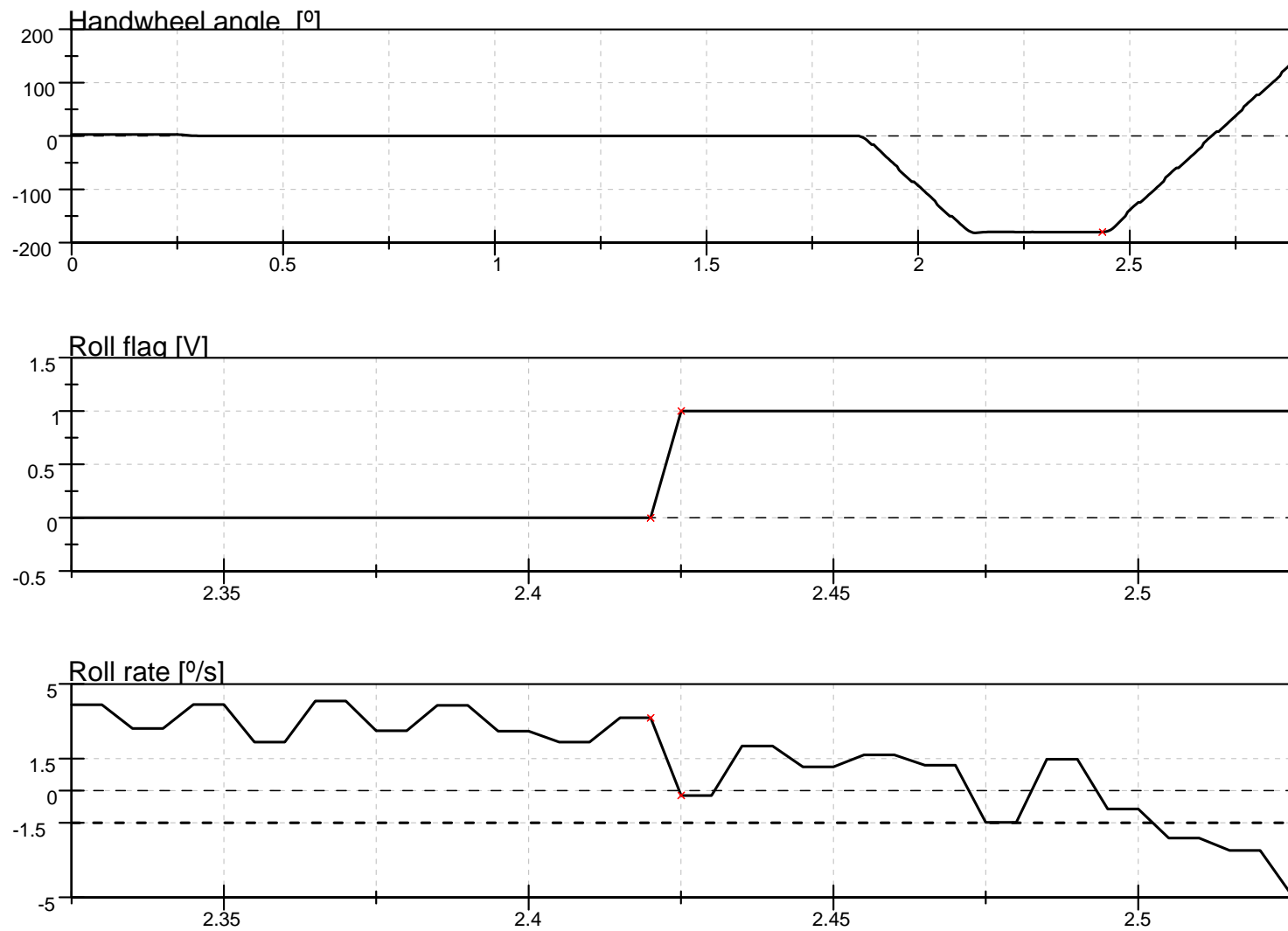


Figure D2. Steering Machine Operation Time History Plots for Default Test Series, L-R, 50 mph

FILENAME: FH005

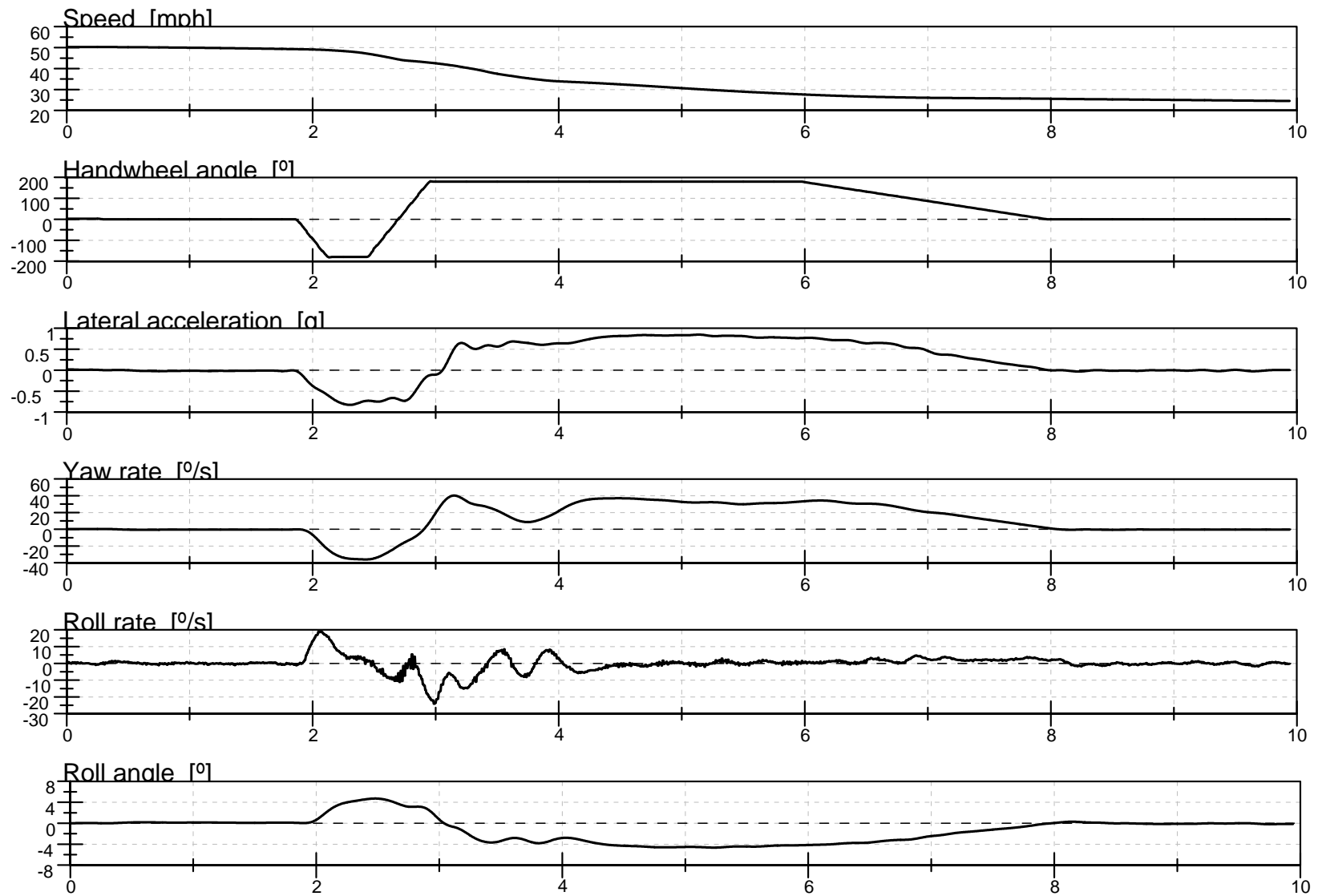


Figure D3. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots For Default Test Series, L-R, 50 mph

FILENAME: FH005

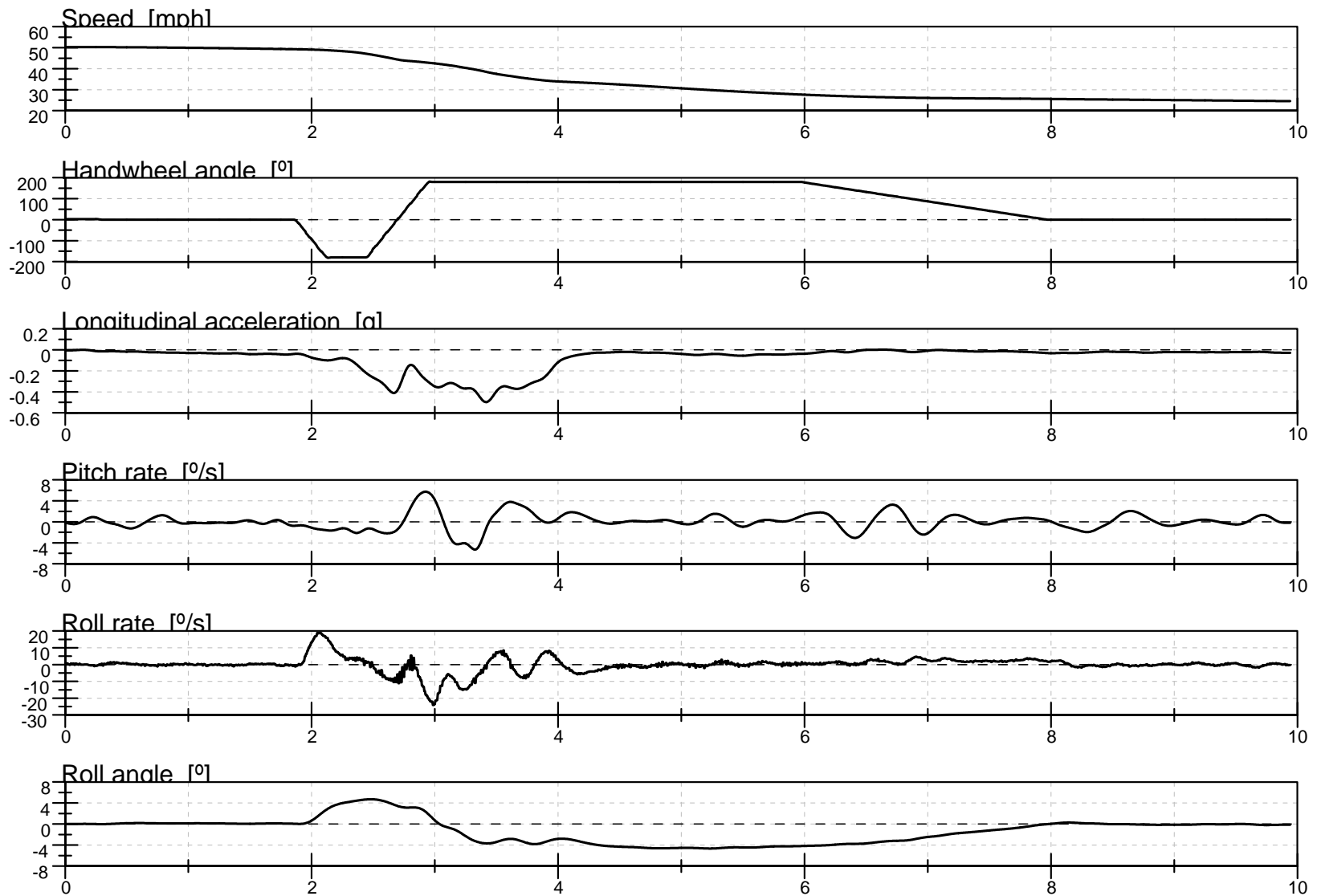


Figure D4. Pitch Rate and Longitudinal Acceleration Time History Plots for Default Test Series, L-R, 50 mph

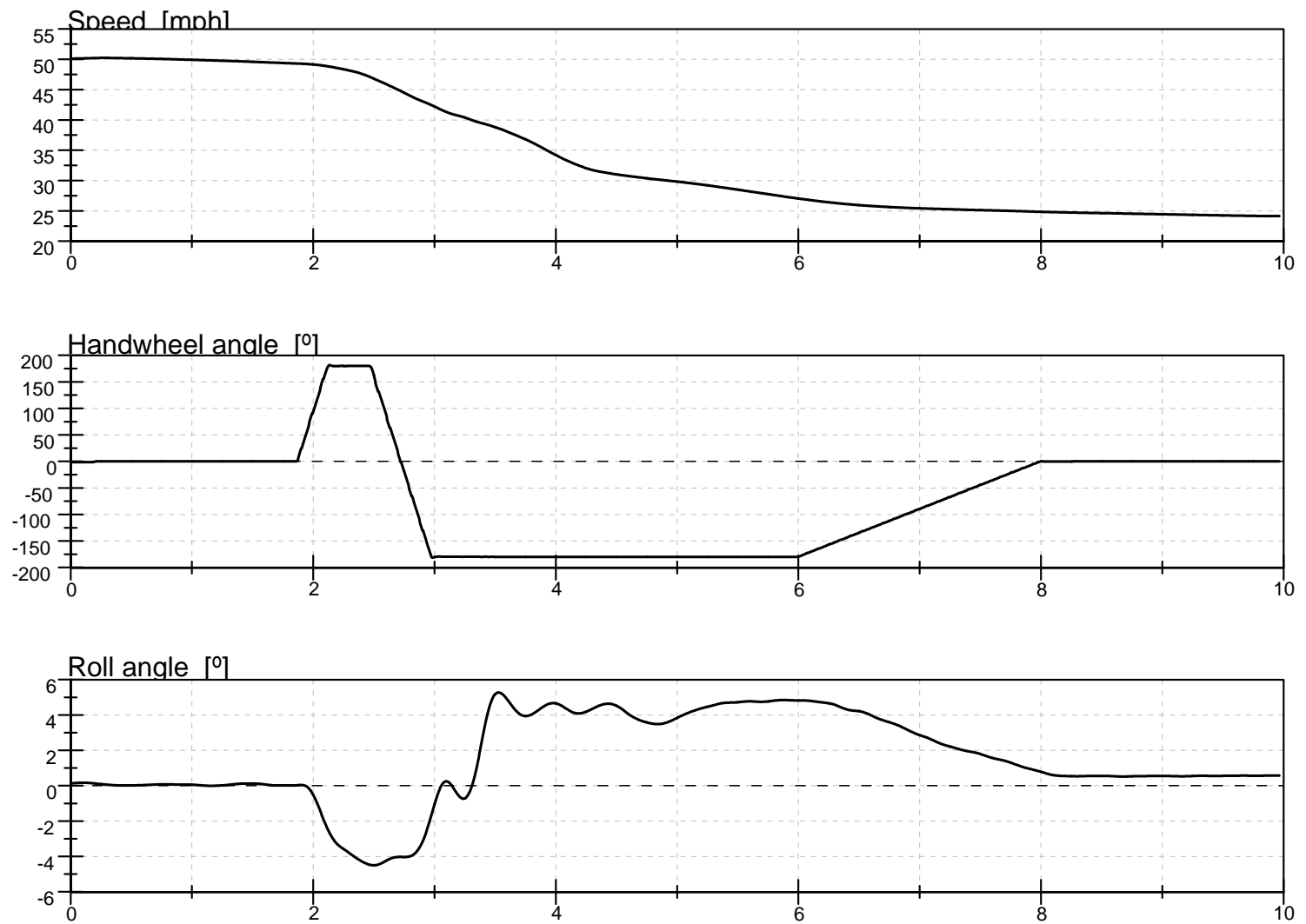


Figure D5. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, R-L, 50 mph

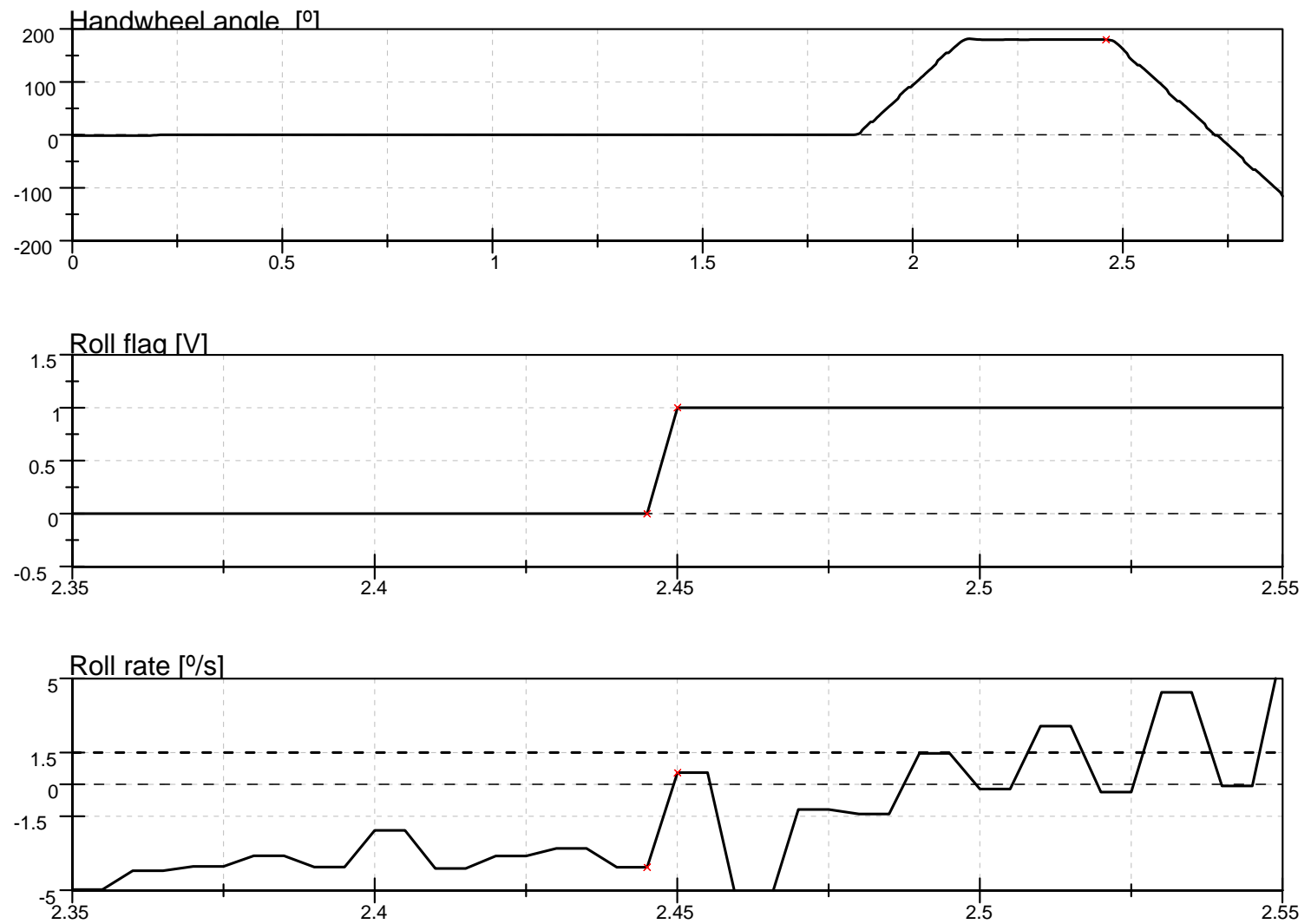


Figure D6. Steering Machine Operation Time History Plots for Default Test Series, R-L, 50 mph

FILENAME: FH010

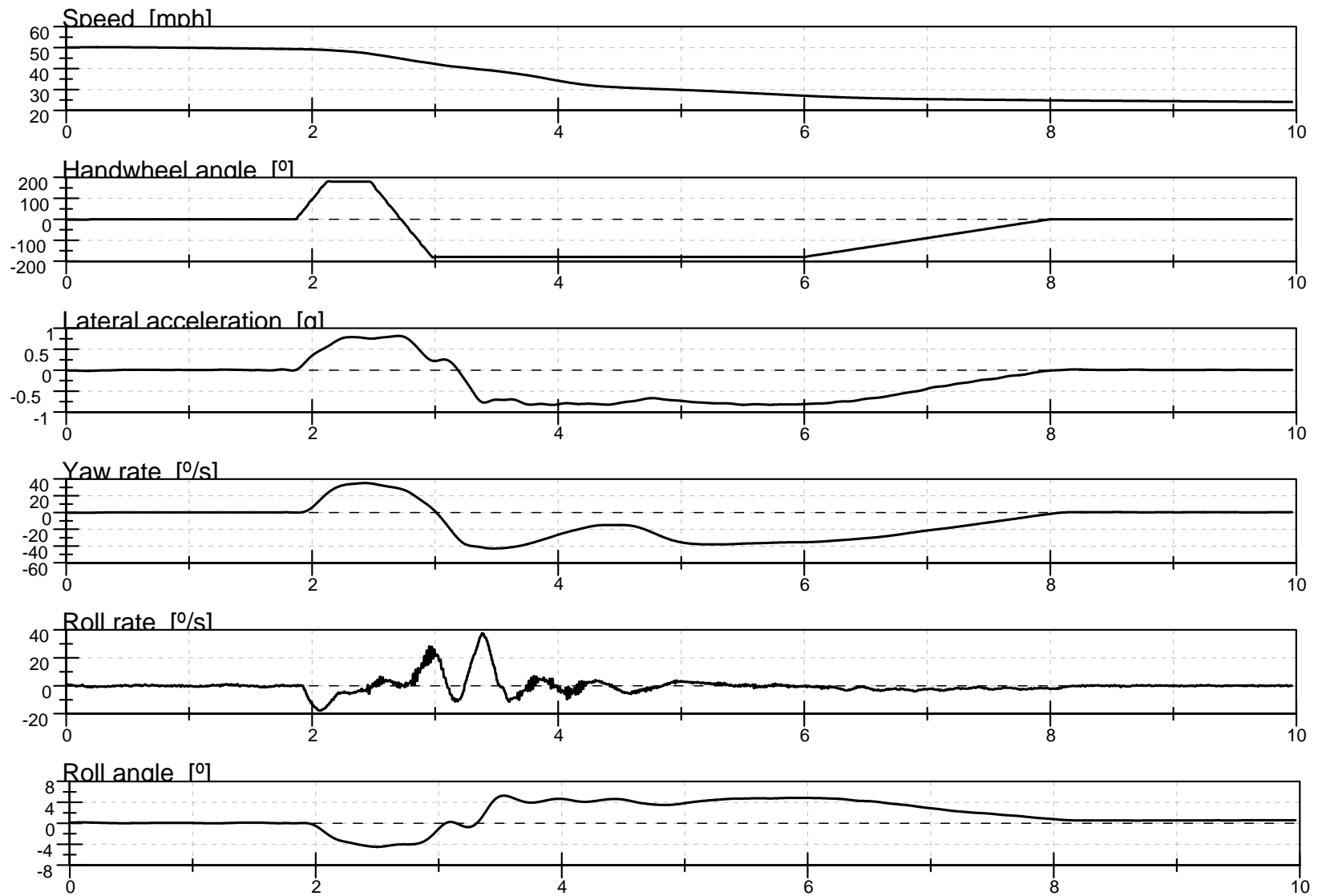


Figure D7. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Default Test Series, R-L, 50 mph

FILENAME: FH010

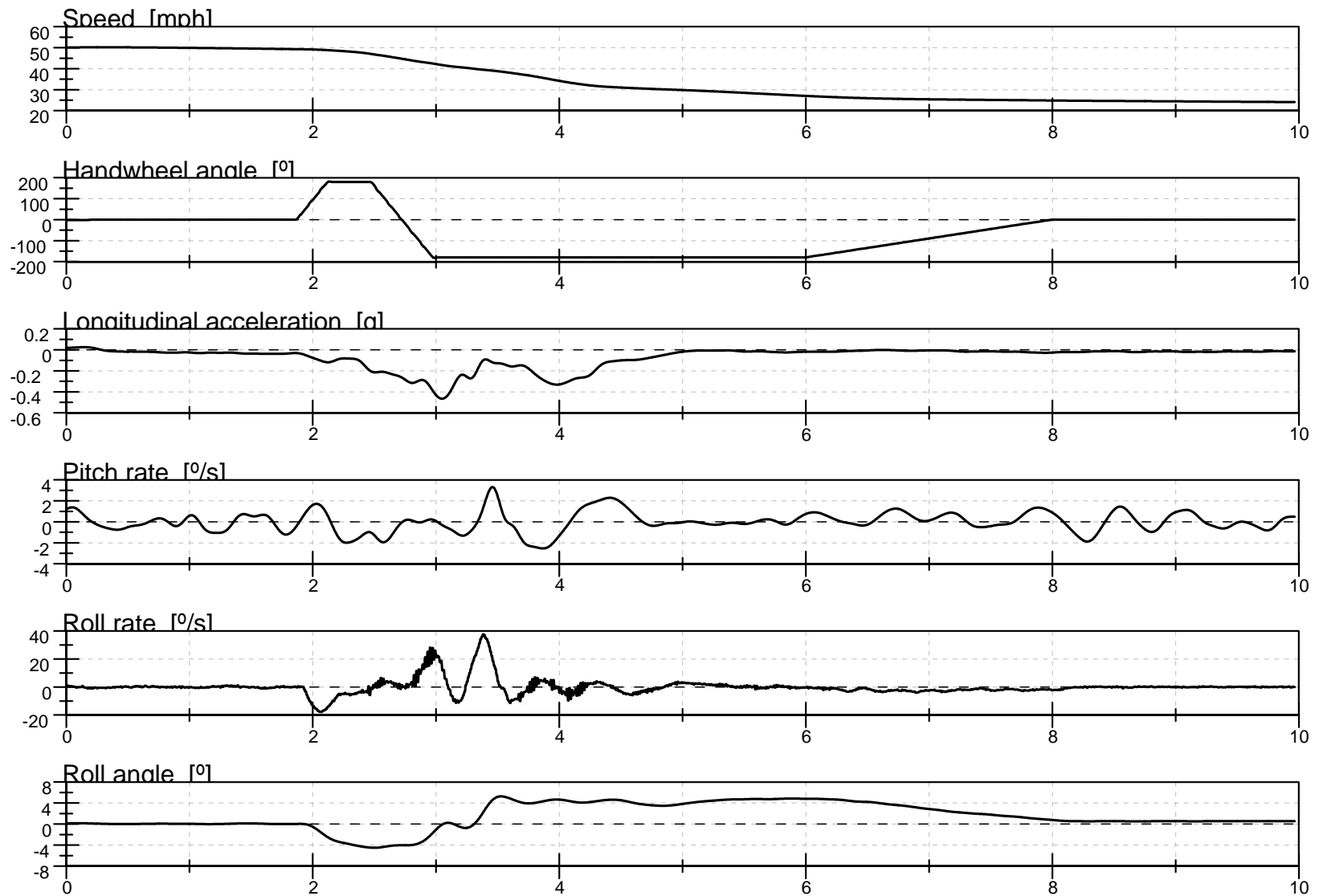


Figure D8. Pitch Rate and Longitudinal Acceleration Time History Plots or Default Test Series, R-L, 50 mph

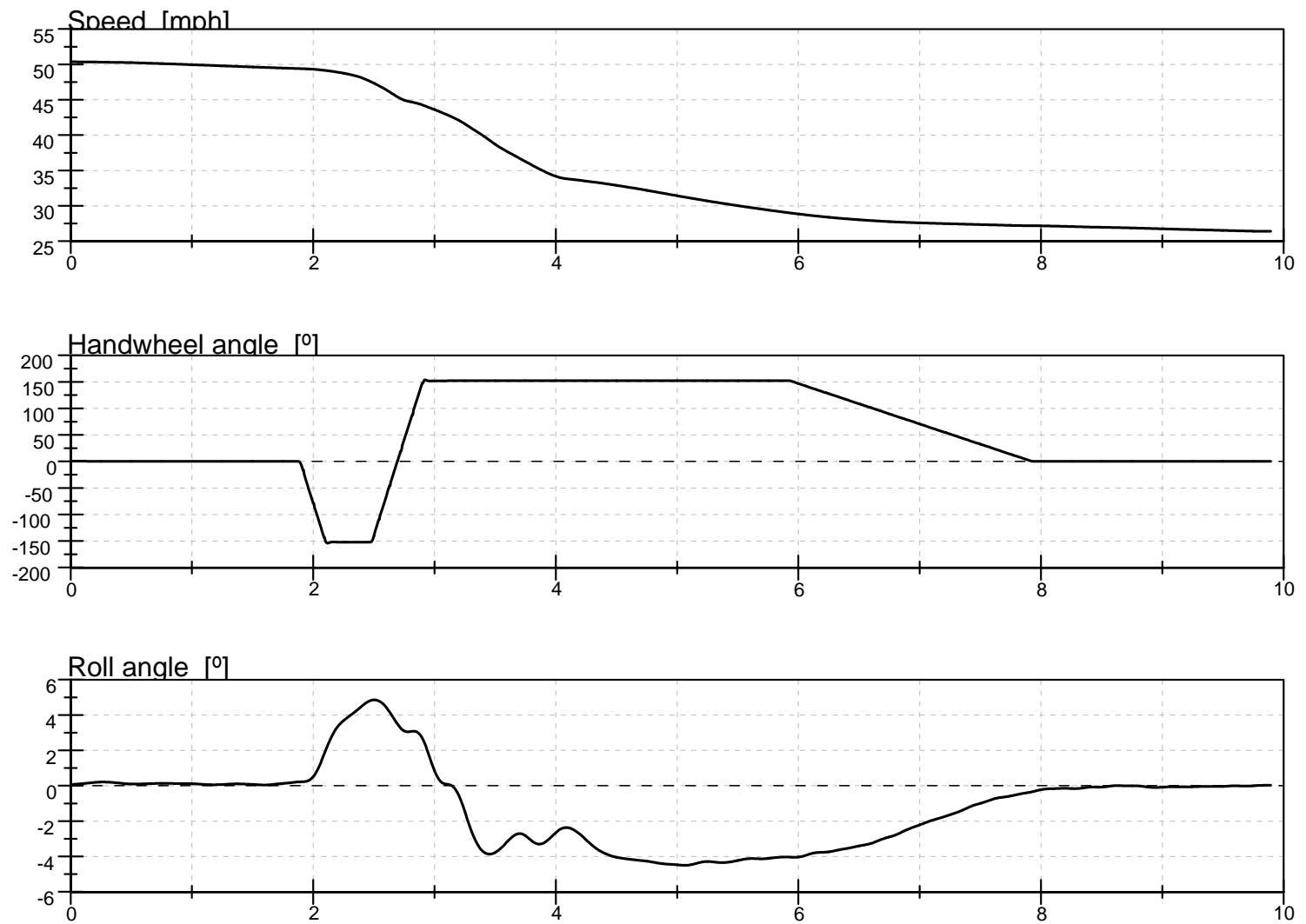


Figure D9. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

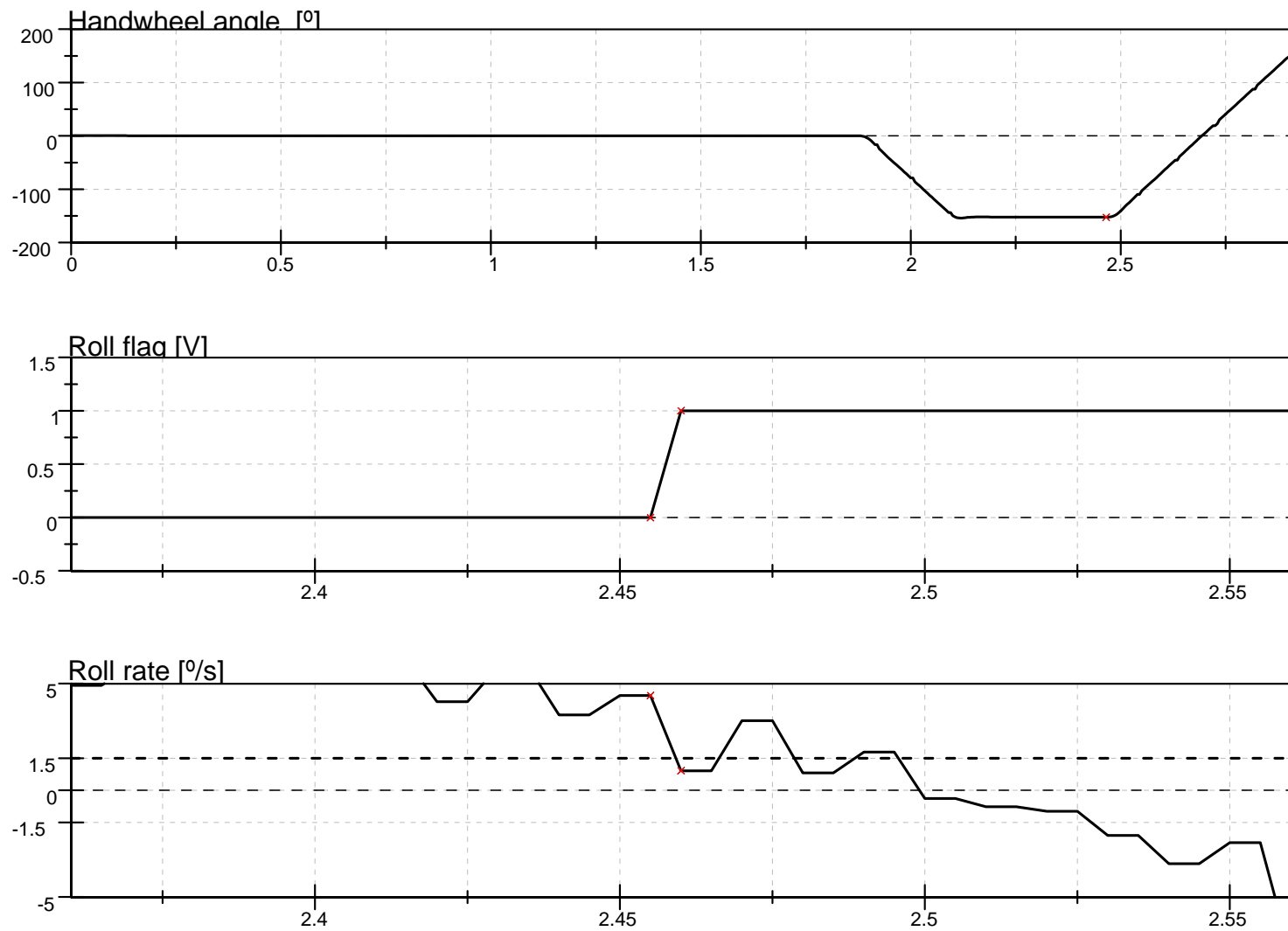


Figure D10. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

FILENAME: FH013

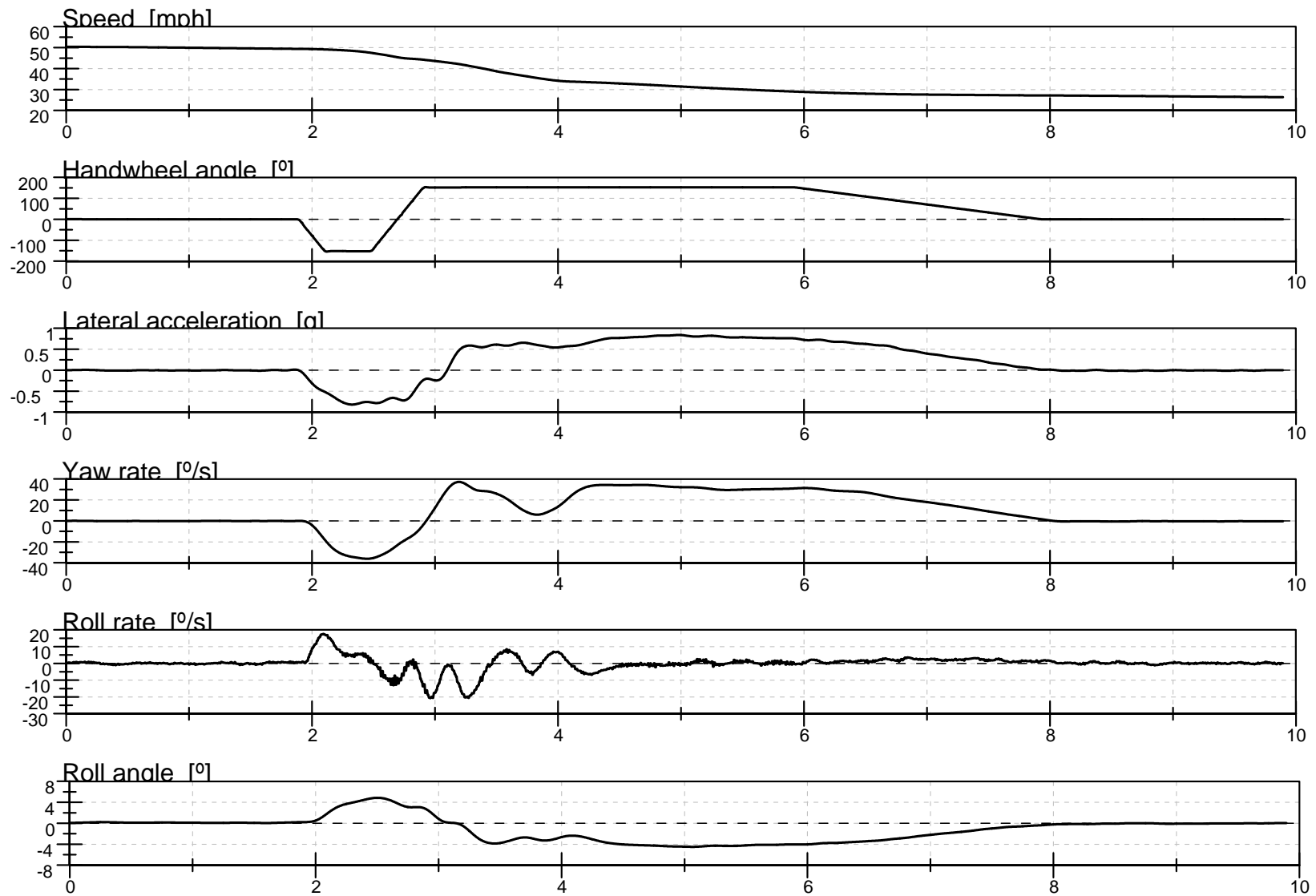


Figure D11. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

FILENAME: FH013

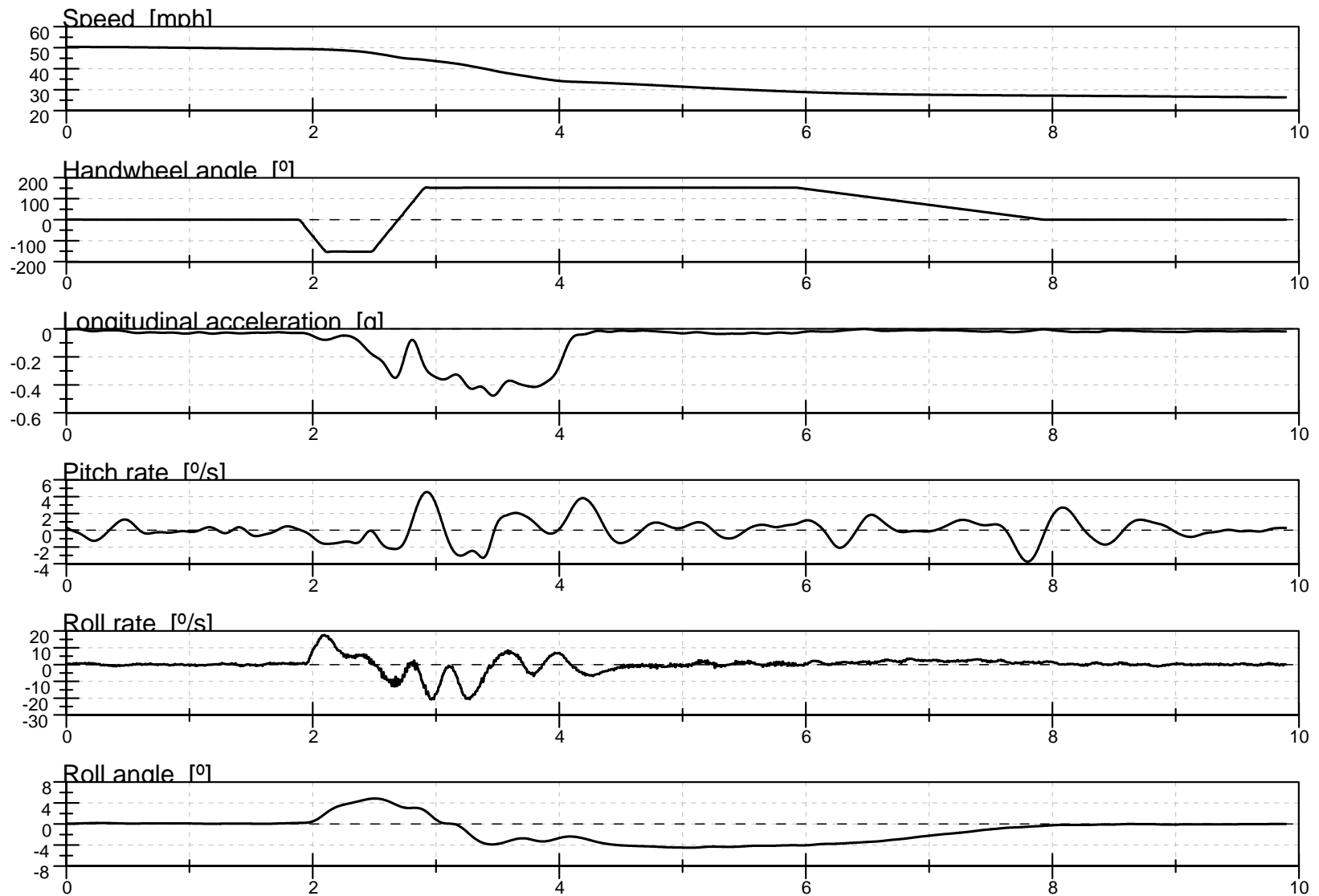


Figure D12. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

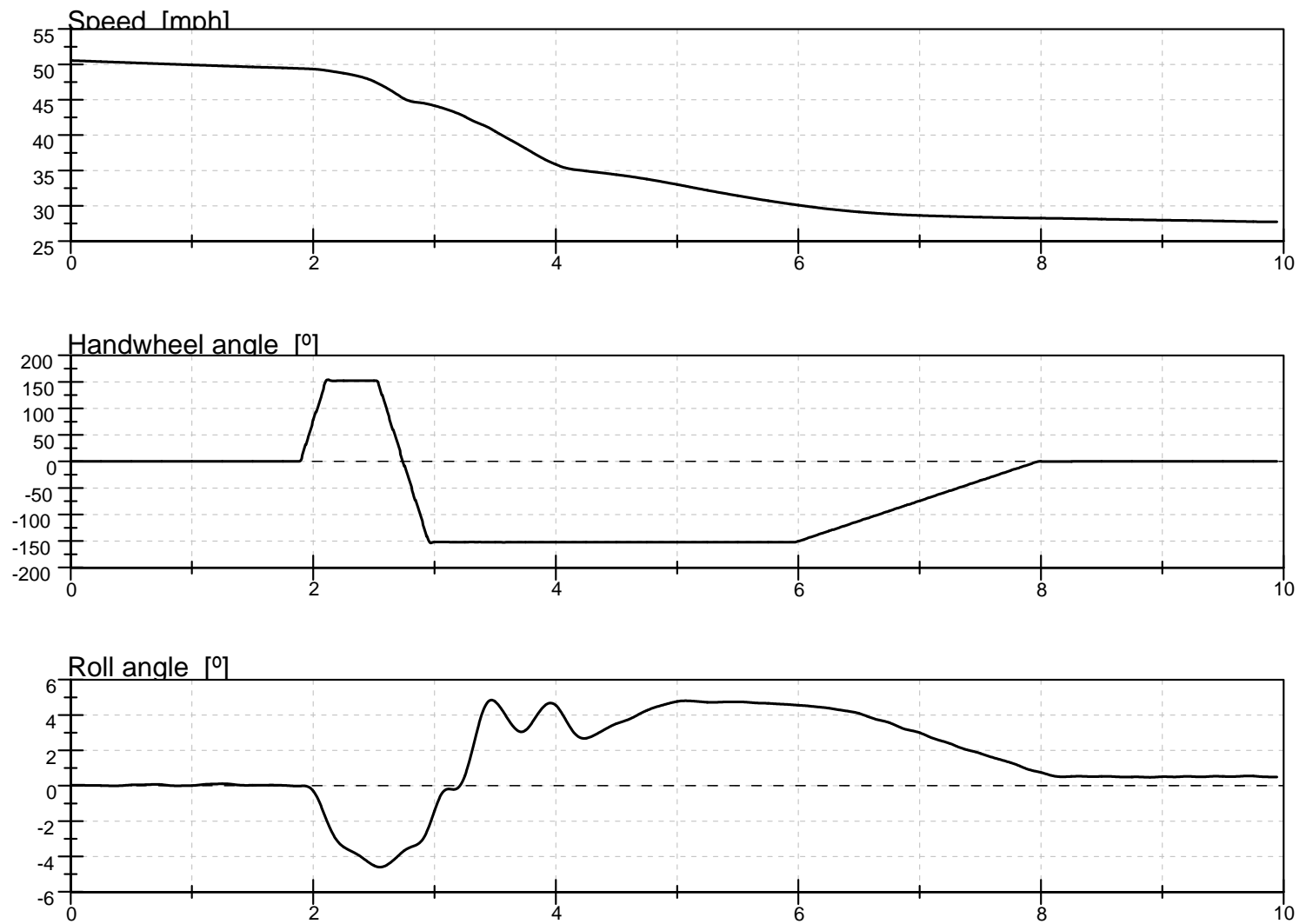


Figure D13. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

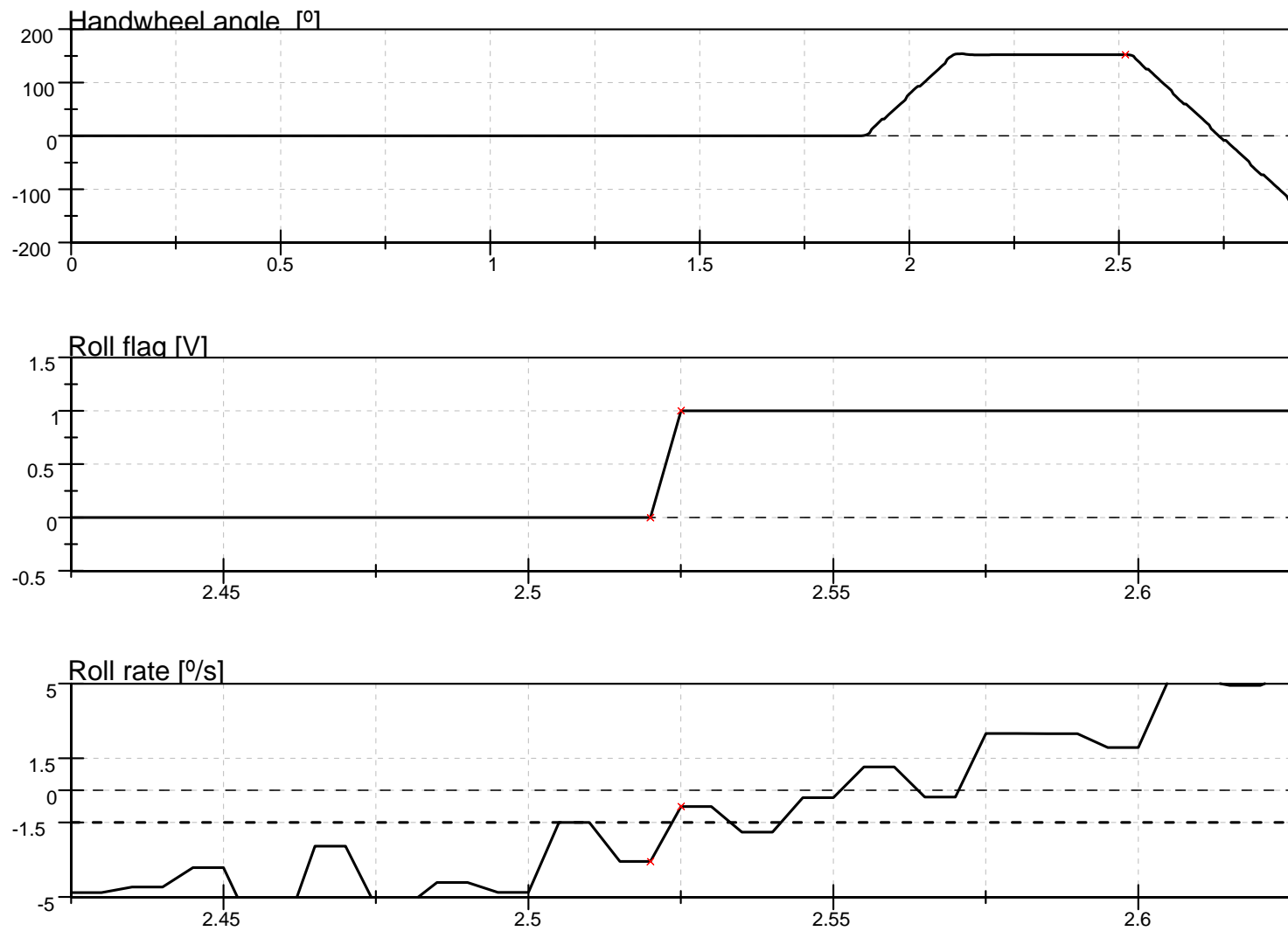


Figure D14. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

FILENAME: FH016

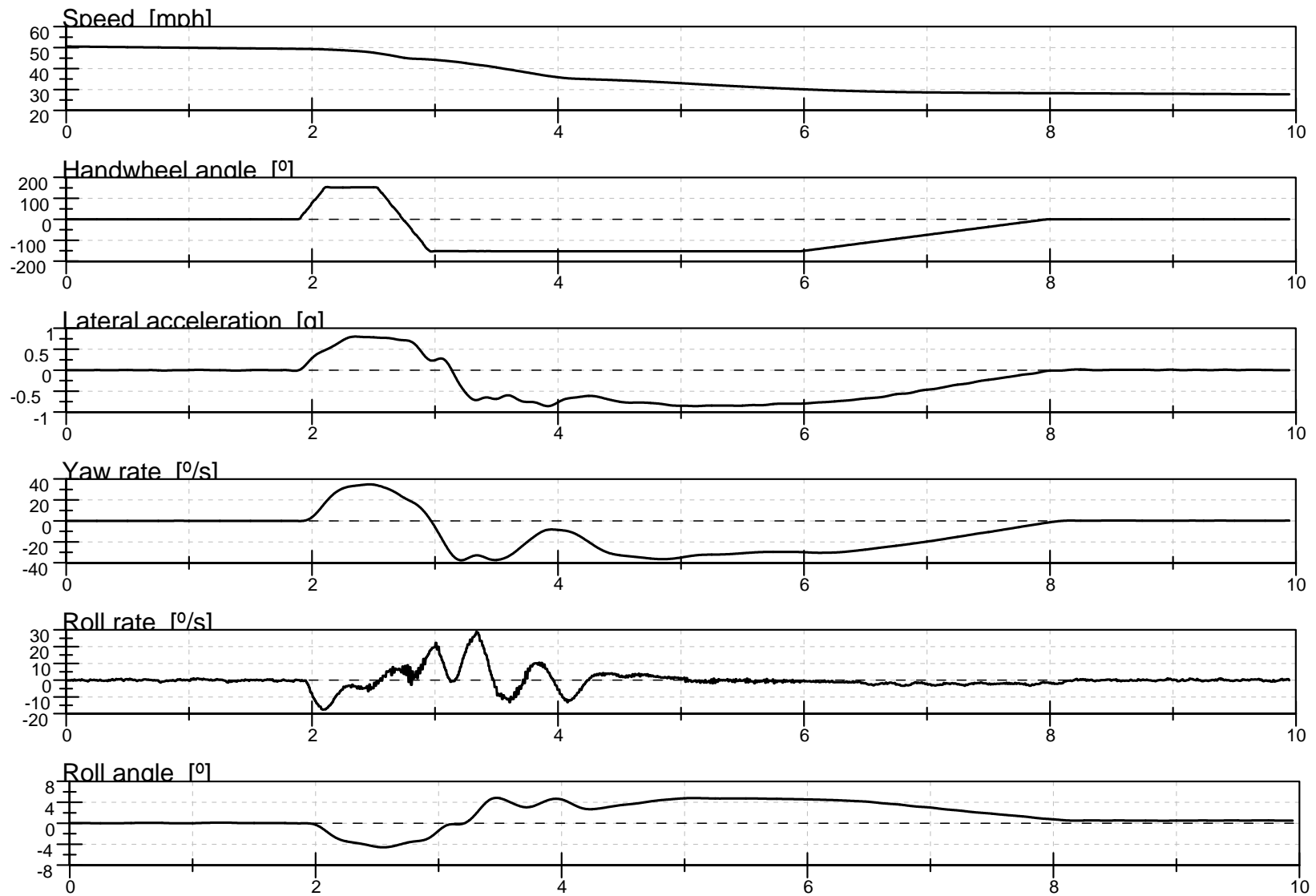


Figure D15. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

FILENAME: FH016

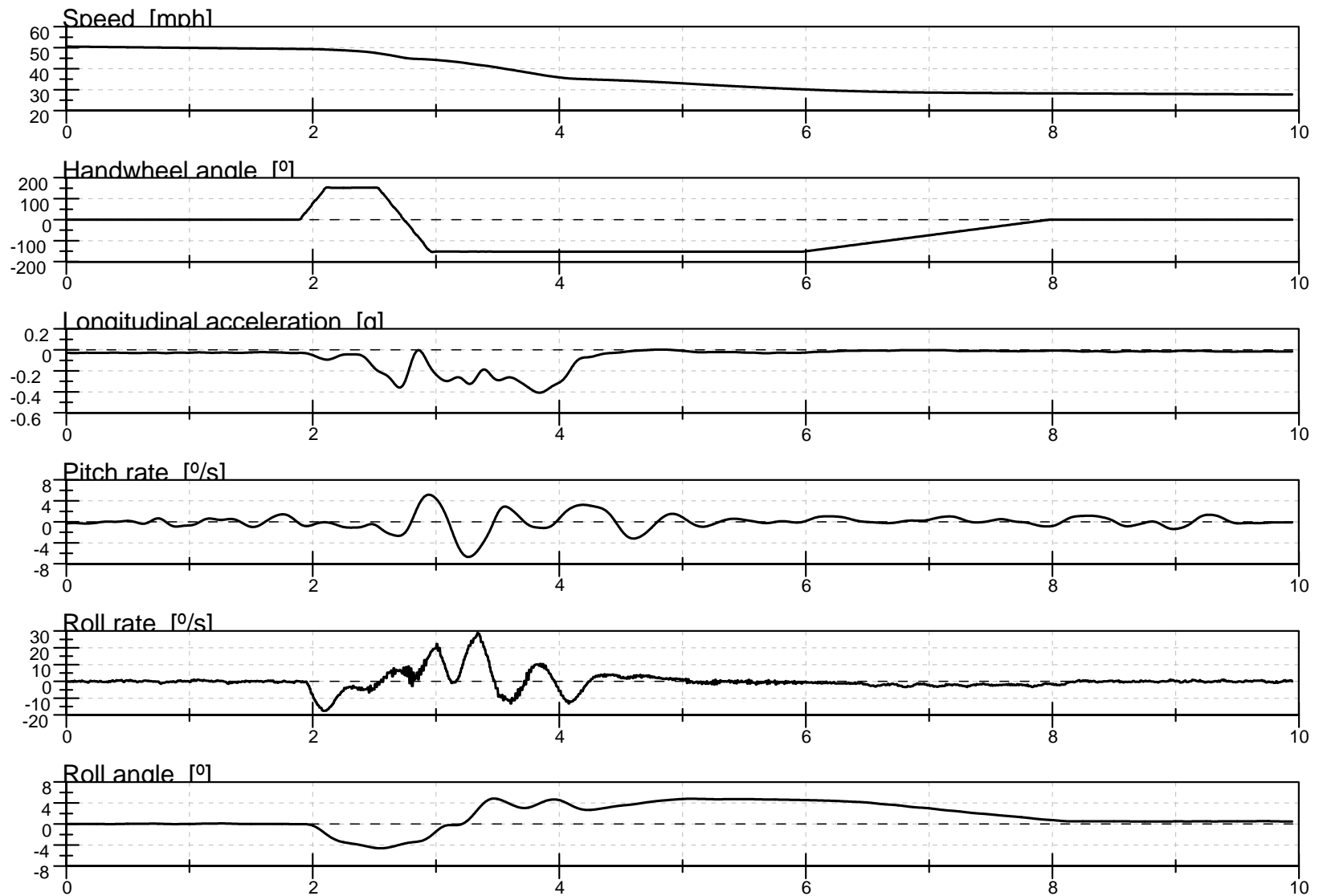


Figure D16. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph