

**NEW CAR ASSESSMENT PROGRAM
DYNAMIC BRAKE SUPPORT SYSTEM CONFIRMATION TEST
NCAP-DRI-DBS-20-03**

2020 Ford F-150 4X4 SuperCrew

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1 July 2020

Final Report

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National Highway Traffic Safety Administration
New Car Assessment Program
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16. Abstract These tests were conducted on the subject 2020 Ford F-150 4X4 SuperCrew in accordance with the specifications of the New Car Assessment Program's (NCAP) most current Test Procedure in docket NHTSA-2015-0006-0026; DYNAMIC BRAKE SUPPORT PERFORMANCE EVALUATION CONFIRMATION TEST FOR THE NEW CAR ASSESSMENT PROGRAM, October 2015. The vehicle passed the requirements of the test for all four DBS test scenarios.			
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Section I

INTRODUCTION

Dynamic Brake Support (DBS) systems are a subset of Automatic Emergency Braking (AEB) systems. DBS systems are designed to avoid or mitigate consequences of rear-end crashes by automatically applying supplemental braking on the subject vehicle when the system determines that the braking applied by the driver is insufficient to avoid a collision.

DBS systems intervene in driving situations where a rear-end collision is expected to be unavoidable unless additional braking is realized. Since DBS interventions are designed to occur late in the pre-crash timeline, and the driver has already initiated crash-avoidance braking, DBS systems are not required to alert the driver that a DBS intervention has occurred. In addition to sensors monitoring vehicle operating conditions, such as speed, brake application, etc., DBS systems employ RADAR, LIDAR, and/or vision-based sensors capable of detecting surrounding vehicles in traffic. Algorithms in the system's Central Processing Unit (CPU) use this information to continuously monitor the likelihood of a rear-end crash, and command additional braking as needed to avoid or mitigate such a crash.

The method prescribed by the National Highway Traffic Safety Administration (NHTSA) to evaluate DBS performance on the test track involves three longitudinal, rear-end type crash configurations and a false positive test. In the rear-end scenarios, a subject vehicle (SV) approaches a stopped, slower-moving, or decelerating principal other vehicle (POV) in the same lane of travel. For these tests, the POV is a strikeable object with the characteristics of a compact passenger car. The fourth scenario is used to evaluate the propensity of a DBS system to inappropriately activate in a non-critical driving scenario that does not present a safety risk to the SV occupant(s).

The purpose of the testing reported herein was to objectively quantify the performance of a Dynamic Brake Support system installed on a 2020 Ford F-150 4X4 SuperCrew. This test to assess Dynamic Brake Support systems is sponsored by the National Highway Traffic Safety Administration under Contract No. DTNH22-14-D-00333 with the New Car Assessment Program (NCAP).

Section II

DATA SHEETS

DYNAMIC BRAKE SUPPORT
DATA SHEET 1: TEST RESULTS SUMMARY

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2020 Ford F-150 4X4 SuperCrew

VIN: 1FTEW1E42LFA1xxxx

Test Date: 5/19/2020

Dynamic Brake Support System setting: Pre-Collision: on,
Alert Sensitivity: High,
Distance Indication: on,
Active Braking: on

**Test 1 - Subject Vehicle Encounters
Stopped Principal Other Vehicle**

SV 25 mph: Pass

**Test 2 - Subject Vehicle Encounters
Slower Principal Other Vehicle**

SV 25 mph POV 10 mph: Pass

SV 45 mph POV 20 mph: Pass

**Test 3 - Subject Vehicle Encounters
Decelerating Principal Other Vehicle**

SV 35 mph POV 35 mph: Pass

**Test 4 - Subject Vehicle Encounters
Steel Trench Plate**

SV 25 mph: Pass

SV 45 mph: Pass

Overall: Pass

Notes:

DYNAMIC BRAKE SUPPORT
DATA SHEET 2: VEHICLE DATA

(Page 1 of 1)

2020 Ford F-150 4X4 SuperCrew

TEST VEHICLE INFORMATION

VIN: 1FTEW1E42LFA1xxxx

Body Style: 4 door Crew Cab Pickup Color: Magnetic

Date Received: 5/12/2020 Odometer Reading: 155 mi

DATA FROM VEHICLE'S CERTIFICATON LABEL

Vehicle manufactured by: Ford Motor Company

Date of manufacture: 10/19

Vehicle Type: Truck

DATA FROM TIRE PLACARD

Tires size as stated on Tire Placard: Front: 275/55R20 113T

Rear: 275/55R20 113T

Recommended cold tire pressure: Front: 240 kPa (35 psi)

Rear: 240 kPa (35 psi)

TIRES

Tire manufacturer and model: Hankook Dynapro AT2

Front tire specification: 275/55R20 113T

Rear tire specification: 275/55R20 113T

Front tire DOT prefix: 15M8D RN H0

Rear tire DOT prefix: 15M8D RN H0

DYNAMIC BRAKE SUPPORT
DATA SHEET 3: TEST CONDITIONS

(Page 1 of 2)

2020 Ford F-150 4X4 SuperCrew

GENERAL INFORMATION

Test date: 5/19/2020

AMBIENT CONDITIONS

Air temperature: 23.3 C (74 F)

Wind speed: 3.1 m/s (6.9 mph)

X Wind speed \leq 10 m/s (22 mph).

X Tests were not performed during periods of inclement weather. This includes, but is not limited to, rain, snow, hail, fog, smoke, or ash.

X Tests were conducted during daylight hours with good atmospheric visibility (defined as an absence of fog and the ability to see clearly for more than 5000 meters). The tests were not conducted with the vehicle oriented into the sun during very low sun angle conditions, where the sun is oriented 15 degrees or less from horizontal, and camera "washout" or system inoperability results.

VEHICLE PREPARATION

Verify the following:

All non-consumable fluids at 100% capacity: X

Fuel tank is full: X

Tire pressures are set to manufacturer's recommended cold tire pressure: X

Front: 240 kPa (35 psi)

Rear: 240 kPa (35 psi)

DYNAMIC BRAKE SUPPORT
DATA SHEET 3: TEST CONDITIONS

(Page 2 of 2)

2020 Ford F-150 4X4 SuperCrew

WEIGHT

Weight of vehicle as tested including driver and instrumentation

Left Front: 772.0 kg (1702 lb)

Right Front: 721.2 kg (1590 lb)

Left Rear: 572.0 kg (1261 lb)

Right Rear: 556.1 kg (1226 lb)

Total: 2621.3 kg (5779 lb)

DYNAMIC BRAKE SUPPORT
DATA SHEET 4: DYNAMIC BRAKE SUPPORT SYSTEM OPERATION

(Page 2 of 4)

2020 Ford F-150 4X4 SuperCrew

If yes, please provide a full description.

It is recommended to wait a minimum of 90 seconds between test runs, and to turn around when restaging as opposed to simply reversing in order to completely remove the target from the sensors field of view. The system effectiveness may reduce if too many AEB activations occur in quick succession. The message "Pre-Collision Assist Not Available" may also appear under repeated AEB activations/impacts. In this case, cycle the ignition to re-enable the Pre-Collision Assist feature.

How is the Forward Collision Warning presented ☒ Warning light
to the driver? ☐
(Check all that apply) ☒ Buzzer or audible alarm
☐ Vibration
☐ Other _____

Describe the method by which the driver is alerted. For example, if the warning is a light, where is it located, its color, size, words or symbol, does it flash on and off, etc. If it is a sound, describe if it is a constant beep or a repeated beep. If it is a vibration, describe where it is felt (e.g., pedals, steering wheel), the dominant frequency (and possibly magnitude), the type of warning (light, audible, vibration, or combination), etc.

The driver is provided with an audible and visual alert. The audible sound is a four-tone chime repeated three times. The visual alert is provided as a red and black flashing graphic in the cluster showing the text "Pre-Collision Assist." or via a flashing red LED bar located in front of the driver below the windshield.

See Appendix A Figure A16.

Is there a way to deactivate the system? ☒ Yes
☐ No

DYNAMIC BRAKE SUPPORT

DATA SHEET 4: DYNAMIC BRAKE SUPPORT SYSTEM OPERATION

(Page 3 of 4)

2020 Ford F-150 4X4 SuperCrew

If yes, please provide a full description including the switch location and method of operation, any associated instrument panel indicator, etc.

CIB and DBS are on by default after every ignition cycle. The CIB and DBS functionality can be turned off through a single checkbox in the cluster menu, accessed by means of buttons on the steering wheel. The hierarchy is:

Settings

Pre-Collision

Active Braking checkbox

In a similar manner, the entire Pre-Collision Assist system can also be disabled. The hierarchy is

Settings

Pre-Collision

Pre-Collision Assist On/Off.

If this has occurred, the driver will be prompted to re-enable the feature after an ignition cycle.

See the Owner's Manual, Pages 127, 131 and 277. These are shown in Appendix B, Pages B-2, B-3, and B-8.

See also Appendix A, Figures A14 and A15.

The Pre-Collision Assist system automatically disables when you select 4X4 LOW or when you manually disable AdvanceTrac.

Is the vehicle equipped with a control whose purpose is to adjust the range setting or otherwise influence the operation of DBS?

 X Yes

 No

DYNAMIC BRAKE SUPPORT
DATA SHEET 4: DYNAMIC BRAKE SUPPORT SYSTEM OPERATION

(Page 4 of 4)

2020 Ford F-150 4X4 SuperCrew

If yes, please provide a full description.

The CIB and DBS functionality can be modified through the cluster menu, accessed by means of buttons on the steering wheel. The hierarchy is:

Settings

Pre-Collision

Alert Sensitivity –

Select High, Normal, or Low

Distance Indication - checkbox for on or off

Active Braking - checkbox for on or off

Pre-Collision - Select on or off

See the Owner's Manual, Pages 127, 131 and 277. These are shown in Appendix B, Pages B-2, B-3, and B-8.

See also Appendix A, Figures A14 and A15.

Are there other driving modes or conditions that render DBS inoperable or reduce its effectiveness?

 X Yes

 No

If yes, please provide a full description.

The limitations of the system are described in the Owner's Manual, Pages 274-275 and 277-278. These are shown in Appendix B, Pages B-5 to B-6 and B-8 to B-9.

Notes:

Section III

TEST PROCEDURES

A. Test Procedure Overview

Four test scenarios were used, as follows:

Test 1. Subject Vehicle (SV) Encounters Stopped Principal Other Vehicle (POV)

Test 2. Subject Vehicle Encounters Slower Principal Other Vehicle

Test 3. Subject Vehicle Encounters Decelerating Principal Other Vehicle

Test 4. Subject Vehicle Encounters Steel Trench Plate

An overview of each of the test procedures follows.

1. TEST 1 – SUBJECT VEHICLE ENCOUNTERS STOPPED PRINCIPAL OTHER VEHICLE ON A STRAIGHT ROAD

This test evaluates the ability of the DBS system to detect and respond to a stopped lead vehicle in the immediate forward path of the SV, as depicted in Figure 1.

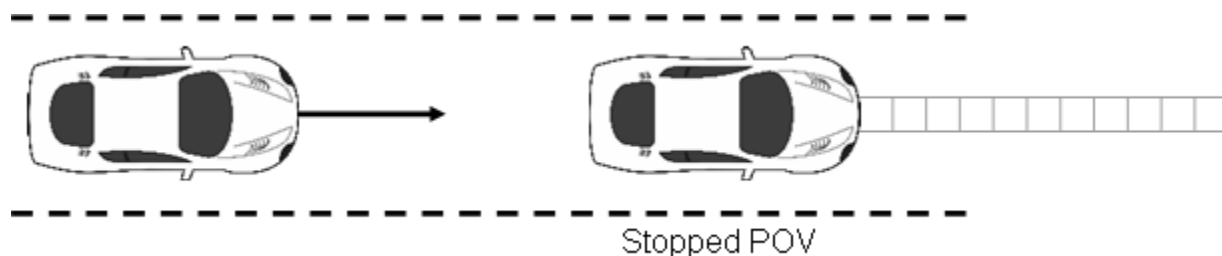


Figure 1. Depiction of Test 1

a. Procedure

The POV was parked in the center of a travel lane, with its longitudinal axis oriented parallel to the roadway edge and facing the same direction as the SV so that the SV approaches the rear of the POV.

The SV ignition was cycled prior to each test run. The SV was driven at a nominal speed of 25 mph (40.2 km/h) in the center of the lane of travel, toward the parked POV. The SV throttle pedal was released within 500 ms after t_{FCW} , i.e., within 500 ms of the FCW alert. The SV brakes were applied at $TTC = 1.1$ seconds (SV-to-POV distance of 40 ft (12 m)). The test concluded when either:

- The SV came into contact with the POV or

- The SV came to a stop before making contact with the POV.

In addition to the general test validity criteria described below, for an individual test trial to be valid, the following was required throughout the test:

- The SV speed could not deviate from the nominal speed by more than 1.0 mph (1.6 km/h) during an interval defined by a Time to Collision (TTC) = 5.1 seconds to t_{FCW} . For this test, TTC = 5.1 seconds is taken to occur at an SV-to-POV distance of 187 ft (57 m).

Table 1. Nominal Stopped POV DBS Test Choreography

Test Speeds		SV Speed Held Constant		SV Throttle Fully Released By		SV Brake Application Onset (for each application magnitude)	
SV	POV	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway
25 mph (40.2 km/h)	0	5.1 → t_{FCW}	187 ft (57 m) → t_{FCW}	Within 500 ms of FCW1 onset	Varies	1.1	40 ft (12 m)

b. Criteria

The performance requirement for this series of tests is that there be no SV-to-POV impact for at least five of the seven valid test trials.

2. TEST 2 – SUBJECT VEHICLE ENCOUNTERS SLOWER PRINCIPAL OTHER VEHICLE

This test evaluates the ability of the DBS system to detect and respond to a slower-moving lead vehicle traveling at a constant speed in the immediate forward path of the SV, as depicted in Figure 2.

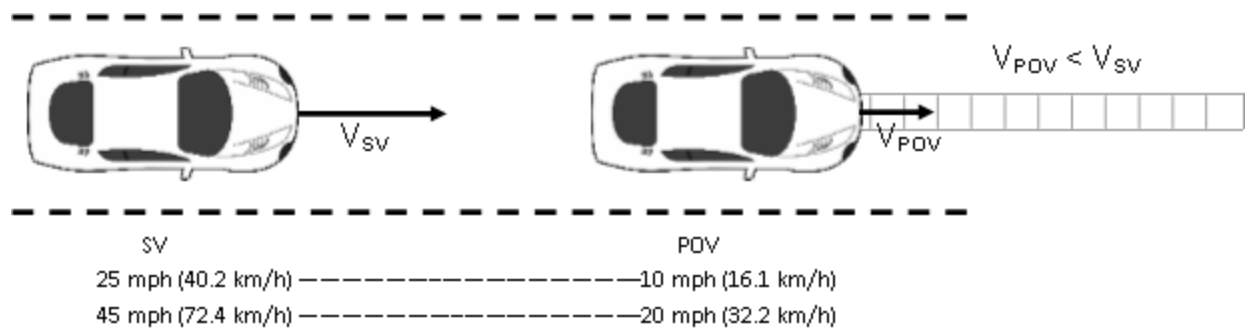


Figure 2. Depiction of Test 2

a. Procedure

The SV ignition was cycled prior to each test run. The tests were conducted two ways. In the first, the POV was driven at a constant 10.0 mph (16.1 km/h) in the center of the lane of travel while the SV was driven at 25.0 mph (40.2 km/h), in the center lane of travel, toward the slower-moving POV. In the second, the POV was driven at a constant 20.0 mph (32.2 km/h) in the center of the lane of travel while the SV was driven at 45.0 mph (72.4 km/h), in the center lane of travel, toward the slower-moving POV. In both cases, the SV throttle pedal was released within 500 ms after t_{FCW} , i.e., within 500 ms of the FCW alert. The SV brakes were applied at $TTC = 1.0$ seconds, assumed to be SV-to-POV distance of 22 ft (7 m) for an SV speed of 25 mph and 37 ft (11 m) for an SV speed of 45 mph.

The test concluded when either:

- The SV came into contact with the POV or
- 1 second after the speed of the SV became less than or equal to that of the POV.

The SV driver then braked to a stop.

In addition to the general test validity criteria described below, for an individual test trial to be valid, the following was required throughout the test:

- The lateral distance between the centerline of the POV and the center of the travel lane could not deviate more than ± 1 ft (0.3 m) during the validity period.
- The SV speed could not deviate more than ± 1.0 mph (± 1.6 km/h) during an interval defined by $TTC = 5.0$ seconds to t_{FCW} .
- The POV speed could not deviate more than ± 1.0 mph (± 1.6 km/h) during the validity period.

Table 2. Nominal Slower-Moving POV DBS Test Choreography

Test Speeds		SV Speed Held Constant		SV Throttle Fully Released By		SV Brake Application Onset (for each application magnitude)	
SV	POV	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway
25 mph (40 km/h)	10 mph (16 km/h)	$5.0 \rightarrow t_{FCW}$	110 ft (34 m) $\rightarrow t_{FCW}$	Within 500 ms of FCW1 onset	Varies	1.0	22 ft (7 m)
45 mph (72 km/h)	20 mph (32 km/h)	$5.0 \rightarrow t_{FCW}$	183 ft (56 m) $\rightarrow t_{FCW}$	Within 500 ms of FCW1 onset	Varies	1.0	37 ft (11 m)

b. Criteria

The performance requirement for this series of tests is that there be no SV-to-POV impact for at least five of the seven valid test trials.

3. TEST 3 – SUBJECT VEHICLE ENCOUNTERS DECELERATING PRINCIPAL OTHER VEHICLE

This test evaluates the ability of the DBS system to detect and respond to a lead vehicle slowing with a constant deceleration in the immediate forward path of the SV as depicted in Figure 3. Should the SV foundation brake system be unable to prevent an SV-to-POV impact for a given test condition, the DBS system should automatically provide supplementary braking capable of preventing an SV-to-POV collision.

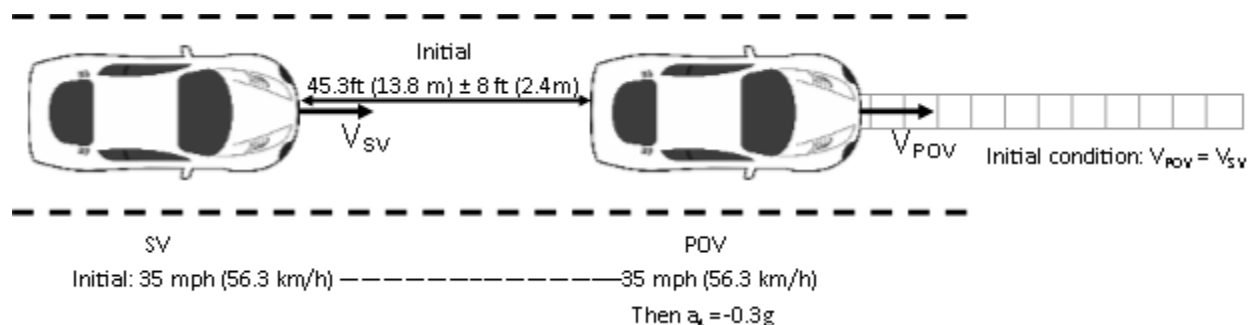


Figure 3. Depiction of Test 3 with POV Decelerating

a. Procedure

The SV ignition was cycled prior to each test run. For this scenario both the POV and SV were driven at a constant 35.0 mph (56.3 km/h) in the center of the lane, with headway of 45.3 ft (13.8 m) ± 8 ft (2.4 m). Once these conditions were met, the POV tow vehicle brakes were applied to achieve $0.3 \pm 0.03 g$. The SV throttle pedal was released within 500 ms of t_{FCW} , and the SV brakes were applied when TTC was 1.4 seconds (31.5 ft (9.6 m)).

The test concluded when either:

- The SV came into contact with the POV or
- 1 second after the velocity of the SV became less than or equal to that of the POV.

The SV driver then braked to a stop.

In addition to the general test validity criteria described below, for an individual test trial to be valid, the following was required throughout the test:

- The lateral distance between the centerline of the POV and the center of the travel lane could not deviate more than ± 1 ft (0.3 m) during the validity period.
- The headway between the SV and POV must have been constant from the onset

of the applicable validity period to the onset of POV braking.

- The SV and POV speed could not deviate more than ± 1.0 mph (1.6 km/h) during an interval defined by the onset of the validity period to the onset of POV braking.
- The average POV deceleration could not deviate by more than ± 0.03 g from the nominal 0.3 g deceleration during the interval beginning at 1.5 seconds after the onset of POV braking and ending either 250 ms prior to the POV coming to a stop or the SV coming into contact with the POV.

Table 3. Nominal Decelerating POV DBS Test Choreography

Test Speeds		SV Speed Held Constant		SV Throttle Fully Released By		SV Brake Application Onset (for each application magnitude)	
SV	POV	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway	TTC (seconds)	SV-to-POV Headway
35 mph (56 km/h)	35 mph (56 km/h)	3.0 seconds prior to POV braking → t_{FCW}	45 ft (14 m) → t_{FCW}	Within 500 ms of FCW1 onset	Varies	1.4	32 ft (10 m)

b. Criteria

The performance requirement for this series of tests is that no SV-to-POV contact occurs for at least five of the seven valid test trials.

4. TEST 4 – FALSE POSITIVE SUPPRESSION

The false positive suppression test series evaluates the ability of a DBS system to differentiate a steel trench plate (STP) from an object presenting a genuine safety risk to the SV. Although the STP is large and metallic, it is designed to be driven over without risk of injury to the driver or damage to the SV. Therefore, in this scenario, the automatic braking available from DBS is not necessary and should be suppressed. The test condition is nearly equivalent to that previously defined for Test 1, the stopped POV condition, but with an STP in the SV forward path in lieu of a POV.

a. Procedure

This test was conducted at two speeds, 25 mph (40.2 km/h) and 45 mph (72.4 km/h). The SV was driven directly towards, and over, the STP, which was positioned in the center of a travel lane, with its longest sides parallel to the road edge. The SV was driven at constant speed in the center of the lane toward the STP. If the SV did not present an FCW alert during the approach to the STP by $TTC = 2.1$ s, the SV driver initiated release of the throttle pedal at $TTC = 2.1$ s and the throttle pedal was fully released within 500 ms

of $TTC = 2.1$ s. The SV brakes were applied at TTC of 1.1 seconds, assumed to be 40 ft (12.3 m) from the edge of the STP at 25 mph or 73 ft (22.1 m) at 45 mph. The test concluded when the front most part of the SV reached a vertical plane defined by the edge of the STP first encountered by the SV.

b. Criteria

In order to pass the False Positive test series, the magnitude of the SV deceleration reduction attributable to DBS intervention must have been less than or equal to 1.25 times the average of the deceleration experienced by the baseline command from the braking actuator for at least five of seven valid test trials.

B. General Information

1. T_{FCW}

The time at which the Forward Collision Warning (FCW) activation flag indicates that the system has issued an alert to the SV driver is designated as t_{FCW} . FCW alerts are typically haptic, visual, or audible, and the onset of the alert is determined by post-processing the test data.

For systems that implement audible or haptic alerts, part of the pre-test instrumentation verification process is to determine the tonal frequency of the audible warning or the vibration frequency of the tactile warning through use of the PSD (Power Spectral Density) function in Matlab. This is accomplished in order to identify the center frequency around which a band-pass filter is applied to subsequent audible or tactile warning data so that the beginning of such warnings can be programmatically determined. The band-pass filter used for these warning signal types is a phaseless, forward-reverse pass, elliptical (Cauer) digital filter, with filter parameters as listed in Table 4.

Table 4. Audible and Tactile Warning Filter Parameters

Warning Type	Filter Order	Peak-to-Peak Ripple	Minimum Stop Band Attenuation	Passband Frequency Range
Audible	5 th	3 dB	60 dB	Identified Center Frequency \pm 5%
Tactile	5 th	3 dB	60 dB	Identified Center Frequency \pm 20%

2. GENERAL VALIDITY CRITERIA

In addition to any validity criteria described above for the individual test scenarios, for an individual trial to be valid, it must have met the following criteria throughout the test:

- The SV driver seatbelt was latched.
- If any load had been placed on the SV front passenger seat (e.g., for instrumentation), the vehicle's front passenger seatbelt was latched.
- The SV was driven at the nominal speed in the center of the travel lane, toward the POV or STP.
- The driver used the least amount of steering input necessary to maintain SV position in the center of the travel lane during the validity period; use of abrupt steering inputs or corrections was avoided.
- The yaw rate of the SV did not exceed ± 1.0 deg/s from the onset of the validity period to the instant SV deceleration exceeded 0.25 g.
- The SV driver did not apply any force to the brake pedal during the applicable validity period. All braking shall be performed by the programmable brake controller.
- The lateral distance between the centerline of the SV and the centerline of the POV or STP did not deviate more than ± 1 ft (0.3 m) during the applicable validity period.

3. VALIDITY PERIOD

The valid test interval began:

- Test 1: When the SV-to-POV TTC = 5.1 seconds
- Test 2: When the SV-to-POV TTC = 5.0 seconds
- Test 3: 3 seconds before the onset of POV braking
- Test 4: 2 seconds prior to the SV throttle pedal being released

The valid test interval ended:

- Test 1: When either of the following occurred:
 - The SV came in contact with the POV (SV-to-POV contact was assessed by using GPS-based range data or by measurement of direct contact sensor output); or
 - The SV came to a stop before making contact with the POV.
- Test 2: When either of the following occurred:
 - The SV came into contact with the POV; or
 - 1 second after the velocity of the SV became less than or equal to that of the POV.
- Test 3: When either of the following occurred:
 - The SV came in contact with the POV; or
 - 1 second after minimum SV-to-POV range occurred.
- Test 4: When the SV stopped.

4. STATIC INSTRUMENTATION CALIBRATION

To assist in resolving uncertain test data, static calibration data was collected prior to each of the test series.

For Tests 1, 2, and 3, the SV, POV, POV moving platform, and tow vehicle were centered in the same travel lane with the same orientation (i.e., facing the same direction). For Test 4, the SV and STP were centered in the same travel lane.

For Tests 1, 2, and 3, the SV was positioned such that it just contacted a vertical plane defining the rearmost location of the POV. For Test 4, the front-most location of the SV was positioned such that it just reached a vertical plane defined by the leading edge of

the STP first encountered by the SV (i.e., just before it is driven onto the STP). This is the “zero position.”

The zero position was documented prior to, and immediately after, conduct of each test series.

If the zero position reported by the data acquisition system was found to differ by more than ± 2 in (± 5 cm) from that measured during collection of the pre-test static calibration data file, the pre-test longitudinal offset was adjusted to output zero and another pre-test static calibration data file was collected. If the zero position reported by the data acquisition system was found to differ by more than ± 2 in (± 5 cm) from that measured during collection of the post-test static calibration data file, the test trials performed between collection of that post-test static calibration data file and the last valid pre-test static calibration data file were repeated.

Static data files were collected prior to, and immediately after, conduct each of the test series. The pre-test static files were reviewed prior to test conduct to confirm that all data channels were operational and were properly configured.

5. NUMBER OF TRIALS

A target total of seven (7) valid trials were performed for each scenario. In cases where the test driver performed more than seven trials, the first seven trials satisfying all test tolerances were used to assess the SV performance.

6. TRANSMISSION

All trials were performed with SV automatic transmissions in “Drive” or with manual transmissions in the highest gear capable of sustaining the desired test speed. Manual transmission clutches remained engaged during all maneuvers. The brake lights of the POV were not illuminated.

C. Principal Other Vehicle

DBS testing requires a POV that realistically represents typical vehicles, does not suffer damage or cause damage to a test vehicle in the event of collision, and can be accurately positioned and moved during the tests. The tests reported herein made use of the NHTSA developed Strikeable Surrogate Vehicle (SSV).

This SSV system was designed specifically for common rear-end crash scenarios which AEB systems address. The key components of the SSV system are:

- A POV shell which is a visually and dimensionally accurate representation of a passenger car.
- A slider and load frame assembly to which the shell is attached.
- A two-rail track on which the slider operates.

- A road-based lateral restraint track.
- A tow vehicle.

The key requirements of the POV element are to:

- Provide an accurate representation of a real vehicle to DBS sensors, including cameras and radar.
- Be resistant to damage and inflict little or no damage to the SV as a result of repeated SV-to-POV impacts.

The key requirements of the POV delivery system are to:

- Accurately control the nominal POV speed up to 35 mph (56 km/h).
- Accurately control the lateral position of the POV within the travel lane.
- Allow the POV to move away from the SV after an impact occurs.

Operationally, the POV shell is attached to the slider and load frame, which includes rollers that allow the entire assembly to move longitudinally along the guide rail. The guide rail is coupled to a tow vehicle and guided by the lateral restraint track secured to the test track surface. The rail includes a provision for restraining the shell and roller assembly in the rearward direction. In operation, the shell and roller assembly engages the rail assembly through detents to prevent relative motion during run-up to test speeds and minor deceleration of the tow vehicle. The combination of rearward stops and forward motion detents allows the test conditions, such as relative POV-SV headway distance and speed etc., to be achieved and adjusted as needed in the preliminary part of a test. If during the test, the SV strikes the rear of the POV shell, the detents are overcome and the entire shell/roller assembly moves forward in a two-stage manner along the rail and away from the SV. The forward end of the rail has a soft stop to restrain forward motion of the shell/roller assembly. After impacting the SSV, the SV driver uses the steering wheel to maintain SV position in the center of the travel lane, thereby straddling the two-rail track. The SV driver must manually apply the SV brakes after impact. The SSV system is shown in Figures A6 through A8 and a detailed description can be found in the NHTSA report: NHTSA'S STRIKEABLE SURROGATE VEHICLE PRELIMINARY DESIGN + OVERVIEW, May 2013.

D. Foundation Brake System Characterization

Data collected and analyzed from a series of pre-test braking runs were used to objectively quantify the response of the vehicle's foundation brake system without the contribution of DBS. The results of these analyses were used to determine the brake pedal input magnitudes needed for the main tests.

This characterization was accomplished by recording longitudinal acceleration and brake pedal force and travel data for a variety of braking runs. For three initial brake characterization runs, the vehicle was driven at 45 mph, and the brakes were applied at a rate of 1 inch/sec up to the brake input level needed for at least 0.7 g. Linear regressions were performed on the data from each run to determine the linear vehicle deceleration

response as a function of both applied brake pedal force and brake pedal travel. The brake input force or displacement level needed to achieve a vehicle deceleration of 0.4 g was determined from the average of the three runs. Using the 0.4 g brake input force or displacement level found from the three initial runs, subsequent runs were performed at 25 mph, 35 mph, and 45 mph, with the brakes applied at a rate of 10 inch/sec to the determined 0.4 g brake input force or displacement level. For each of the three test speeds, if the average calculated deceleration level was found to be within 0.4 ± 0.025 g, the resulting force or displacement was recorded and used. If the average calculated deceleration level exceeded this tolerance, the brake input force or displacement levels were adjusted and retested until the desired magnitude was realized. Prior to each braking event, the brake pad temperatures were required to be in the range of 149° - 212°F.

E. Brake Control

1. SUBJECT VEHICLE PROGRAMMABLE BRAKE CONTROLLER

To achieve accurate, repeatable, and reproducible SV brake pedal inputs, a programmable brake controller was used for all brake applications. The controller has the capability to operate in one of two user-selectable, closed-loop, control modes:

- Constant pedal displacement. By maintaining constant actuator stroke, the position of the vehicle's brake pedal remains fixed for the duration of the input. To achieve this, the brake controller modulates application force.
- Hybrid control. Hybrid control uses position-based control to command the initial brake application rate and actuator position, then changes to force-based control to command a reduction of applied force to a predetermined force. This force is maintained until the end of the braking maneuver by allowing the brake controller to modulate actuator displacement.

2. SUBJECT VEHICLE BRAKE PARAMETERS

- Each test run began with the brake pedal in its natural resting position, with no preload or position offset.
- The onset of the brake application was considered to occur when the brake actuator had applied 2.5 lbf (11 N) of force to the brake pedal.
- The magnitude of the brake application was that needed to produce 0.4 g deceleration, as determined in the foundation brake characterization.
- The SV brake application rate was between 9 to 11 in/s (229 to 279 mm/s), where the application rate is defined as the slope of a linear regression line applied to brake pedal position data over a range from 25% to 75% of the commanded input magnitude.

3. POV AUTOMATIC BRAKING SYSTEM

The POV was equipped with an automatic braking system, which was used in Test Type

3. The braking system consisted of the following components:

- Electronically controlled linear actuator, mounted on the seat rail and attached to the brake pedal. The actuator can be programmed for control of stroke and rate.
- PC module programmed for control of the stroke and rate of the linear actuator.
- Switch to activate actuator.

F. Instrumentation

Table 5 lists the sensors, signal conditioning, and data acquisition equipment used for these tests.

Table 5. Test Instrumentation and Equipment

Type	Output	Range	Accuracy, Other Primary Specs	Mfr, Model	Serial Number	Calibration Dates Last Due
Tire Pressure Gauge	Vehicle Tire Pressure	0-100 psi 0-690 kPa	< 1% error between 20 and	Omega DPG8001	17042707002	By: DRI Date: 7/3/2019 Due: 7/3/2020
Platform Scales	Vehicle Total, Wheel, and Axle Load	2200 lb/platform	0.1% of reading	Intercomp SW wireless	0410MN20001	By: DRI Date: 4/20/2020 Due: 4/20/2021
Linear (string) encoder	Throttle pedal travel	10 in 254 mm	0.1 in 2.54 mm	UniMeasure LX-EP	49041189	By: DRI Date: 5/22/2020 Due: 5/22/2021
Load Cell	Force applied to brake pedal					By: DRI
		0 - 250 lb 0 - 1112 N	0.1% FS	Honeywell 41A	1464391	Date: 8/30/2019 Due: 8/30/2020
		0-250 lb 1112 N	0.05% FS	Stellar Technology PNC700	1607338	Date: 8/30/2019 Due: 8/30/2020
Differential Global Positioning System	Position, Velocity	Latitude: ± 90 deg Longitude: ± 180 deg Altitude: 0-18 km Velocity: 0-1000 knots	Horizontal Position: ± 1 cm Vertical Position: ± 2 cm Velocity: 0.05 km/h	Trimble GPS Receiver, 5700 (base station and in-vehicle)	00440100989	NA

Table 5. Test Instrumentation and Equipment (continued)

Type	Output	Range	Accuracy, Other Primary Specs	Mfr, Model	Serial Number	Calibration Dates Last Due
Multi-Axis Inertial Sensing System	Position; Longitudinal, Lateral, and Vertical Accels; Lateral, Longitudinal and Vertical Velocities; Roll, Pitch, Yaw Rates; Roll, Pitch, Yaw Angles	Accels $\pm 10g$, Angular Rate ± 100 deg/s, Angle >45 deg, Velocity >200 km/h	Accels $.01g$, Angular Rate 0.05 deg/s, Angle 0.05 deg, Velocity 0.1 km/h	Oxford Inertial +		By: Oxford Technical Solutions
					2258	Date: 5/3/2019 Due: 5/3/2021
					2182	Date: 9/16/2019 Due: 9/16/2021
Real-Time Calculation of Position and Velocity Relative to Lane Markings (LDW) and POV (FCW)	Distance and Velocity to lane markings (LDW) and POV (FCW)	Lateral Lane Dist: ± 30 m Lateral Lane Velocity: ± 20 m/sec Longitudinal Range to POV: ± 200 m Longitudinal Range Rate: ± 50 m/sec	Lateral Distance to Lane Marking: ± 2 cm Lateral Velocity to Lane Marking: ± 0.02 m/sec Longitudinal Range: ± 3 cm Longitudinal Range Rate: ± 0.02 m/sec	Oxford Technical Solutions (OXTS), RT-Range	97	NA
Microphone	Sound (to measure time at alert)	Frequency Response: 80 Hz – 20 kHz	Signal-to-noise: 64 dB, 1 kHz at 1 Pa	Audio-Technica AT899	NA	NA
Light Sensor	Light intensity (to measure time at alert)	Spectral Bandwidth: 440-800 nm	Rise time < 10 msec	DRI designed and developed Light Sensor	NA	NA
Accelerometer	Acceleration (to measure time at alert)	$\pm 5g$	$\leq 3\%$ of full range	Silicon Designs, 2210-005	NA	NA

Type	Output	Range	Accuracy, Other Primary Specs	Mfr, Model	Serial Number	Calibration Dates Last Due
Coordinate Measurement Machine	Inertial Sensing System Coordinates	0-8 ft 0-2.4 m	± 0.0020 in. ± 0.051 mm (Single point articulation accuracy)	Faro Arm, Fusion	UO8-05-08-06636	By: DRI Date: 1/6/2020 Due: 1/6/2021
Type	Description			Mfr, Model		Serial Number
Data Acquisition System	Data acquisition is achieved using a dSPACE MicroAutoBox II. Data from the Oxford IMU, including Longitudinal, Lateral, and Vertical Acceleration, Roll, Yaw, and Pitch Rate, Forward and Lateral Velocity, Roll and Pitch Angle are sent over Ethernet to the MicroAutoBox. The Oxford IMUs are calibrated per the manufacturer's recommended schedule (listed above).			dSPACE Micro-Autobox II 1401/1513		
				Base Board		549068
				I/O Board		588523

APPENDIX A

Photographs

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Figure A1. Front View of Subject Vehicle



Figure A2. Rear View of Subject Vehicle

Go Further
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VEHICLE DESCRIPTION

F-150

2020 F-150 4X4 SUPERCREW
145" WHEELBASE
3.5L V6 ECOBOOST
ELEC 10-SPEED AUTO W/TOW MD

EXTERIOR
MAGNETIC
INTERIOR
BLACK LTHR TRIM BUCKET SEAT

LF A1

STANDARD EQUIPMENT INCLUDED AT NO EXTRA CHARGE

EXTERIOR

- BOX LIGHTING-LED
- BOXLINK™
- DAYTIME RUNNING LIGHTS
- FOG LAMPS
- FULLY BOXED STEEL FRAME
- HEADLAMPS - AUTO HIGH BEAM
- HEADLAMPS - AUTOLAMP (ON/OFF)
- PICKUP BOX TIE DOWN HOOKS
- POWER ADJ/HEATED/POWER FOLD EXTERIOR MIRRORS
- POWER SLIDING REAR WINDOW W/DEFROST & PRIVACY TINT
- POWER TAILGATE LOCK
- TRAILER SWAY CONTROL

INTERIOR

- 60/40 FOLD-UP REAR BENCH
- 8.0" PRODUCTIVITY SCREEN
- A/C W/DUAL CLIMATE CONTROL
- ADJUST PEDALS W/MEMORY
- AMBIENT LIGHTING-ONE COLOR
- AUTO DIM REARVIEW MIRROR
- HTD/VENTILATED FRT SEATS
- LEATHER TRIMMED SEATS
- LEATHER WRAPPED STR WHEEL
- POWER DRV AND PASS SEATS-10-WAY WITH DRV MEMORY AND LUMBAR
- STEERING - TILT/TELESCOPIC WHEEL WITH AUDIO

FUNCTIONAL

- AUTO START STOP TECH
- BLIS W/CROSS-TRAFFIC ALERT
- CLASS IV TRAILER HITCH W/SMART TRLR TOW CONNECTOR
- FORDPASS™ CONNECT 4GWI-FI HOTSPOT TELEMATICS MODEM
- GAS-CHARGED SHOCKS
- INTELLIGENT ACCESS W/PUSH BUTTON START
- LANE KEEPING SYSTEM
- PRE-COLLISION ASSIST W/AEB
- REAR VIEW CAMERA
- REMOTE START- FORDPASS APP
- SIRIUSXM® - SVC N/A AK&HI
- SYNC®3 8" SCRIN W/APPLINK®

SAFETY/SECURITY

- ADVANCED SECURITY PACK
- ADVANCETRAC® WITH RSC®
- AIRBAGS - FRONT SEAT MOUNTED SIDE IMPACT
- AIRBAGS - SAFETY CANOPY®
- CTR HIGH MOUNT STOP LAMP
- SOS POST-CRASH ALERT SYS™
- TIRE PRESSURE MONIT SYS

WARRANTY

- 3YR/36,000 BUMPER / BUMPER
- 5YR/60,000 POWERTRAIN
- 5YR/60,000 ROADSIDE ASSIST

INCLUDED ON THIS VEHICLE

EQUIPMENT GROUP 502A

- LARIAT SERIES
- REMOTE START SYSTEM
- REVERSE SENSING SYSTEM
- LED SIDE-MIRROR SPOTLIGHTS
- 110V/400W OUTLET
- 8-SPEAKER SOUND SYSTEM
- HEATED STEERING WHEEL
- LARIAT BED UTILITY PACKAGE
- BOXLINK
- LED BOX LIGHTING
- SECOND-ROW HEATED SEATS

OPTIONAL EQUIPMENT/OTHER

- 3.5L V6 ECOBOOST 1,600.00
- 275/55R20 BSW ALL-TERRAIN NO CHARGE
- 3.55 ELECTRONIC LOCK RR AXLE NO CHARGE
- 7000X GVWR PACKAGE NO CHARGE
- FRONT LICENSE PLATE BRACKET 995.00
- POWER-DEPLOYABLE RUNNING BDS NO CHARGE
- CALIFORNIA EMISSIONS SYSTEM NO CHARGE
- TWIN PANEL MOONROOF 1,495.00
- PRO TRAILER BACKUP ASSIST 1,250.00
- ADAPT CRUISE-STOPGO-PEDEST DEC 795.00
- VOICE-ACTIVATED NAVIGATION 1,295.00
- MAX TRAILER TOW PACKAGE
- 36GAL EXTENDED RANGE FUEL TAN
- INTEGRATED TRAILER BRAKE CONT
- FX4 OFF-ROAD PACKAGE
- 36KD PLATES
- FLOOR LINER - TRAY STYLE 905.00

PRICE INFORMATION

375.00 MSRP

20" SIX-SPOKE DARK ALLOY WHLS TECHNOLOGY PACKAGE 1,295.00

360-DEGREE CAMERA LARIAT SPORT APPEARANCE PKG 300.00

TOTAL BEFORE DISCOUNTS 58,645.00

XL/LARIAT DISCT NAV - 500.00

LAR LUX CHROME OR SPRT - 1,500.00

TECH & ADP CRUISE DISCT - 500.00

TOTAL SAVINGS - 2,500.00

TOTAL MSRP \$66,145.00

GOVERNMENT 5-STAR SAFETY RATINGS

Overall Vehicle Score ★★★★★

Based on the combined ratings of frontal, side and rollover. Should ONLY be compared to other vehicles of similar size and weight.

Frontal Crash Driver ★★★★★ Passenger ★★★★★

Based on the risk of injury in a frontal impact. Should ONLY be compared to other vehicles of similar size and weight.

Side Crash Front seat ★★★★★ Rear seat ★★★★★

Based on the risk of injury in a side impact.

Rollover ★★★★★

Based on the risk of rollover in a single-vehicle crash.

Star ratings range from 1 to 5 stars (★★★★★), with 5 being the highest.

Source: National Highway Traffic Safety Administration (NHTSA).
www.safercar.gov or 1-888-327-4236

Fuel Economy and Environment

Fuel Economy

18 MPG combined city/hwy

16 city

22 highway

5.6 gallons per 100 miles

Standard Pickup Trucks range from 12 to 25 MPG. The best vehicle rates 136 MPG.

You spend \$3,750 more in fuel costs over 5 years compared to the average new vehicle.

Annual fuel cost \$2,250

Fuel Economy & Greenhouse Gas Rating (tailpipe only) 3

Smog Rating (tailpipe only) 5

This vehicle emits 488 grams CO₂ per mile. The best emits 0 grams per mile (tailpipe only). Producing and distributing fuel also create emissions. Learn more at fuelconomy.gov.

Actual results will vary for many reasons, including driving conditions and how you drive and maintain your vehicle. The average new vehicle gets 27 MPG and costs \$7,500 to fuel over 5 years. Cost estimates are based on 15,000 miles per year at \$2.70 per gallon. MPGe is miles per gasoline gallon equivalent. Vehicle emissions are a significant cause of climate change and smog.

fuelconomy.gov

Calculate personalized estimates and compare vehicles

42 YEARS FORD F-SERIES

AMERICA'S BEST SELLING TRUCKS

BUILT FORD TOUGH

FORD PROTECT

Insist on Ford Protect! The only extended service plan fully backed by Ford and honored at every Ford dealership in the U.S., Canada and Mexico. See your Ford dealer or visit www.FordOwner.com.

SCAN OR TEXT 3FJA 70 48226

Wing & Date rates may apply. Text HELP for help.

www.ford.com/PassengerWarning

WARNING: Operating, servicing and maintaining a passenger vehicle, pickup truck, van, or off-road vehicle can expose you to chemicals including engine exhaust, carbon monoxide, phthalates, and lead, which are known to the State of California to cause cancer and birth defects or other reproductive harm. To minimize exposure, avoid breathing exhaust, do not idle the engine except as necessary, service your vehicle in a well-ventilated area and wear gloves or wash your hands frequently when servicing your vehicle. For more information go to www.PSVWarnings.ca.gov/passenger-vehicle.

1FTEW1E42LFA1

MANUFACTURER'S SUGGESTED RETAIL PRICE

DEALER INSTALLED OPTIONS

FACTORY DISCOUNTS

Figure A3. Window Sticker (Monroney Label)

MFD. BY FORD MOTOR CO.

FRONT GAWR: 1599 KG (3525 LB)

WITH 275/55R20 113T
20x8.5J

AT 240 kPa/ 35 PSI COLD

THIS VEHICLE CONFORMS TO ALL APPLICABLE FEDERAL MOTOR VEHICLE
SAFETY STANDARDS IN EFFECT ON THE DATE OF MANUFACTURE SHOWN ABOVE.

VIN: 1FTEW1E42LFA1

DATE: 10/19

GVWR: 3175 KG (7000 LB)

REAR GAWR: 1837 KG (4050 LB)

TIRES
RIMS

WITH 275/55R20 113T
20x8.5J

AT 240 kPa/ 35 PSI COLD

TIRES
RIMS



EXT PNT: J7

RC: 71 DSO:

WB

INT TR

TP/PS

R

AXLE

TR

SPR

F0044

145

HB

3

L9

G

33BB

T0378

MADE IN U.S.A.

2201910076053

ULC

▽ 5U5A-3520472-AA

Figure A4. Vehicle Certification Label



TIRE AND LOADING INFORMATION

SEATING CAPACITY TOTAL : 5 FRONT: 2 REAR: 3

The combined weight of occupants and cargo should never exceed : **701 kg or 1546 lbs.**

▽5U5A-1532-AA (TLU)

TIRE	SIZE	COLD TIRE PRESSURE
FRONT	275/55R20 113T	240 KPA, 35 PSI
REAR	275/55R20 113T	240 KPA, 35 PSI
SPARE	265/70R17 115T	240 KPA, 35 PSI

**SEE OWNERS
MANUAL FOR
ADDITIONAL
INFORMATION**

1FTEW1E42LFA1



Figure A5. Tire Placard



Figure A6. Rear View of Principal Other Vehicle (SSV)



Figure A7. Load Frame/Slider of SSV

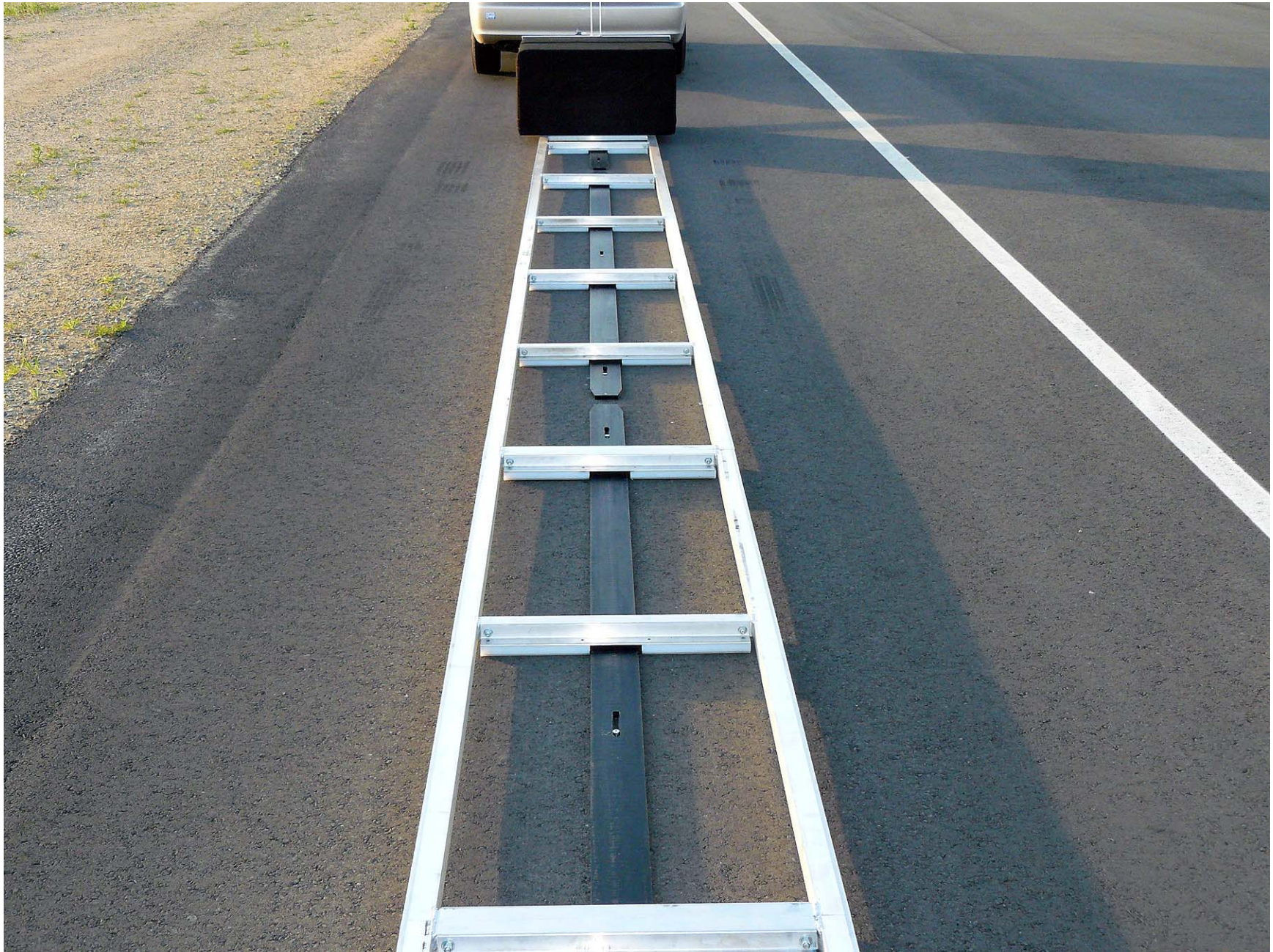


Figure A8. Two-Rail Track and Road-Based Lateral Restraint Track



Figure A9. Steel Trench Plate
A-11



Figure A10. DGPS, Inertial Measurement Unit, and MicroAutoBox Installed in Subject Vehicle

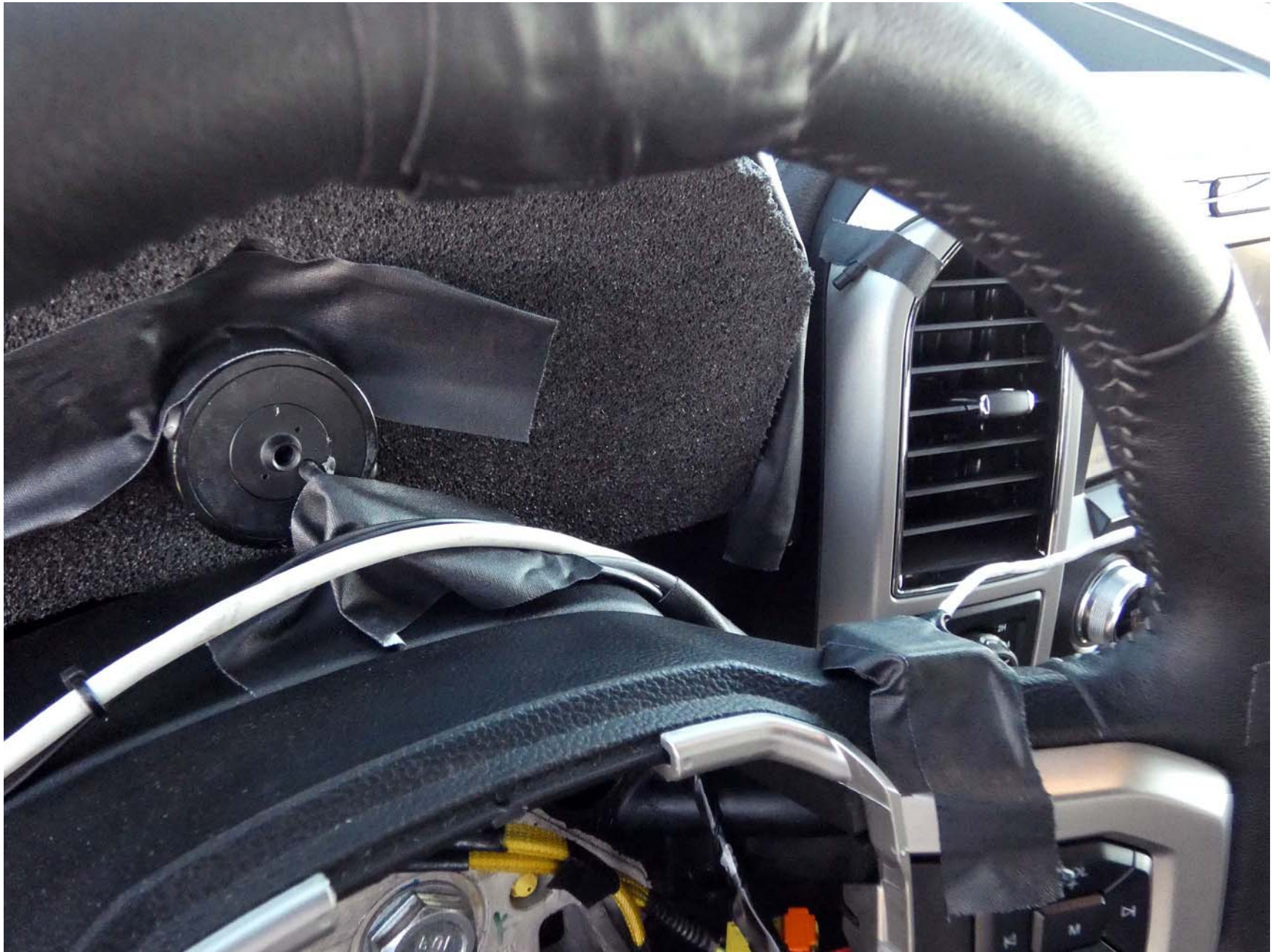


Figure A11. Sensors for Detecting Auditory and Visual Alerts



Figure A12. Computer and Brake Actuator Installed in Subject Vehicle



Figure A13. Brake Actuator Installed in POV System



Figure A14. System Setup Menus



Figure A15. Controls for Changing System Setup Parameters

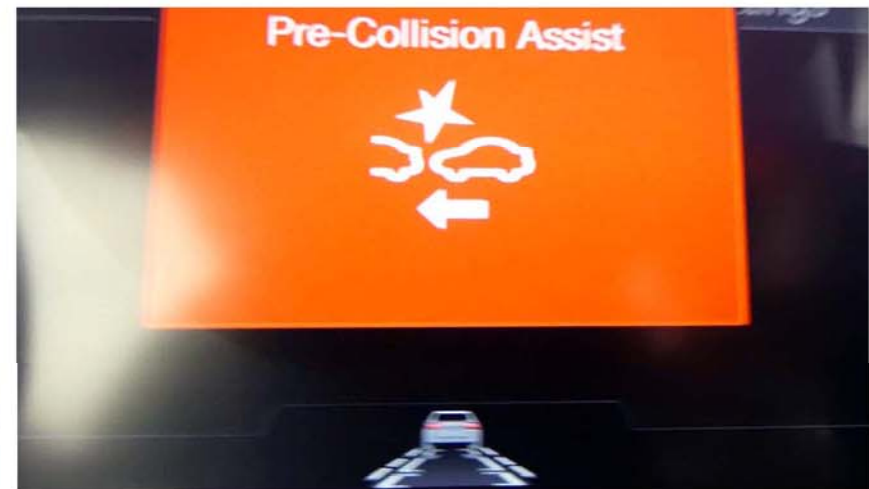


Figure A16. Visual Alert
A-18

APPENDIX B

Excerpts from Owner's Manual

Information Displays

Settings		
	MyKey	Enter the submenu and select your setting
	Display Setup	Units
		Temperature
		Tire Pressure
		Language

Information Display Controls (Type 3) (If Equipped)



E176093

- Press the up and down arrow buttons to scroll through and highlight the options within a menu.
- Press the right arrow button to enter a sub-menu.

- Press the left arrow button to exit a menu.
- Press the **OK** button to choose and confirm a setting or messages.

Main menu

You can access the menus using the information display control.

- My View
- Trip/Fuel
- Truck Info
- Towing
- Off Road
- Settings

My View

- Use the arrow buttons to choose between the following My View options.

Information Displays

Towing	
Con- nec- tion Check- list	Conventional
	Fifth Wheel
	Gooseneck

Off Road



Use the arrow buttons to choose between the following off road options.

Off Road	
Off Road Status	Pitch, Steering Angle, Roll, Elocker and 4X4
Power Distribution	

Settings



Use the arrow buttons to configure different driver setting choices.

Settings	
Auto Regen	
Cross Traffic Alert	
Driver Alert	
Rear Park Aid	
Trailer Blind Spot	
Pre-Collision	Enter the submenu for items such as alert sensitivity, distance indication and active braking
Cruise Control	Enter the submenu and select your setting
DTE Calcula- tion	Enter the submenu and select your setting

Information Displays

Message	Action
Park Brake Maintenance Mode	The electric park brake system has been put into a special mode that is used to allow service of the rear brakes. Contact an authorized dealer.
Park Brake Limited Function Service Required	The electric park brake system has detected a condition that requires service. Some functionality may still be available. Contact an authorized dealer.
Park Brake Malfunction Service Now	The electric park brake system has detected a condition that requires service. Contact an authorized dealer.

Power Steering

Message	Action
Steering Fault Service Now	The power steering system has detected a condition that requires service. See an authorized dealer.
Steering Loss Stop Safely	The power steering system is not working. Stop your vehicle in a safe place. Contact an authorized dealer.
Steering Assist Fault Service Required	The power steering system has detected a condition within the power steering system or passive entry or passive start system requires service. Contact an authorized dealer.
Steering Lock Malfunction Service Now	The steering lock system has detected a condition that requires service. See an authorized dealer.

Pre-Collision Assist

Message	Action
Pre-Collision Assist Not Available Sensor Blocked	You have a blocked sensor due to bad weather, ice, mud or water in front of the radar sensor. You can typically clean the sensor to resolve.
Pre-Collision Assist Not Available	A fault with the system has occurred. Contact an authorized dealer as soon as possible.

Driving Aids

Extreme continuous steering may increase the effort required for you to steer your vehicle, this increased effort prevents overheating and permanent damage to the steering system. You do not lose the ability to steer your vehicle manually. Typical steering and driving maneuvers allow the system to cool and return to normal operation.

Steering Tips

If the steering wanders or pulls, check for:


- Correct tire pressures.
- Uneven tire wear.
- Loose or worn suspension components.
- Loose or worn steering components.
- Improper vehicle alignment.


Note: A high crown in the road or high crosswinds may also make the steering seem to wander or pull.


Adaptive Learning (If Equipped)


The electronic power steering system adaptive learning helps correct road irregularities and improves overall handling and steering feel. It communicates with the brake system to help operate advanced stability control and accident avoidance systems. Additionally, whenever the battery is disconnected or a new battery installed, you must drive your vehicle a short distance before the system relearns the strategy and reactivates all systems.


PRE-COLLISION ASSIST

 **WARNING:** You are responsible for controlling your vehicle at all times. The system is designed to be an aid and does not relieve you of your responsibility to drive with due care and attention. Failure to follow this instruction could result in the loss of control of your vehicle, personal injury or death.

 **WARNING:** The system does not detect vehicles that are driving in a different direction, cyclists or animals. Failure to take care may result in the loss of control of your vehicle, serious personal injury or death.

 **WARNING:** The system does not operate during hard acceleration or steering. Failure to take care may lead to a crash or personal injury.

 **WARNING:** The system may fail or operate with reduced function during cold and severe weather conditions. Snow, ice, rain, spray and fog can adversely affect the system. Keep the front camera and radar free of snow and ice. Failure to take care may result in the loss of control of your vehicle, serious personal injury or death.

 **WARNING:** In situations where the vehicle camera has limited detection capability, this may reduce system performance. These situations include but are not limited to direct or low sunlight, vehicles at night without tail lights, unconventional vehicle types, pedestrians with complex backgrounds,

Driving Aids

partly obscured pedestrians, or pedestrians that the system cannot distinguish from a group. Failure to take care may result in the loss of control of your vehicle, serious personal injury or death.

⚠ WARNING: The system cannot help prevent all crashes. Do not rely on this system to replace driver judgment and the need to maintain a safe distance and speed.

Using the Pre-Collision Assist System

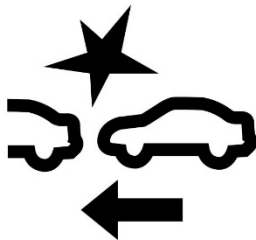
The Pre-Collision Assist system is active at speeds above approximately 3 mph (5 km/h) and pedestrian detection is active at speeds up to 50 mph (80 km/h).



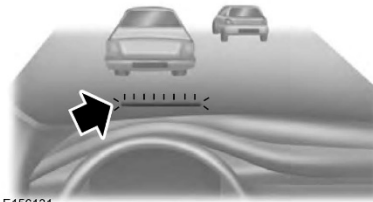
E156130

If your vehicle is rapidly approaching another stationary vehicle, a vehicle traveling in the same direction as yours, or a pedestrian within your driving path, the system provides three levels of functionality:

1. Alert
2. Brake Support
3. Active Braking



E255268



E156131

Alert: When active, a flashing visual warning appears and an audible warning tone sounds.

Brake Support: The system is designed to help reduce the impact speed by preparing the brakes for rapid braking. The system does not automatically apply the brakes. If you press the brake pedal, the system could apply additional braking up to maximum braking force, even if you lightly press the brake pedal.

Active Braking: Active braking may activate if the system determines that a collision is imminent. The system may help the driver reduce impact damage or avoid the crash completely.

Note: *Brake Support and Active Braking are active at speeds up to 75 mph (120 km/h). If the vehicle has a radar sensor or Adaptive Cruise Control, then Brake Support and Active Braking are active up to the maximum speed of the vehicle.*

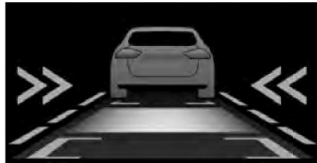
Note: *If you perceive Pre-Collision Assist alerts as being too frequent or disturbing, then you can reduce the alert sensitivity, though the manufacturer recommends using the highest sensitivity setting where possible. Setting lower sensitivity would lead to fewer and later system warnings.*

Note: *The Pre-Collision Assist system automatically disables when you select 4X4 LOW or when you manually disable AdvanceTrac™.*

Driving Aids

Distance Indication and Alert (If Equipped)

Distance Indication and Alert is a function that provides the driver with a graphical indication of the time gap to other preceding vehicles traveling in the same direction. The Distance Indication and Alert screen in the display screen shows one of the graphics that follow.



E254791

If the time gap to a preceding vehicle is small, a red visual indication displays.

Note: *Distance Indication and Alert deactivates and the graphics do not display when Adaptive Cruise Control is active.*

Speed	Sensitivity	Graphics	Distance Gap	Time Gap
62 mph (100 km/h)	Normal	Grey	>82 ft (25 m)	>0.9sec
62 mph (100 km/h)	Normal	Yellow	56–82 ft (17–25 m)	0.6sec — 0.9sec
62 mph (100 km/h)	Normal	Red	<56 ft (17 m)	<0.6sec

Driving Aids

Adjusting the Pre-Collision Assist Settings

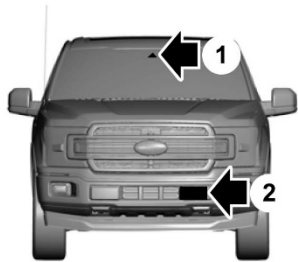
You can adjust the following settings by using the information display controls. See **General Information** (page 120).

- You can change Alert and Distance Alert sensitivity to one of three possible settings.
- You can switch Distance Indication and Alert on or off.
- If required, you can switch Active Braking on or off.
- If required, you can switch the entire Pre-Collision Assist feature on or off.

Note: Active braking automatically turns on every time you switch the ignition on.

Note: If your vehicle has a radar sensor, we recommend that you switch the system off if you install a snow plow or similar object in such a way that it may block the radar sensor. Your vehicle remembers the selected setting across key cycles.

Blocked Sensors



- 1 Camera.
- 2 Radar sensor (if equipped).

If a message regarding a blocked sensor or camera appears in the information display, the radar signals or camera images are obstructed. If your vehicle has a radar sensor, it is located behind the fascia cover in the center of the lower grille. With a blocked sensor or camera, the Pre-Collision Assist system may not function, or performance may reduce. The following table lists possible causes and actions for when this message displays.

Camera Troubleshooting

Cause	Action
The windshield in front of the camera is dirty or obstructed in some way.	Clean the outside of the windshield in front of the camera.
The windshield in front of the camera is clean but the message remains in the display screen.	Wait a short time. It may take several minutes for the camera to detect that there is no obstruction.

Driving Aids

Radar Troubleshooting (If Equipped)

Cause	Action
The surface of the radar in the grille is dirty or obstructed in some way.	Clean the grille surface in front of the radar or remove the object causing the obstruction.
The surface of the radar in the grille is clean but the message remains in the display screen.	Wait a short time. It may take several minutes for the radar to detect that there is no obstruction.
Heavy rain, spray, snow or fog is interfering with the radar signals.	The Pre-Collision Assist system is temporarily disabled. Pre-Collision Assist automatically reactivates a short time after the weather conditions improve.
Swirling water or snow or ice on the surface of the road may interfere with the radar signals.	The Pre-Collision Assist system is temporarily disabled. Pre-Collision Assist automatically reactivates a short time after the weather conditions improve.
Radar is out of alignment due to a front end impact.	Contact an authorized dealer to have the radar checked for proper coverage and operation.

Note: Proper system operation requires a clear view of the road by the camera. Have any windshield damage in the area of the camera's field of view repaired.

Note: If something hits the front end of your vehicle or damage occurs and your vehicle has a radar sensor, the radar sensing zone may change. This could cause missed or false vehicle detections. Contact an authorized dealer to have the radar checked for proper coverage and operation.

Note: If your vehicle detects excessive heat at the camera or a potential misalignment condition, a message may display in the information display indicating temporary sensor unavailability. When operational conditions are correct, the message deactivates. For example, when the ambient temperature around the sensor decreases or the sensor automatically recalibrates successfully.

DRIVE CONTROL

Selectable Drive Modes

This provides a single location to control multiple system performance settings such as steering, handling and powertrain response.

Changing the drive mode automatically changes the functionality of the following systems:

APPENDIX C

Run Log

Subject Vehicle: **2020 Ford F-150 4X4 SuperCrew**

Test Date: **5/19/2020**

Principal Other Vehicle: **SSV**

Run	Test Type	Valid Run?	FCW TTC (s)	Minimum Distance (ft)	Peak Deceleration (g)	Pass/Fail	Notes
	Brake characterization and determination						See Appendix D
9	Static Run						
10	Stopped POV	Y	1.65	14.56	0.99	Pass	
11		Y	1.62	11.88	0.91	Pass	
12		Y	1.60	13.73	0.92	Pass	
13		Y	1.59	14.43	0.98	Pass	
14		Y	1.67	15.46	1.01	Pass	
15		Y	1.64	14.55	0.99	Pass	
16		Y	1.65	15.13	1.01	Pass	
17	Static Run						
18	Slower POV, 25 vs 10	Y	1.52	7.92	0.89	Pass	
19		Y	1.44	7.37	0.86	Pass	
20		Y	1.50	7.47	0.90	Pass	
21		Y	1.50	8.03	0.88	Pass	
22		Y	1.57	7.92	0.89	Pass	
23		Y	1.58	8.43	0.90	Pass	
24		Y	1.53	8.20	0.91	Pass	

Run	Test Type	Valid Run?	FCW TTC (s)	Minimum Distance (ft)	Peak Deceleration (g)	Pass/Fail	Notes
25	Static run						
26	Slower POV, 45 vs 20	Y	2.12	6.27	0.98	Pass	
27		N					SV lateral offset
28		Y	2.07	10.72	0.97	Pass	
29		N					SV speed & Throttle
30		Y	2.20	11.71	1.01	Pass	
31		Y	2.14	9.21	0.98	Pass	
32		Y	2.16	10.68	0.98	Pass	
33		N					POV speed
34		N					SV speed & Throttle
35		Y	2.22	11.35	0.98	Pass	
36		Y	2.07	10.70	0.98	Pass	
37	Static run						
38	Decelerating POV, 35	N					Throttle
39		N					Throttle
40		Y	1.46	4.41	1.01	Pass	
41		Y	1.36	3.55	0.98	Pass	
42		Y	1.50	8.28	0.73	Pass	
43		Y	1.48	3.92	0.80	Pass	

Run	Test Type	Valid Run?	FCW TTC (s)	Minimum Distance (ft)	Peak Deceleration (g)	Pass/Fail	Notes
44		Y	1.38	1.99	0.53	Pass	
45		Y	1.51	2.18	0.56	Pass	
46		N					POV brakes
47		Y	1.43	4.20	0.74	Pass	
48	Static run						
49	STP - Static run						
50	Baseline, 25	N					Brake force
51		Y			0.46		
52		Y			0.47		
53		Y			0.50		
54		Y			0.52		
55		N					SV speed, brake force
56		Y			0.53		
57		Y			0.50		
58		Y			0.51		
59	STP - Static run						
60	Baseline, 45	N					SV speed
61		Y			0.47		
62		N					SV speed
63		Y			0.45		

Run	Test Type	Valid Run?	FCW TTC (s)	Minimum Distance (ft)	Peak Deceleration (g)	Pass/Fail	Notes
64		N					Brake force
65		Y			0.49		
66		Y			0.50		
67		Y			0.50		
68		Y			0.53		
69		N					Corrupted file
70		N					Corrupted file
71		Y			0.48		
72	STP - Static run						
73	STP False Positive, 25	Y			0.48	Pass	
74		Y			0.45	Pass	
75		Y			0.50	Pass	
76		Y			0.48	Pass	
77		Y			0.46	Pass	
78		Y			0.46	Pass	
79		Y			0.46	Pass	
80	STP - Static run						
81	STP False Positive, 45	Y			0.45	Pass	
82		Y			0.46	Pass	

Run	Test Type	Valid Run?	FCW TTC (s)	Minimum Distance (ft)	Peak Deceleration (g)	Pass/Fail	Notes
83		Y			0.47	Pass	
84		N					Throttle
85		Y			0.46	Pass	
86		Y			0.45	Pass	
87		Y			0.43	Pass	
88		Y			0.46	Pass	
89	STP - Static run						

APPENDIX D

Brake Characterization

Subject Vehicle: **2020 Ford F-150 4X4 SuperCrew**

Test Date: **5/19/2020**

DBS Initial Brake Characterization				
Run Number	Stroke at 0.4 g (in)	Force at 0.4 g (lb)	Slope	Intercept
1	1.83619	18.58887	0.879376	0.865713
2	1.821642	17.87172	0.849126	0.438927
3	1.89038	18.51374	0.921	0.30235

DBS Brake Characterization Determination								
Run	DBS Mode	Speed	Valid Run	Average Decel. (g)	0.4 g Stroke Value (in)	0.4 g Force Value (lb)	Stroke/Force Calculator (in)	Notes
4	Displacement	35	N					Application rate
5			N					Application rate
6			Y	0.388	1.95		2.01	
7		25	Y	0.386	1.95		2.02	
8		45	Y	0.395	1.95		1.97	

Appendix E

TIME HISTORY PLOTS

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Description of Time History Plots

A set of time history plots is provided for each valid run in the test series. Each set of plots comprises time varying data from both the Subject Vehicle (SV) and the Principal Other Vehicle (POV), as well as pass/fail envelopes and thresholds. Plots shown herein are grouped by test type and are presented sequentially within a given test type. The following is a description of data types shown in the time history plots, as well as a description of the color code indicating to which vehicle the data pertain.

Time History Plot Description

Each time history plot consists of data relevant to the test type under consideration, and therefore the data channels plotted vary according to test type. The test types (shown in the plot titles) include:

- Stopped POV (SV at 25 mph)
- Slower POV, 25/10 (SV at 25 mph, POV at 10 mph)
- Slower POV, 45/20 (SV at 45 mph, POV at 20 mph)
- Decelerating POV 35 mph (Both vehicles at 35 mph with 13.8 m gap, POV brakes at 0.3 g)
- False Positive Baseline 25 mph (Baseline run at 25 mph)
- False Positive Baseline 45 mph (Baseline run at 45 mph)
- False Positive STP 25 mph (Steel trench plate run over at 25 mph)
- False Positive STP 45 mph (Steel trench plate run over at 45 mph)
- DBS Brake Characterization, Initial
- DBS Brake Characterization Determination

Time history figures include the following sub-plots:

- FCW Warning – Displays the Forward Collision Warning alert (which can be audible, visual, or haptic). Depending on the type of FCW alert or instrumentation used to measure the alert, this can be any combination of the following:
 - Filtered, rectified, and normalized sound signal. The vertical scale is 0 to 1.
 - Filtered, rectified, and normalized acceleration (i.e., haptic alert, such as steering wheel vibration). The vertical scale is 0 to 1.
 - Normalized light sensor signal. The vertical scale is 0 to 1.

As only the audible or haptic alert is perceptible by the driver during a test run, the earliest of either of these alerts is used to define the onset of the FCW alert. A vertical black bar on the plot indicates the TTC (sec) at the first moment of the warning issued by the FCW system. The FCW TTC is displayed to the right of the subplot in green.

- Headway (ft) – Longitudinal separation between the frontmost point of the Subject Vehicle and the rearmost point of the Strikeable Surrogate Vehicle (SSV) towed by the Principal Other Vehicle. The minimum headway during the run is displayed to the right of the subplot.
- SV/POV Speed (mph) – Speed of the Subject Vehicle and the Principal Other Vehicle (if any). For DBS tests, in the case of an impact, the speed reduction experienced by the Subject Vehicle up until the moment of impact is displayed to the right of the subplot.
- Yaw Rate (deg/sec) – Yaw rate of the Subject Vehicle and Principal Other Vehicle (if any).
- Lateral Offset (ft) – Lateral offset within the lane of the Subject Vehicle to the center of the lane of travel. Note that for tests involving the Strikeable Surrogate Vehicle (SSV), the associated lateral restraint track is defined to be the center of the lane of travel. If testing is done with a different POV which does not have a lateral restraint track, lateral offset is defined to be the lateral offset between the SV and POV.
- Ax (g) – Longitudinal acceleration of the Subject Vehicle and Principal Other Vehicle (if any). The peak value of Ax for the SV is shown on the subplot.
- Pedal Position – Position of the accelerator pedal and brake pedal. The units for the brake pedal are inches and the units for the accelerator pedal are percent of full scale divided by 10.
- Brake Force (lb) – Force on the brake pedal as applied by the DBS controller. The TTC at the onset of the brake by the DBS controller is shown on the subplot. Additionally, the average force at the brake pedal while the DBS controller is active is displayed.

Note that the minimum (worst) GPS fix type is displayed in the lower right corner of each page. The only valid fix type is RTK fixed (displayed in green). If the fix type during any portion of the test was anything other than RTK fixed, then “RTK Fixed OR LESS!!” is displayed in red.

Envelopes and Thresholds

Some of the time history plot figures contain either green or yellow envelopes and/or black or red threshold lines. These envelopes and thresholds are used to programmatically and visually determine the validity of a given test run. Envelope and threshold exceedances are indicated with either red shading or red asterisks, and red text is placed to the right side of the plot indicating the type of exceedance. Such exceedances indicate either that the test was invalid or that the requirements of the test were not met (i.e., failure of the AEB system).

For plots with green envelopes, in order for the test to be valid, the time-varying data must not exceed the envelope boundaries at any time within the envelope. Exceedances of a green envelope are indicated by red shading in the area between the measured time-varying data and the envelope boundaries.

With the exception of the brake force plots (see description below), for plots with yellow envelopes, in order for the test to be valid, the time-varying data must not exceed the envelope at the beginning (left edge of the boundary) and/or end (right edge), but may exceed the boundary during the time between the left and right edges. Exceedances at the left or right extent of a yellow envelope are indicated by red asterisks.

For the headway plot, a dashed black threshold line indicating a relative headway of zero is given. If no impact occurs, a green circle is displayed at the moment of minimum distance. If impact occurs, a red asterisk is displayed at the moment of impact.

For the Ax plot, if the scenario is an AEB brake to stop scenario, a vertical dashed black line is displayed for all plots indicating the moment of first POV braking. The yellow envelope in this case is relevant to the POV braking only. The left edge of the envelope is at 1.5 seconds after the first POV braking. A solid black threshold line extends horizontally 0.5 seconds to the left of the envelope. This threshold line represents the time during which the Ax of the Principal Other Vehicle must first achieve 0.27g (the upper edge of the envelope, i.e., $0.30\text{ g} \pm 0.03\text{ g}$). A green circle or red asterisk is displayed at the moment the POV brake level achieves 0.27g. A green circle indicates that the test was valid (the threshold was crossed during the appropriate interval) and a red asterisk indicates that the test was invalid (the threshold was crossed out of the appropriate interval).

For the pedal position plot, a thick black bar appears on the brake pedal position data over the DBS controller brake onset period to signify the time over which the brake application rate is determined. The calculated brake application rate is also displayed on the figure.

For the brake force plots:

- If the tests are done in Hybrid mode, the brake force plot shows a dashed black threshold line indicating a brake force of 2.5 lbs. For the time period where the DBS controller is active, the brake force at the pedal must not fall below this 2.5 lb threshold. Exceedances of this threshold are indicated by red shading in the area between the measured time-varying data and the dashed threshold line. A blue envelope represents the target average brake force necessary to be valid
- If the tests are done in displacement mode, there are no relevant brake force level thresholds or average brake force calculations.

In the instance of the “last second” braking applied by the brake robot, a thick vertical red line will appear on the plots at the moment the brake robot activates. Note that last second braking is only done when it has been determined by the onboard computer that test failure cannot be avoided. It is done simply to reduce the collision speed in order to minimize the likelihood of damage to the SSV and to the Subject Vehicle. Therefore, data validity checks are not performed after the red line, and certain values, such as minimum distance or peak deceleration, may not be accurate.

Color Codes

Color codes have been adopted to easily identify which data correspond to which vehicle, as well as to indicate the types of envelopes and thresholds used in the plots.

Color codes can be broken into four categories:

1. Time-varying data
2. Validation envelopes and thresholds
3. Individual data points
4. Text

1. Time-varying data color codes:

- Blue = Subject Vehicle data
- Magenta = Principal Other Vehicle data
- Brown = Relative data between SV and POV (i.e., TTC, lateral offset and headway distance)

2. Validation envelope and threshold color codes:

- Green envelope = time varying data must be within the envelope at all times in order to be valid
- Yellow envelope = time varying data must be within limits at left and/or right ends
- Blue envelope = visualized target range for the time varying data averaged over a period equal to the length of the envelope
- Black threshold (Solid) = time varying data must cross this threshold in the time period shown in order to be valid
- Black threshold (Dashed) = for reference only – this can include warning level thresholds, TTC thresholds, and acceleration thresholds.
- Red threshold (Solid) = for reference only – indicates the activation of last-minute braking by the brake robot. Data after the solid red line is not used to determine test validity.

3. Individual data point color codes:

- Green circle = passing or valid value at a given moment in time
- Red asterisk = failing or invalid value at a given moment in time

4. Text color codes:

- Green = passing or valid value
- Red = failing or invalid value

Other Notations

- NG – Indicates that the value for that variable was outside of bounds and therefore “No Good”.
- No Wng – No warning was detected.
- POV – Indicates that the value for the Principal Other Vehicle was out of bounds.
- SV – Indicates that the value for the Subject Vehicle was out of bounds.
- SR – Shows the speed reduction value.
- Thr – Indicates that the requirements for the throttle were not met.

The minimum (worst) GPS fix type is displayed in the lower right corner of each page. The only valid fix type is RTK fixed (displayed in green). If the fix type during any portion of the test was anything other than RTK fixed, then “RTK Fixed OR LESS!!” is displayed in red.

Examples of valid or passing time history plots for each test type (including passing, failing, and invalid runs) are shown in Figure E1 through E12. Figures E1 through E8 show passing runs for each of the 8 test types. Figure E9 shows an example of a passing brake characterization run. Figures E10 and E11 show examples of invalid runs. Figure E12 shows an example of a valid test that failed the DBS requirements. Time history data plots for the tests of the vehicle under consideration herein are provided beginning with Figure E13.

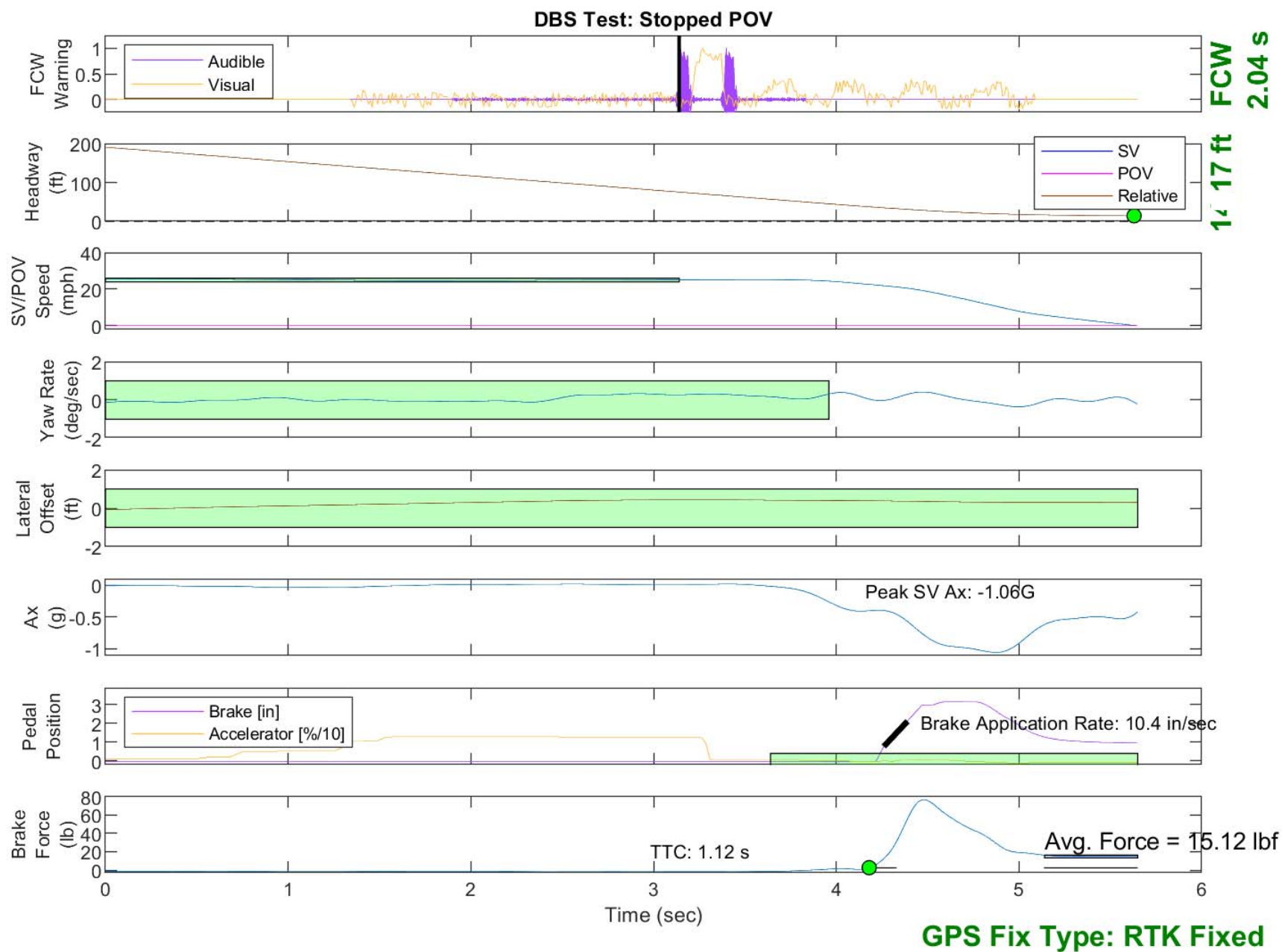


Figure E1. Example Time History for Stopped POV, Passing

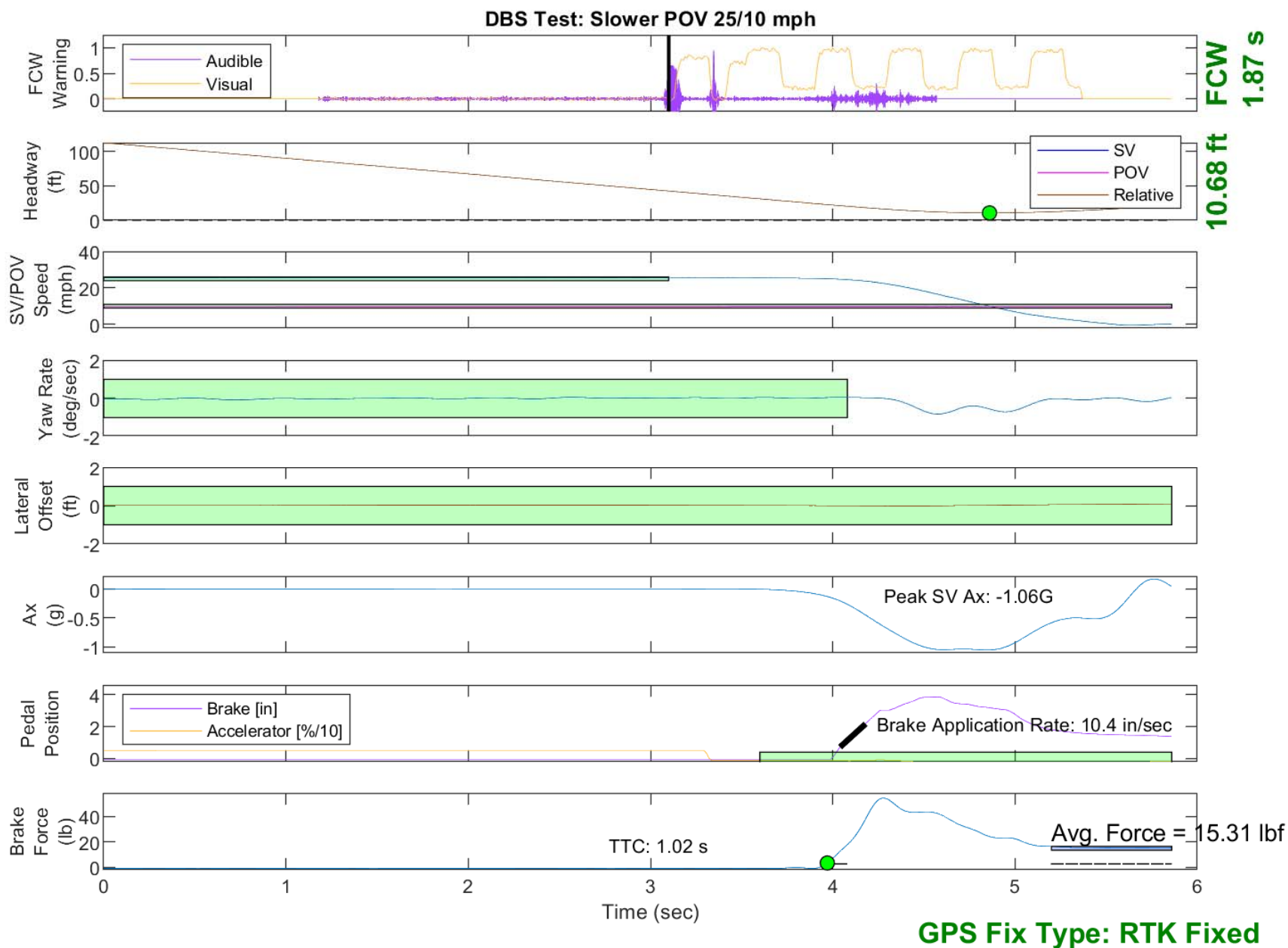


Figure E2. Example Time History for Slower POV 25 vs. 10, Passing

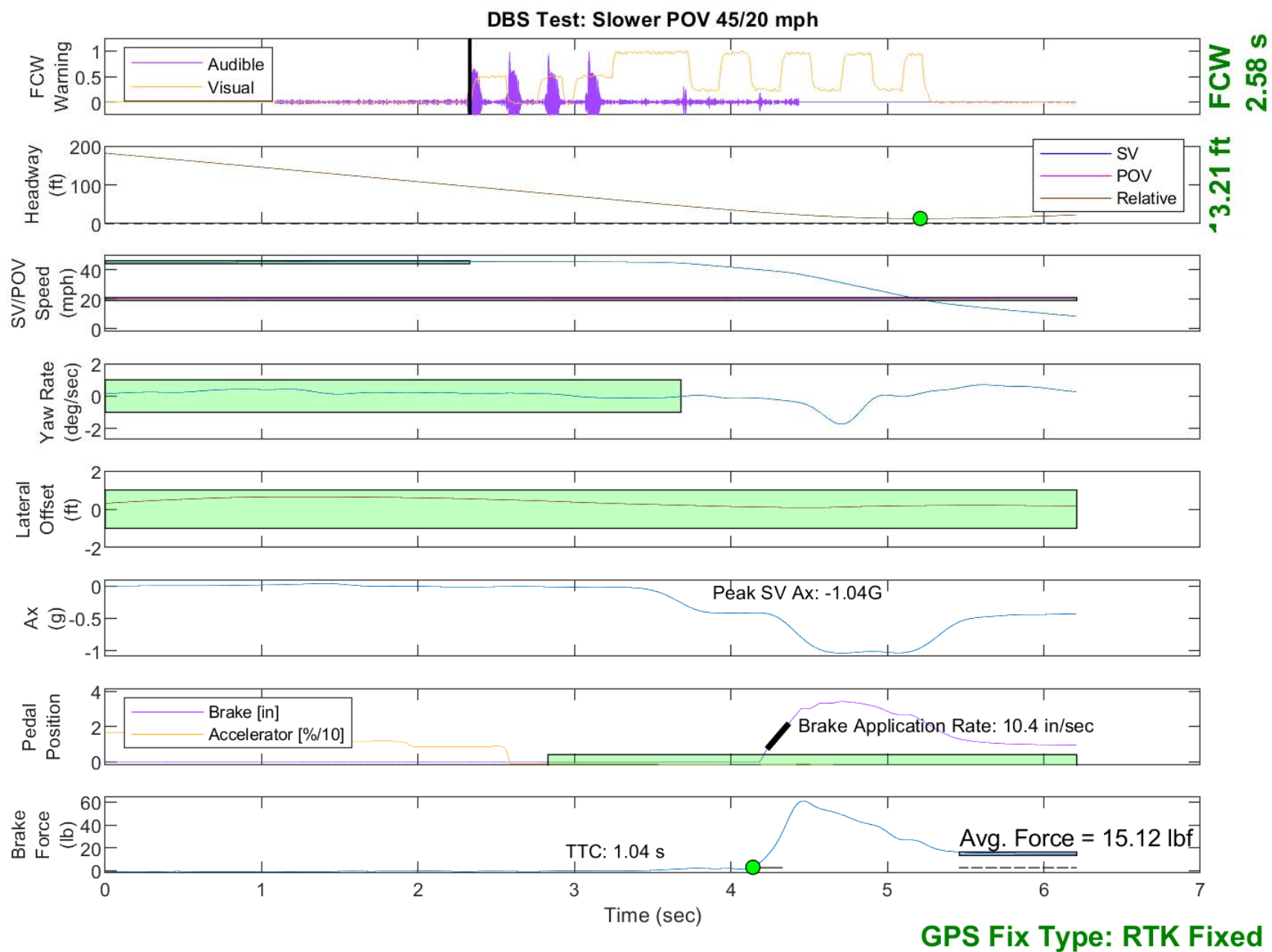


Figure E3. Example Time History for Slower POV 45 vs. 20, Passing

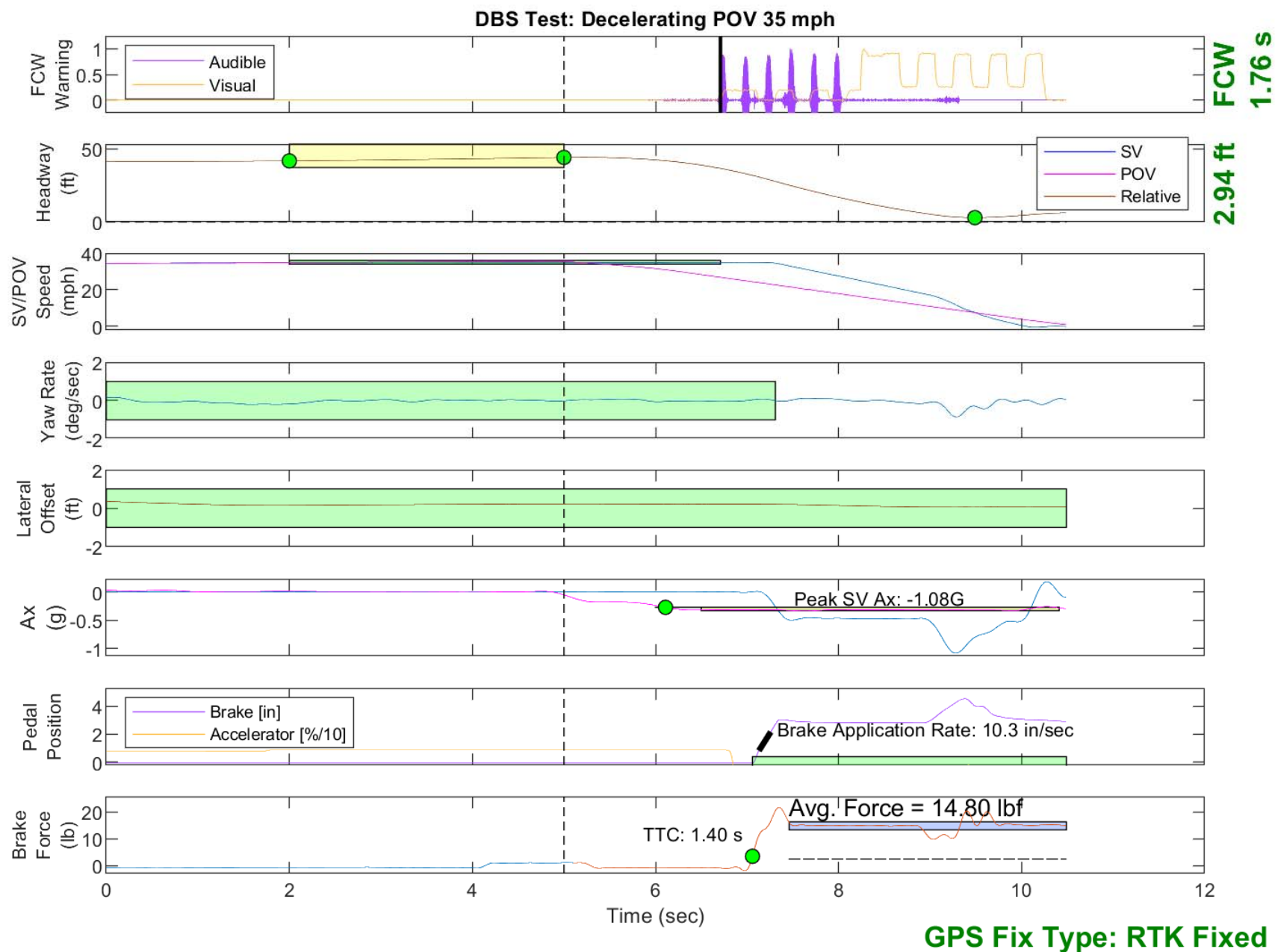


Figure E4. Example Time History for Decelerating POV 35, Passing

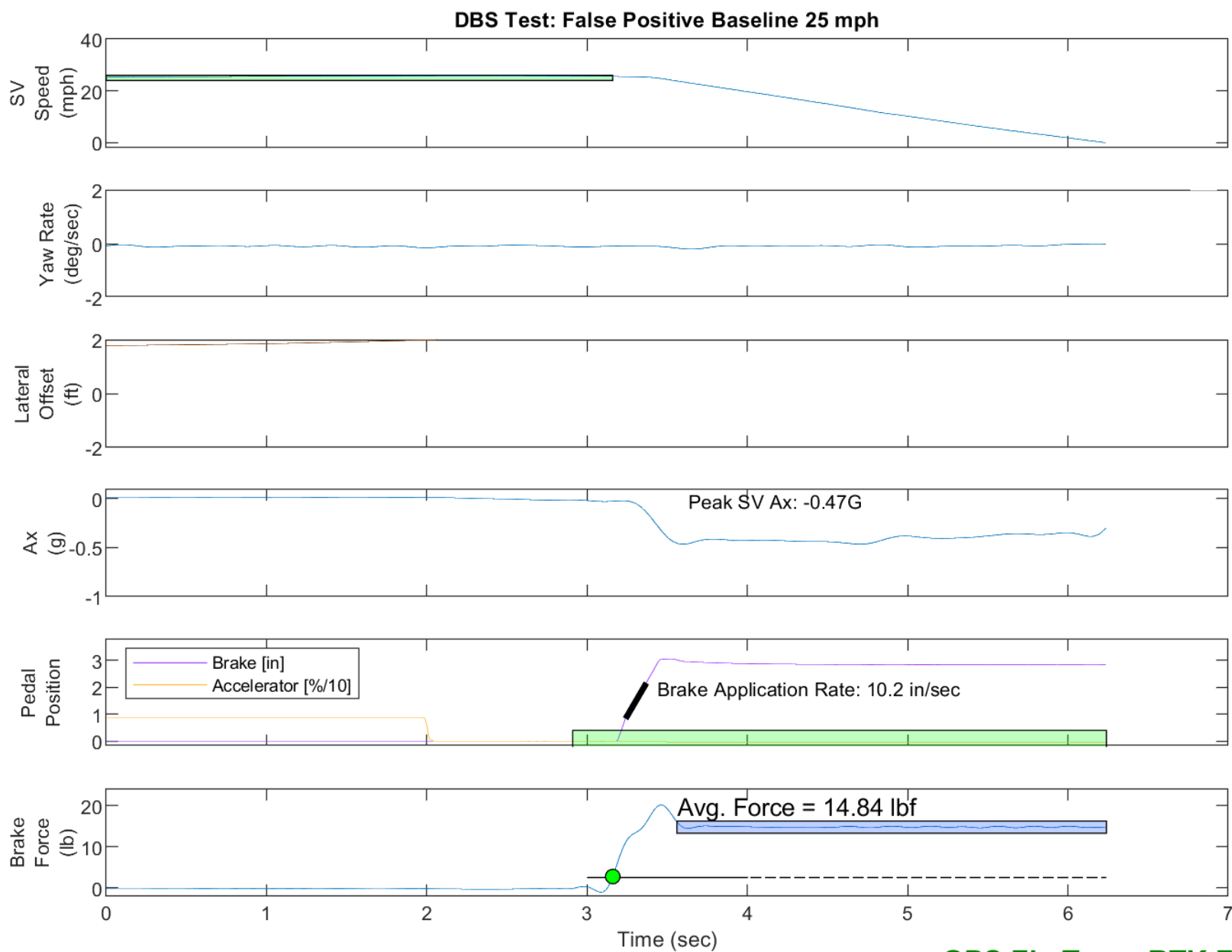


Figure E5. Example Time History for False Positive Baseline 25

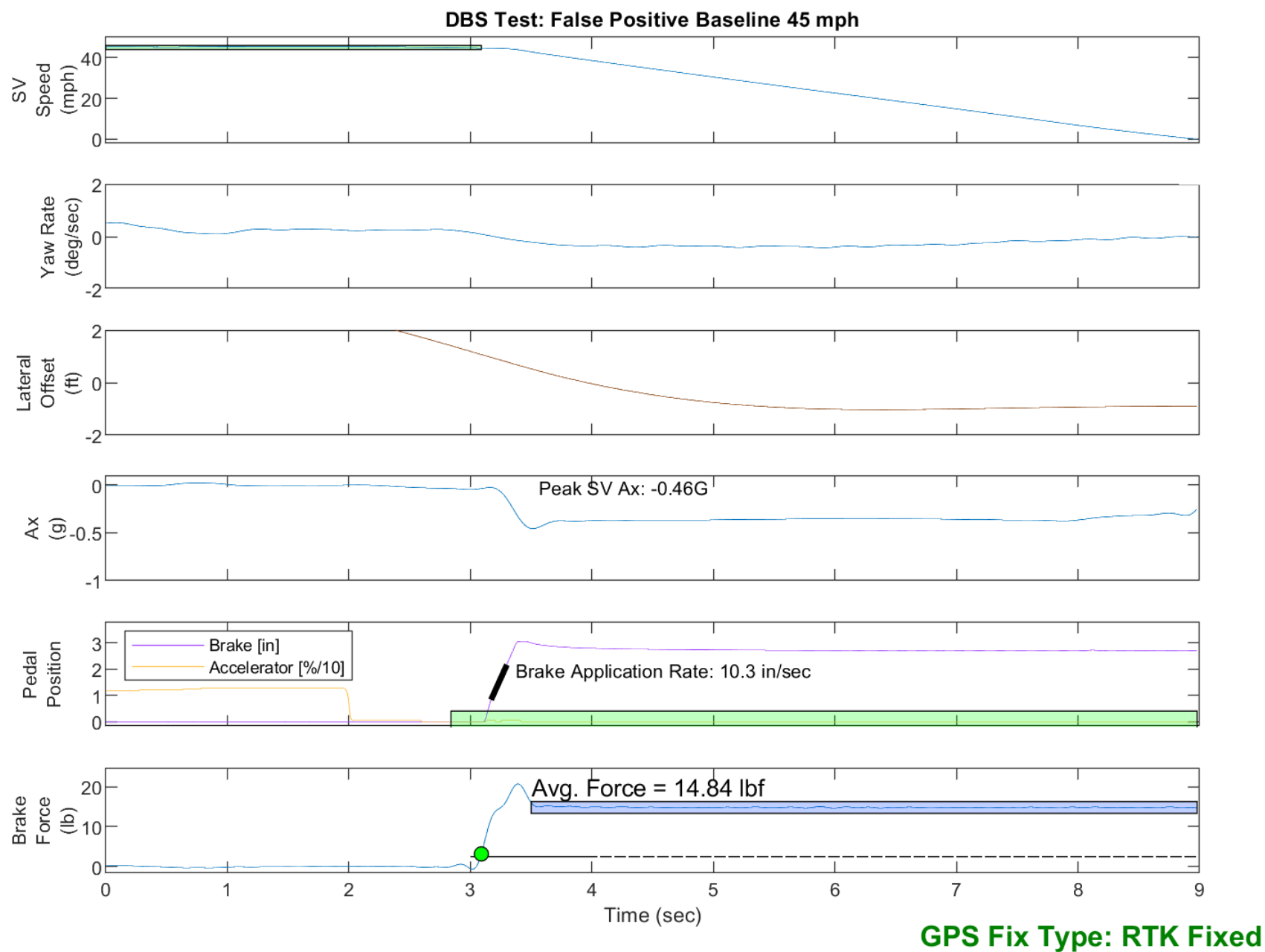


Figure E6. Example Time History for False Positive Baseline 45

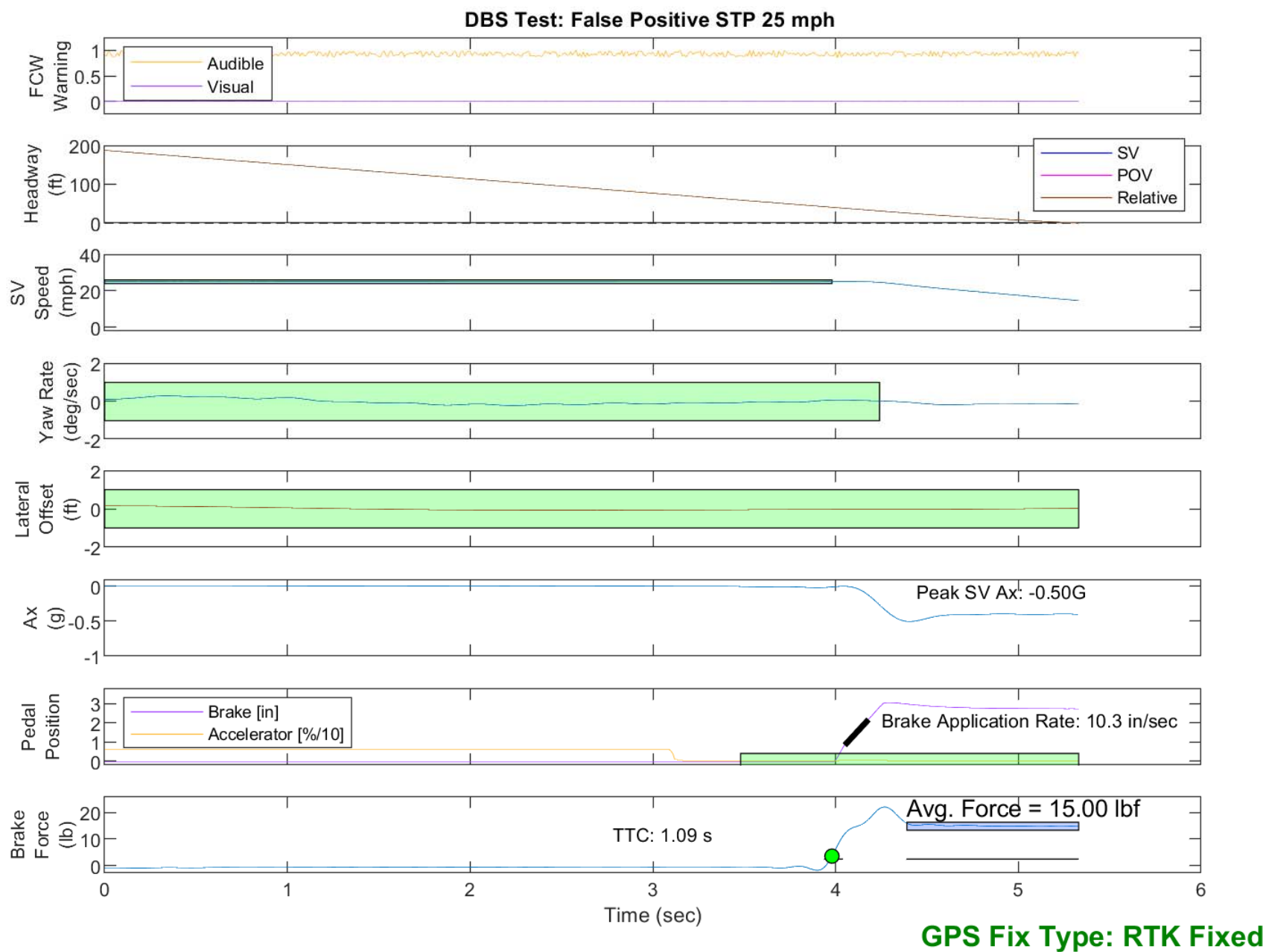


Figure E7. Example Time History for False Positive Steel Plate 25, Passing

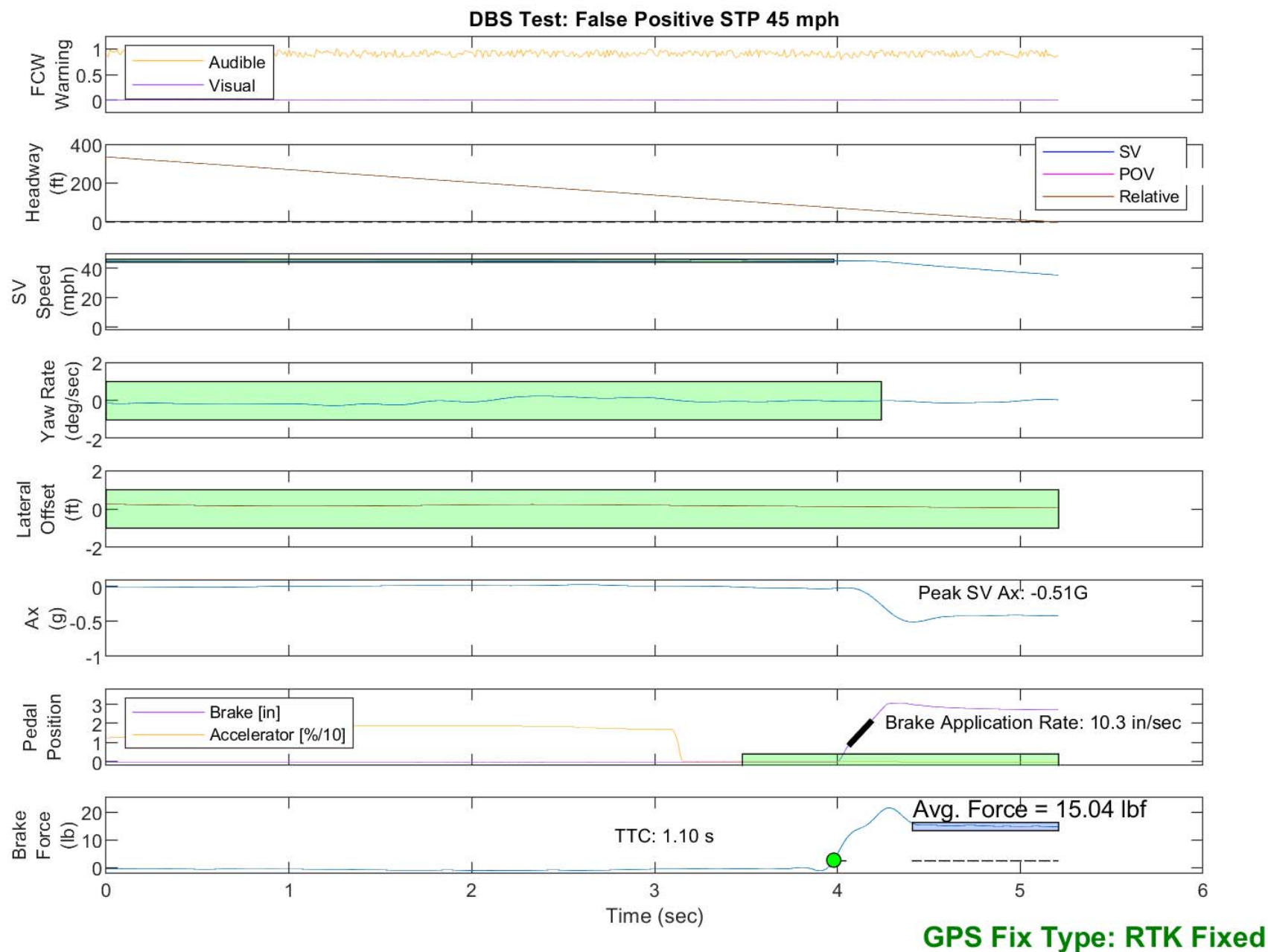


Figure E8. Example Time History for False Positive Steel Plate 45, Passing

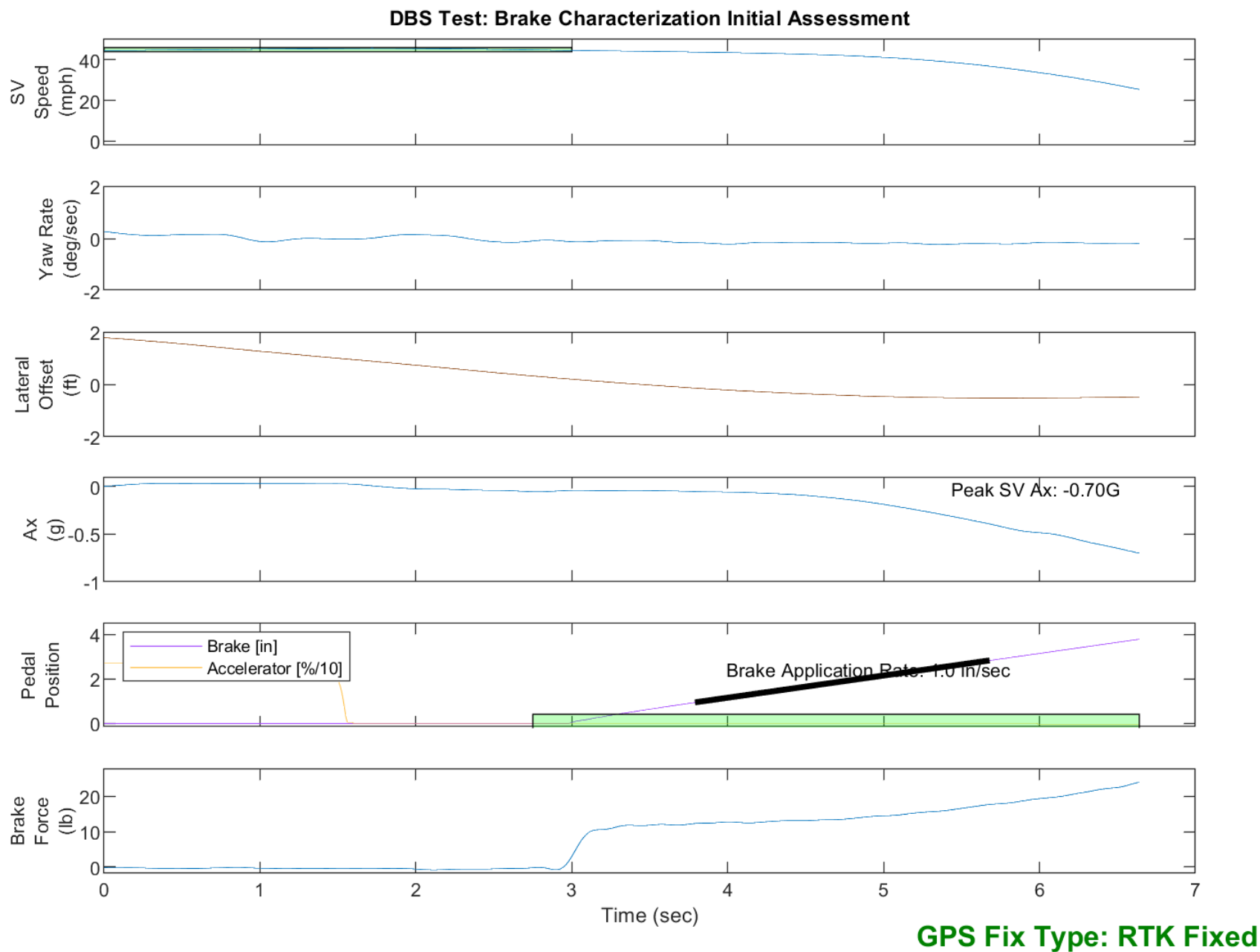


Figure E9. Example Time History for DBS Brake Characterization, Passing

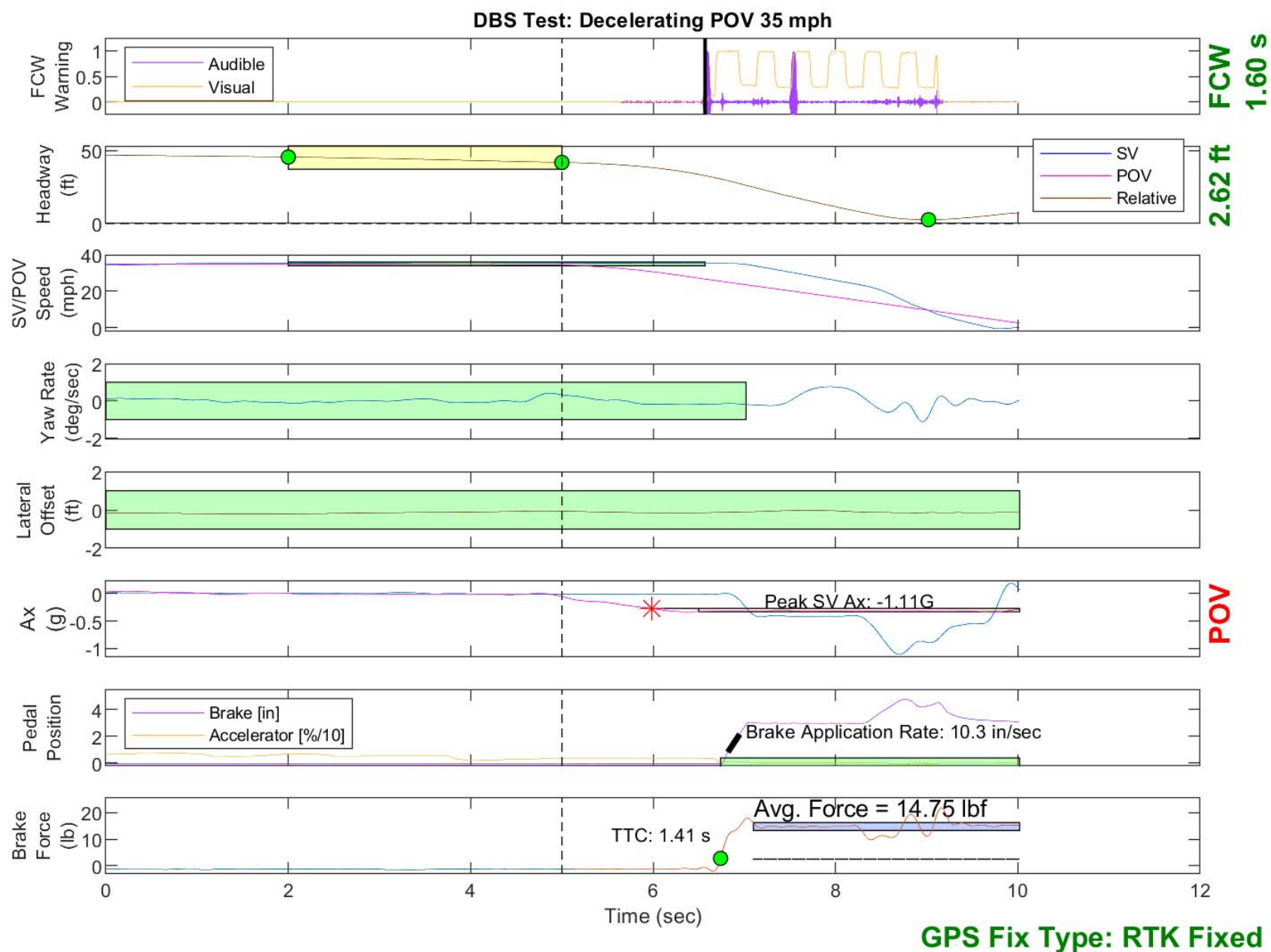


Figure E10. Example Time History Displaying Invalid POV Acceleration Criteria

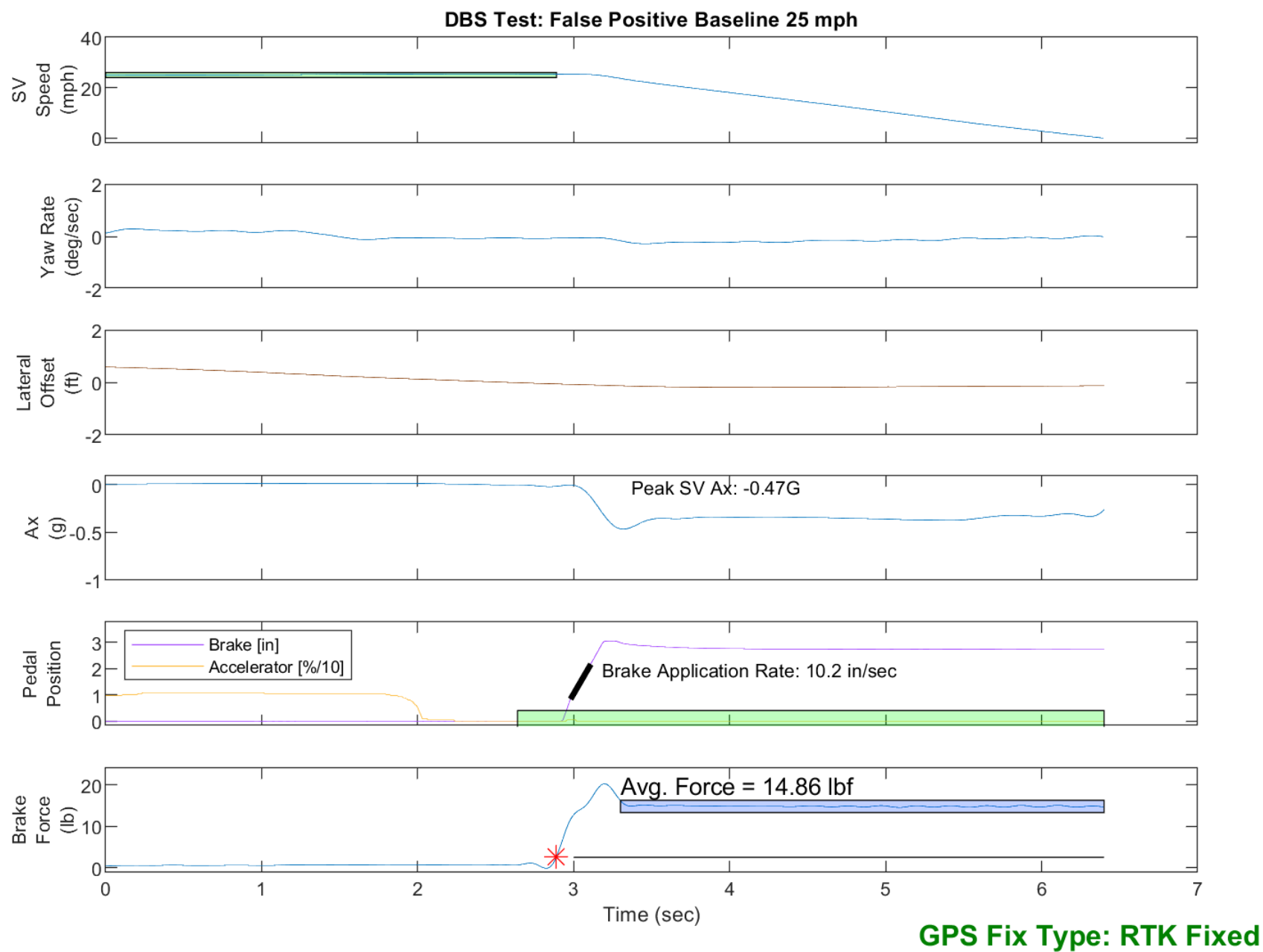


Figure E11. Example Time History Displaying Invalid Brake Force Criteria

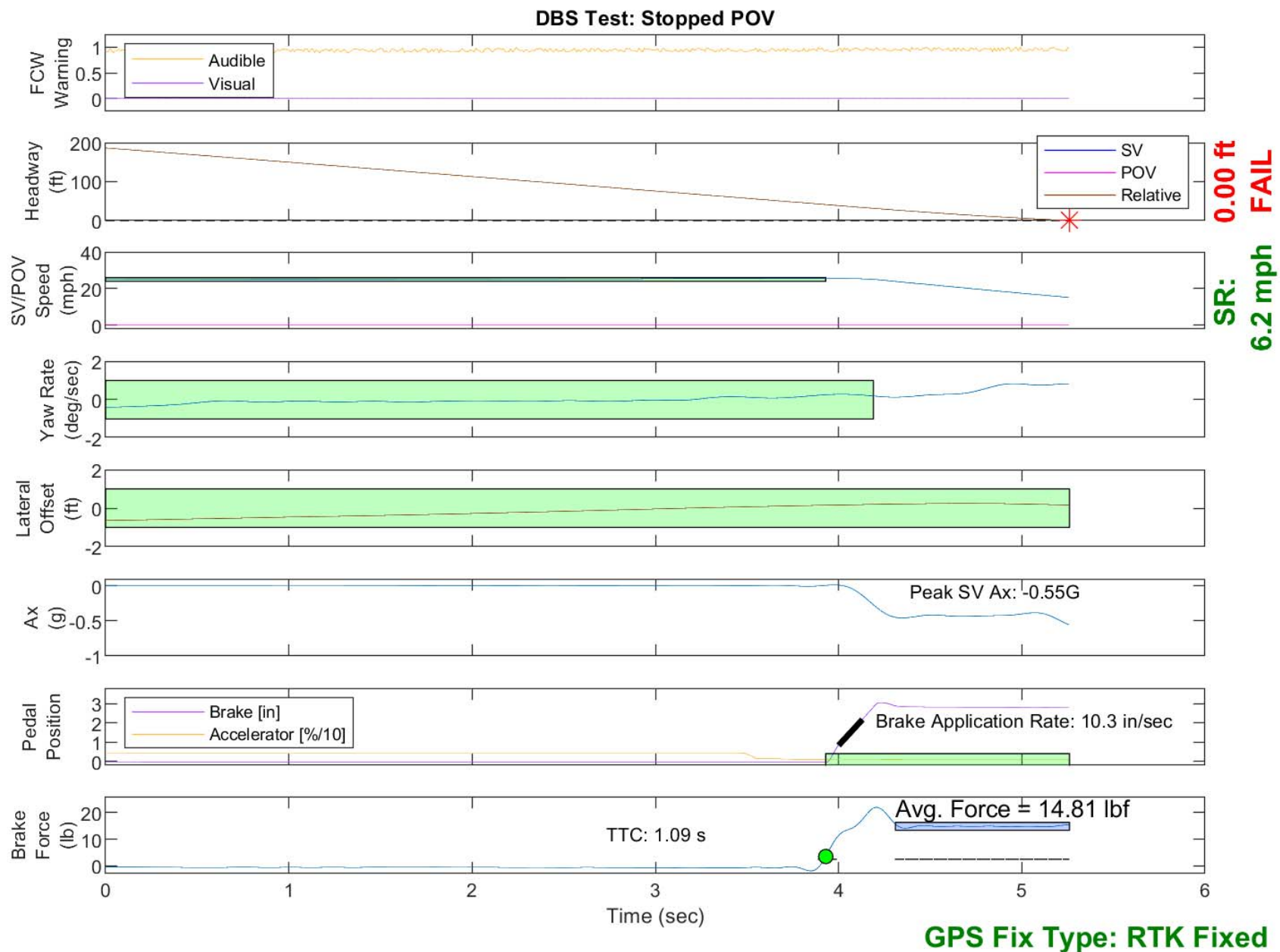


Figure E12. Example Time History for a Failed Run

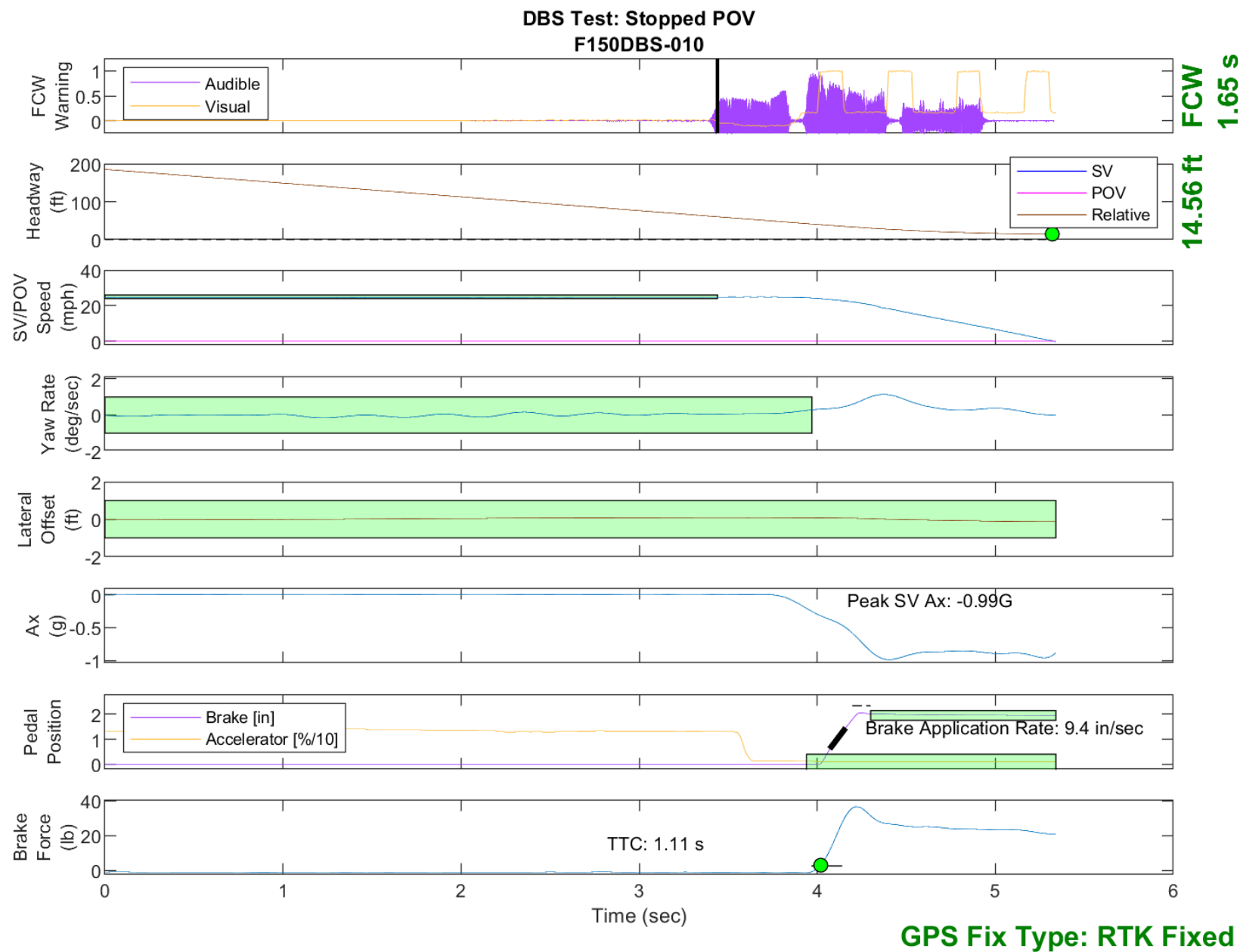


Figure E13. Time History for DBS Run 10, SV Encounters Stopped POV

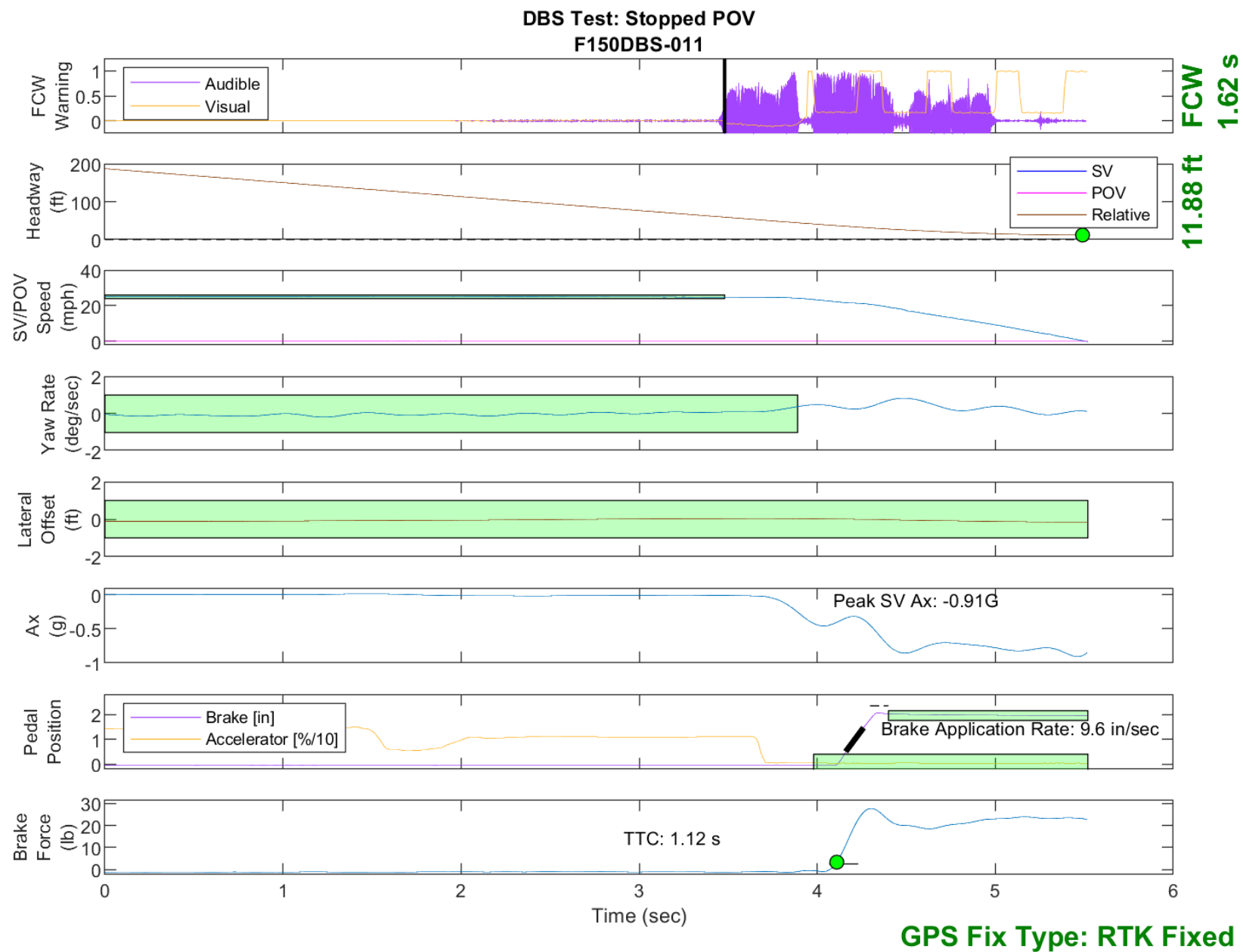


Figure E14. Time History for DBS Run 11, SV Encounters Stopped POV

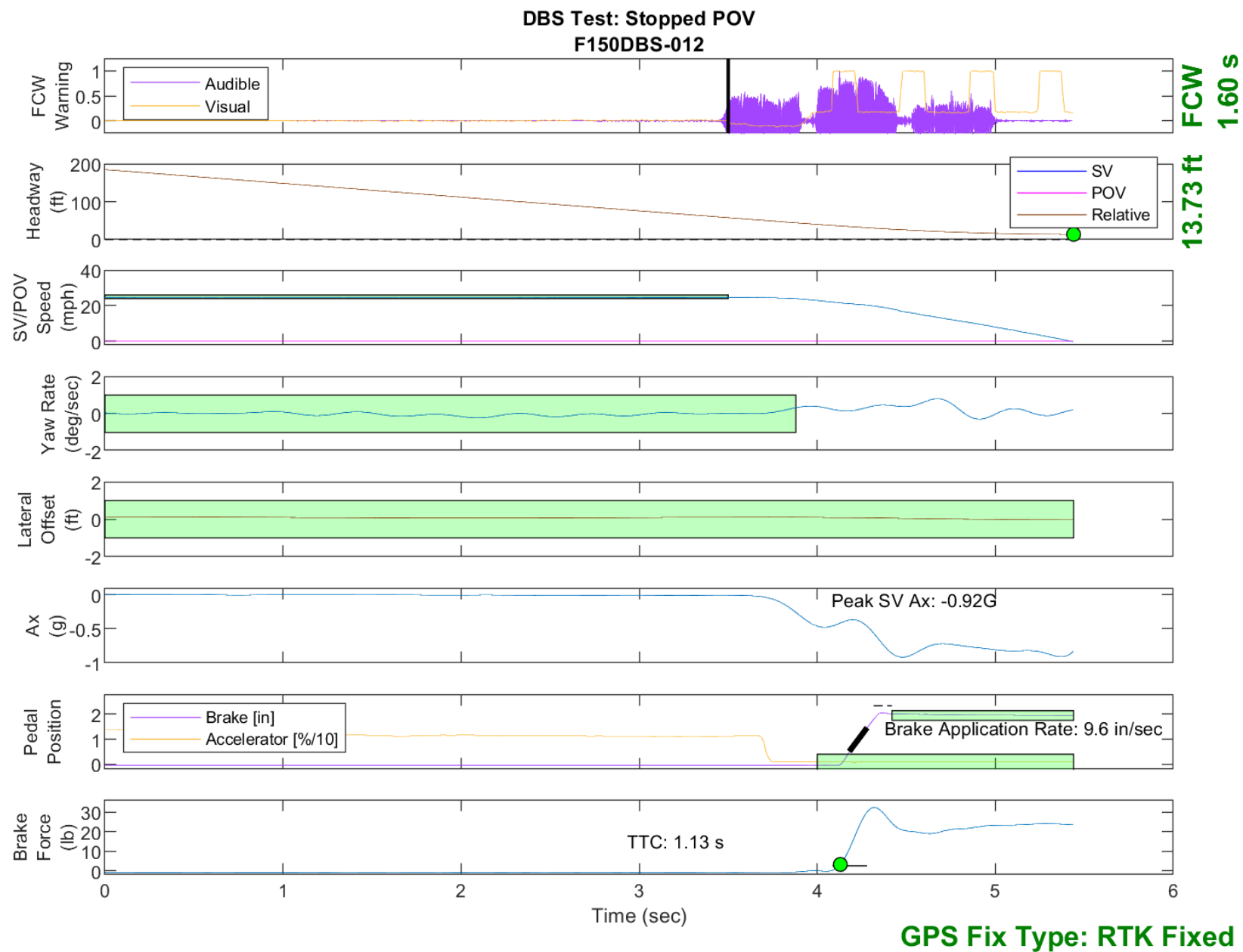


Figure E15. Time History for DBS Run 12, SV Encounters Stopped POV

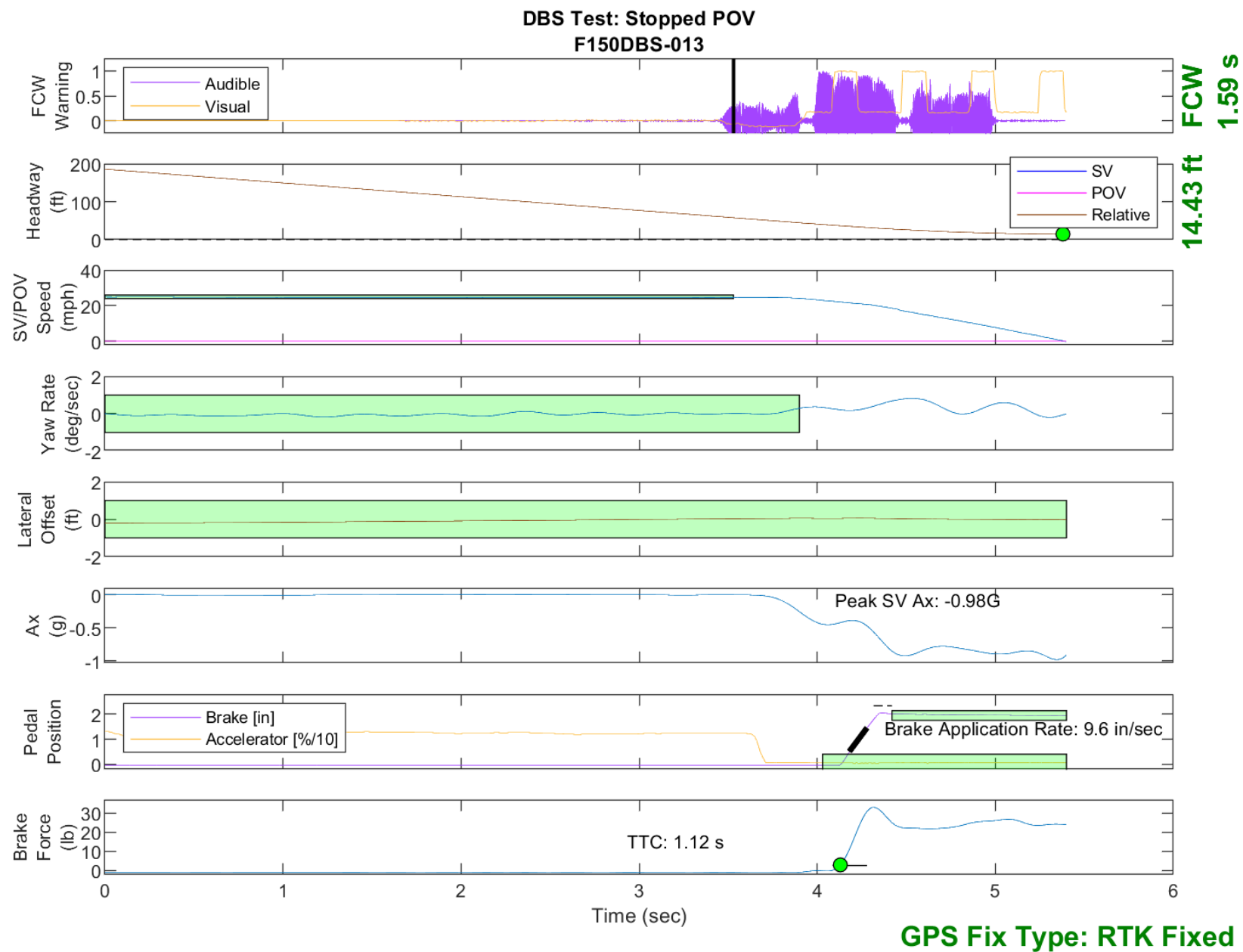


Figure E16. Time History for DBS Run 13, SV Encounters Stopped POV

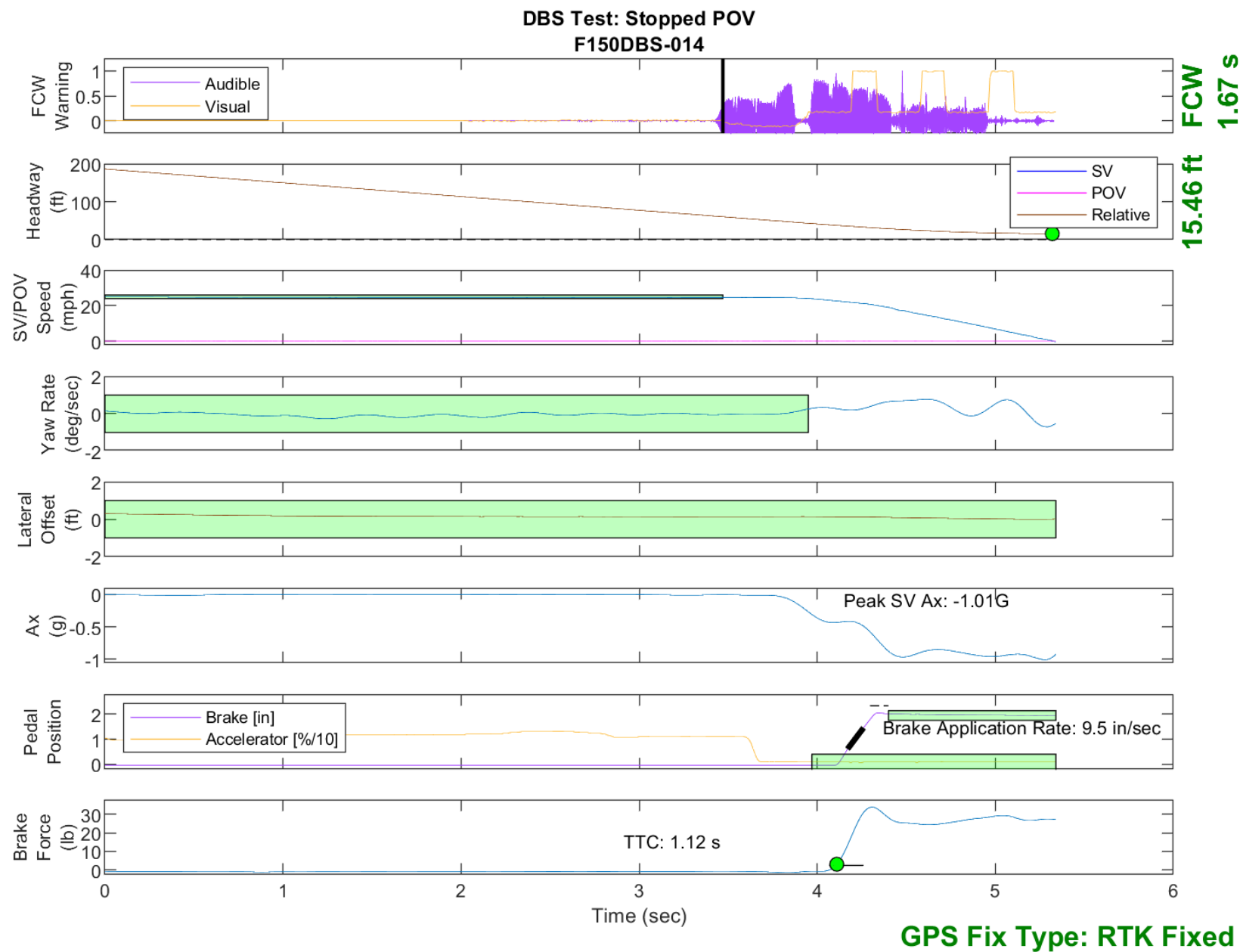


Figure E17. Time History for DBS Run 14, SV Encounters Stopped POV

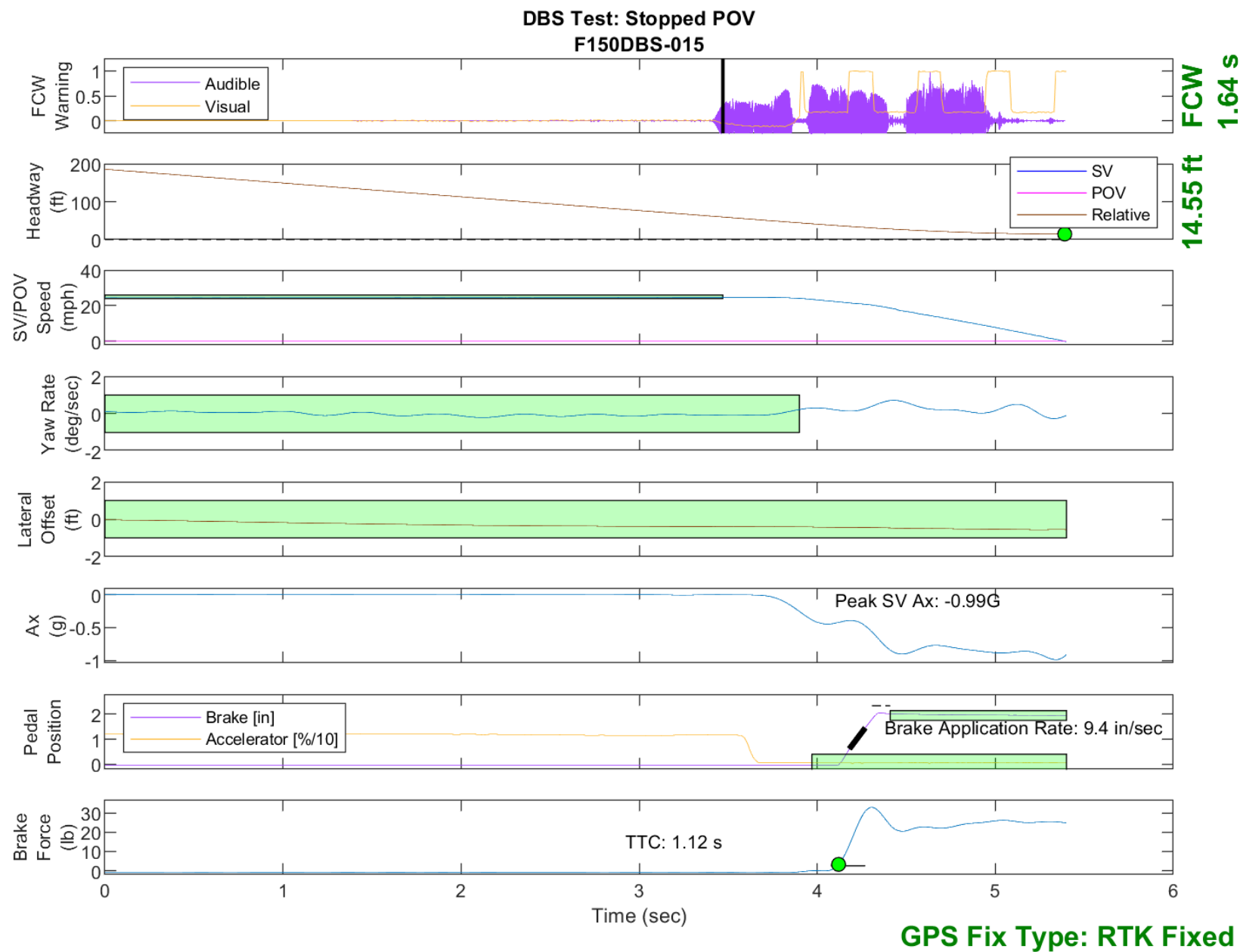


Figure E18. Time History for DBS Run 15, SV Encounters Stopped POV

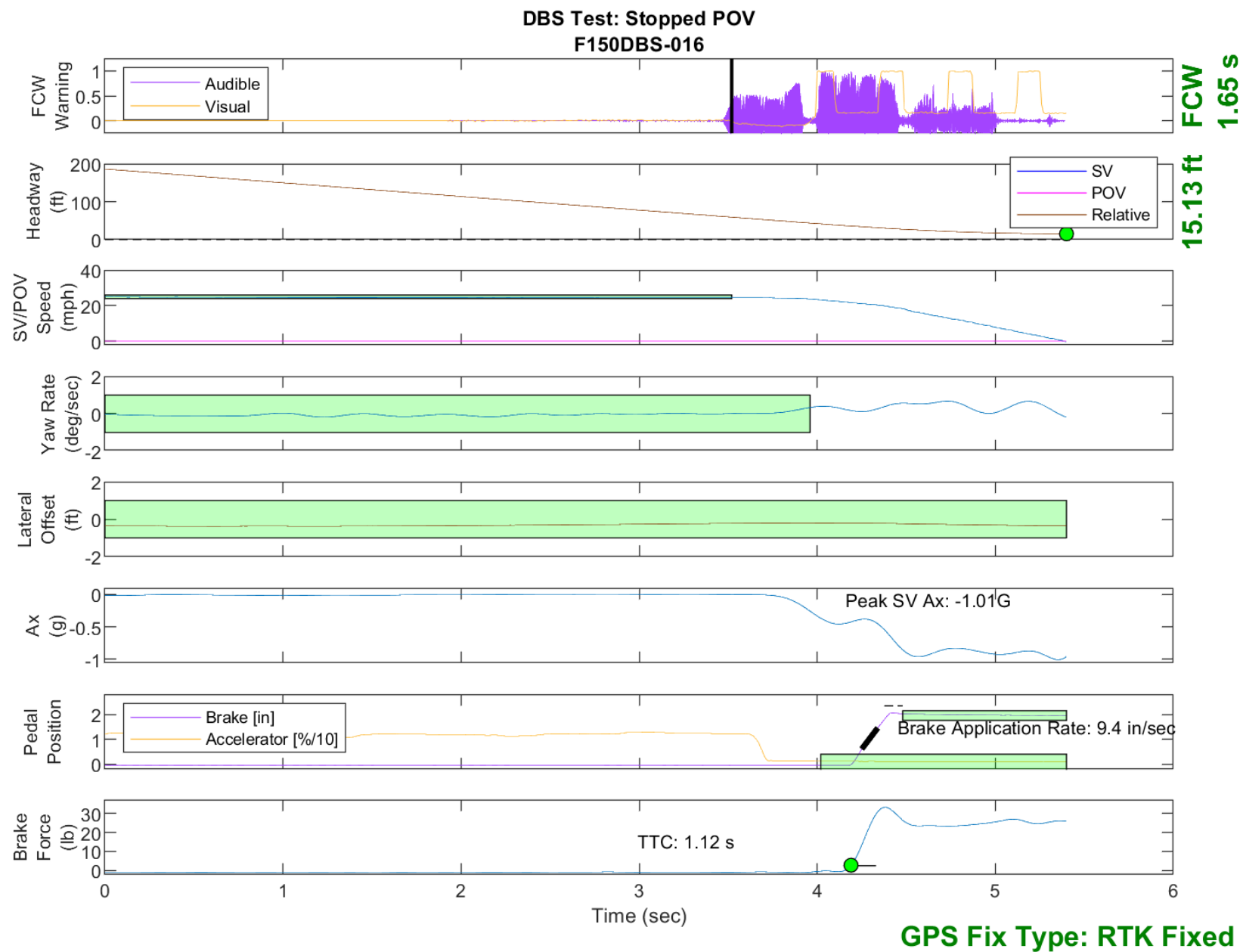


Figure E19. Time History for DBS Run 16, SV Encounters Stopped POV

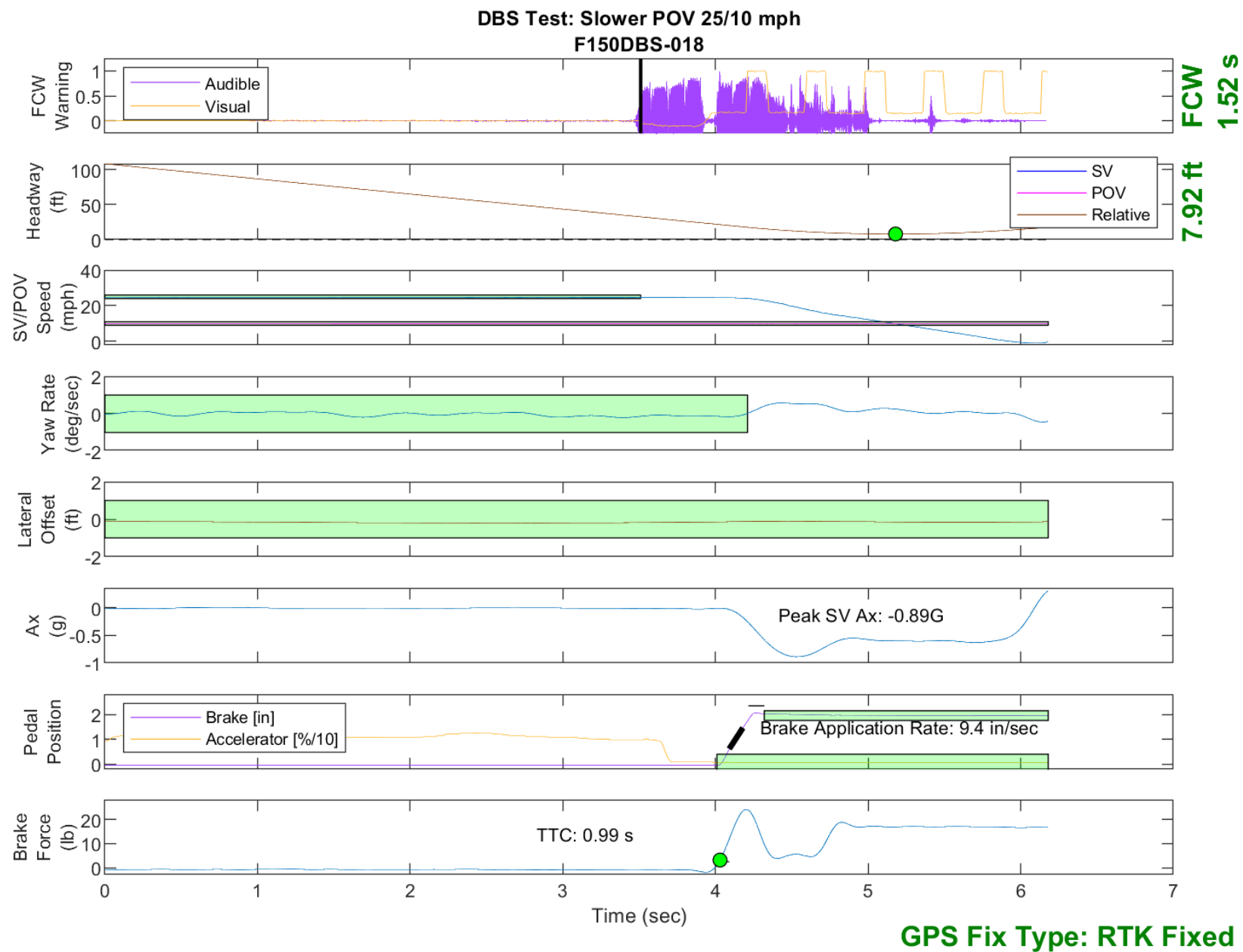


Figure E20. Time History for DBS Run 18, SV Encounters Slower POV, SV 25 mph, POV 10 mph

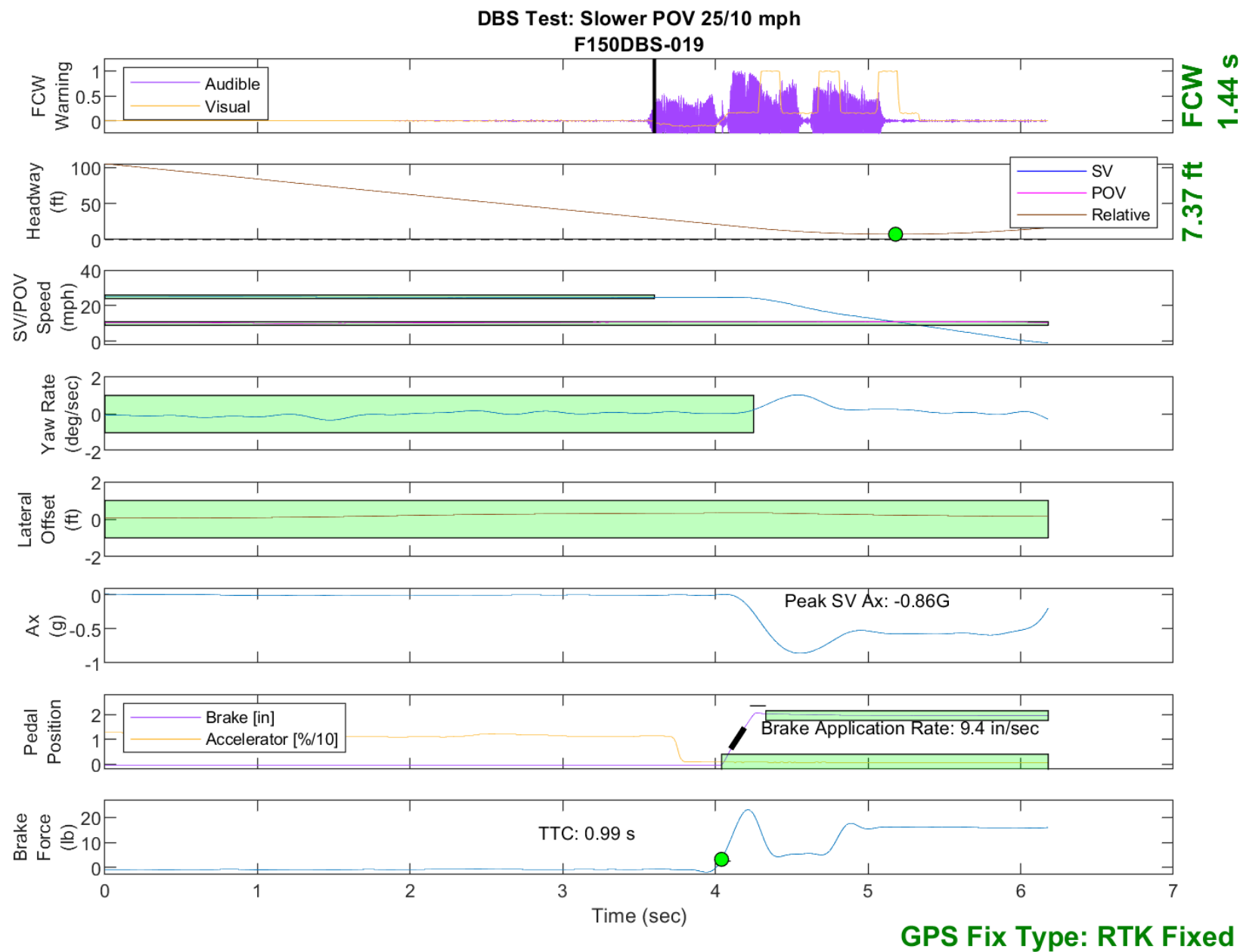


Figure E21. Time History for DBS Run 19, SV Encounters Slower POV, SV 25 mph, POV 10 mph

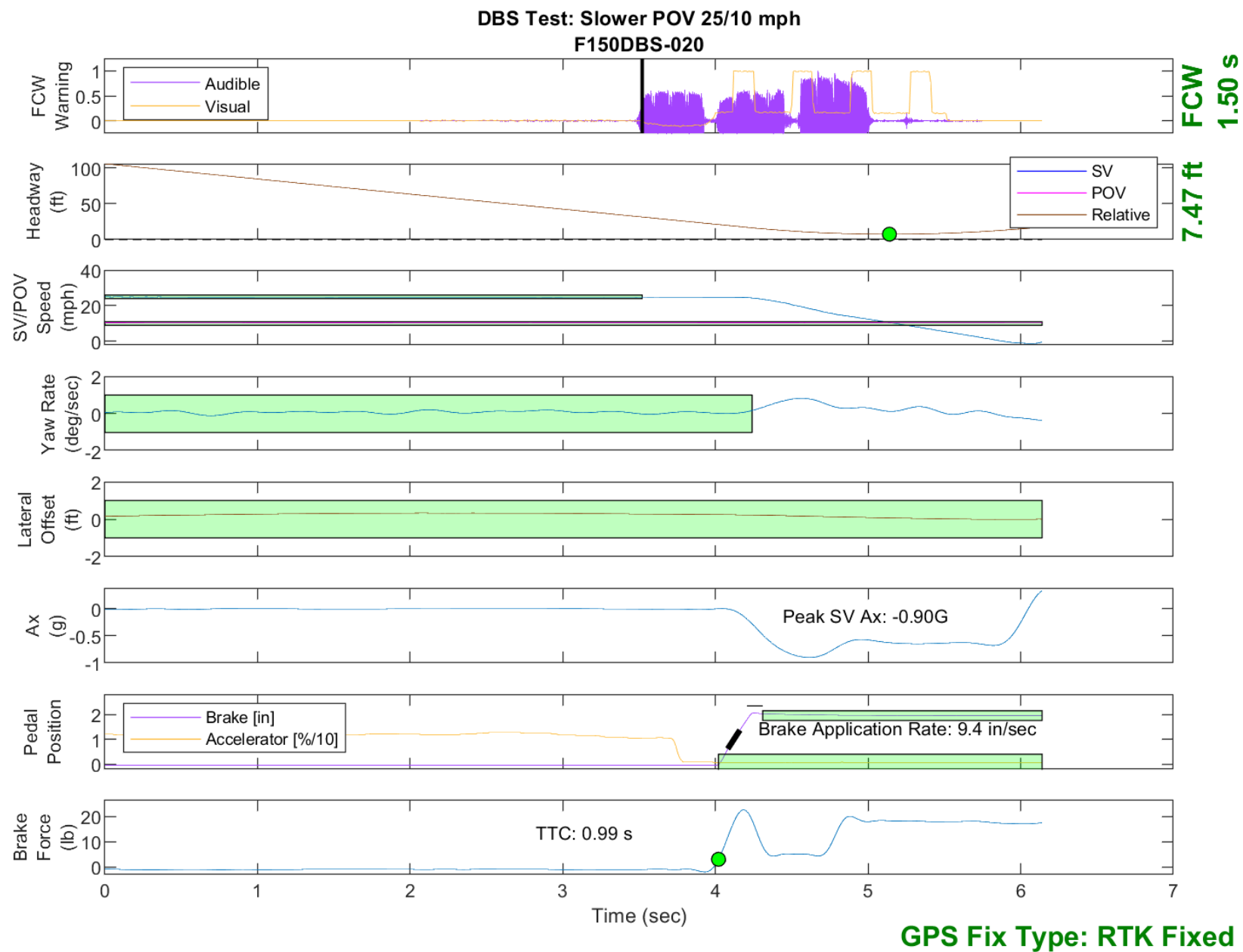


Figure E22. Time History for DBS Run 20, SV Encounters Slower POV, SV 25 mph, POV 10 mph

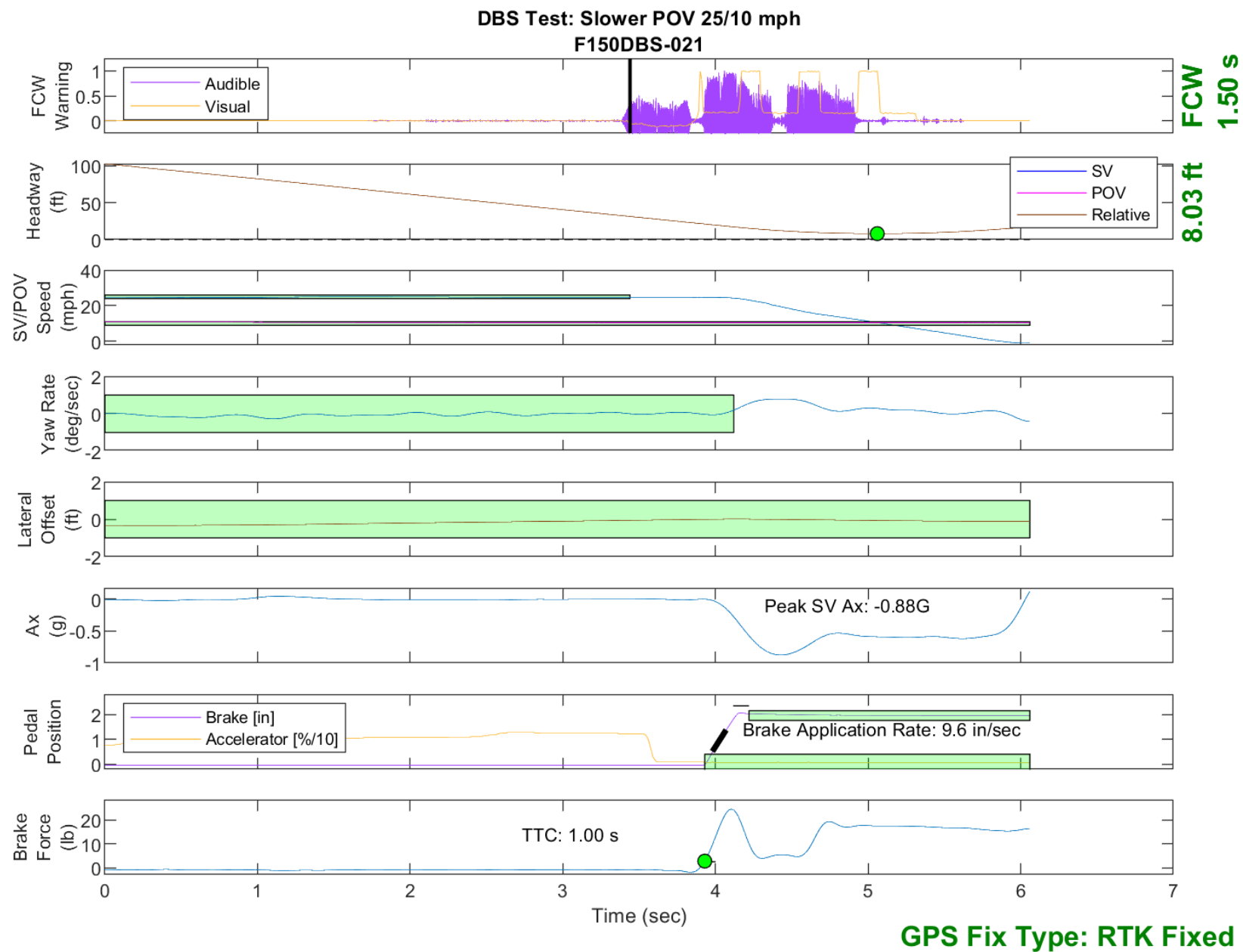


Figure E23. Time History for DBS Run 21, SV Encounters Slower POV, SV 25 mph, POV 10 mph

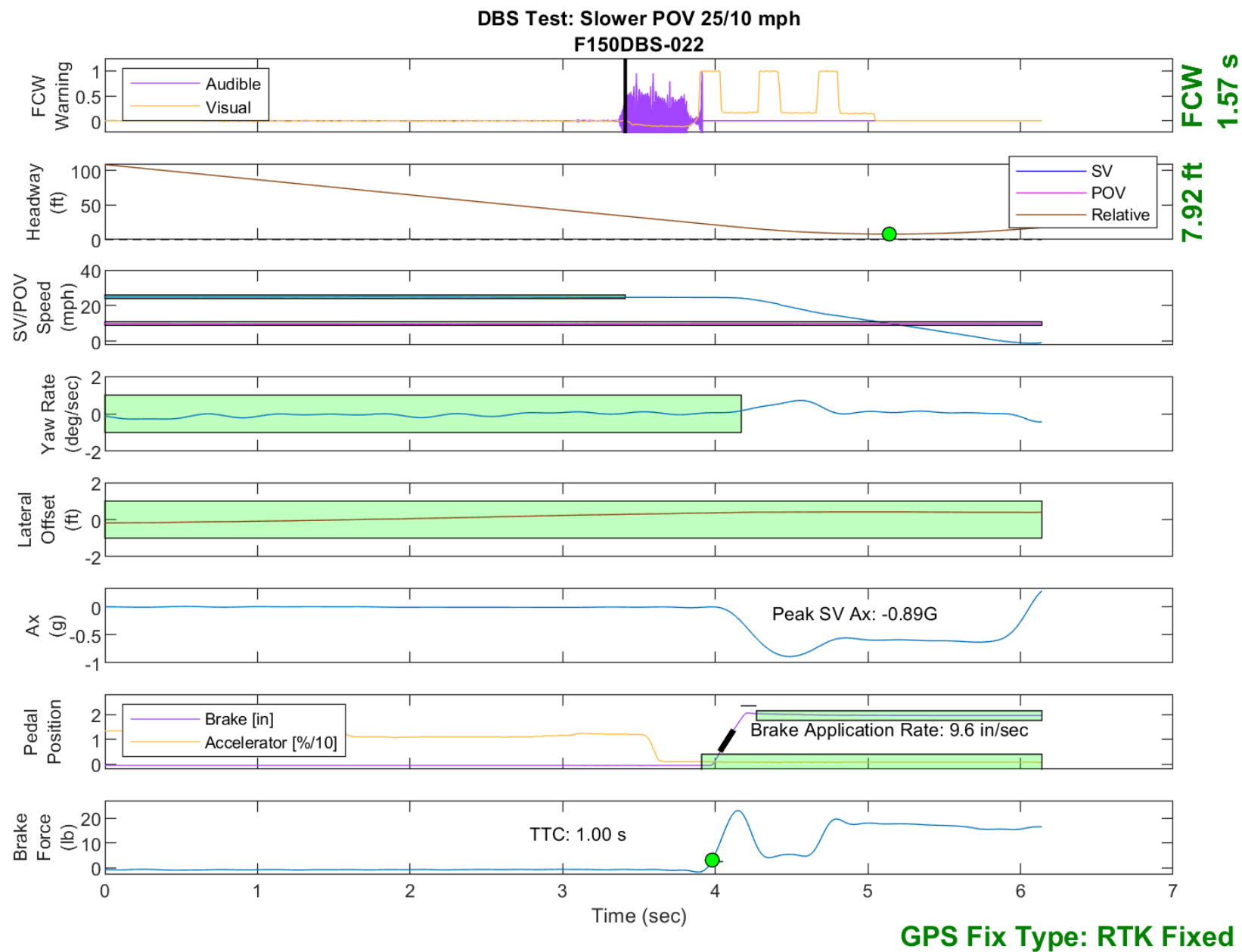


Figure E24. Time History for DBS Run 22, SV Encounters Slower POV, SV 25 mph, POV 10 mph

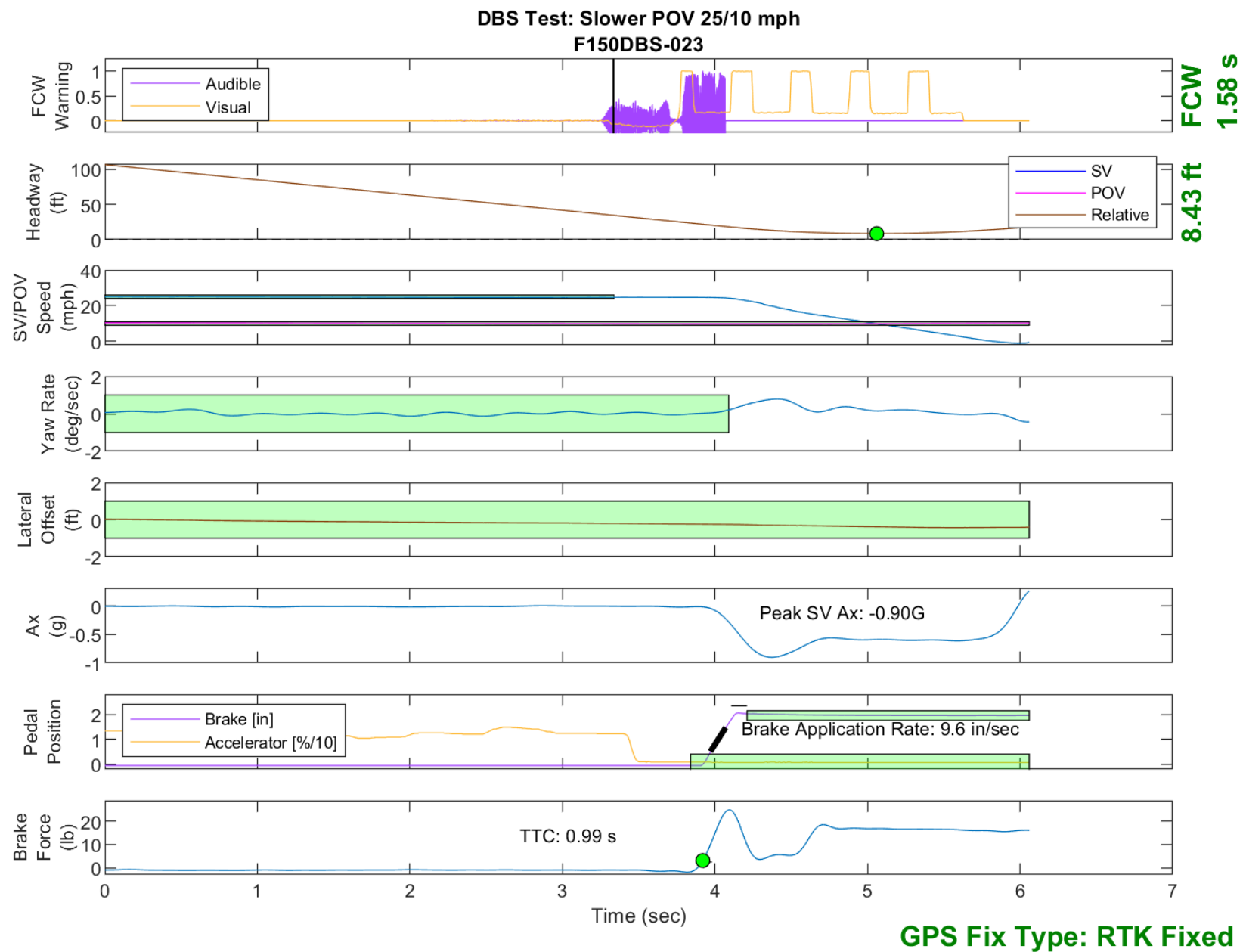


Figure E25. Time History for DBS Run 23, SV Encounters Slower POV, SV 25 mph, POV 10 mph

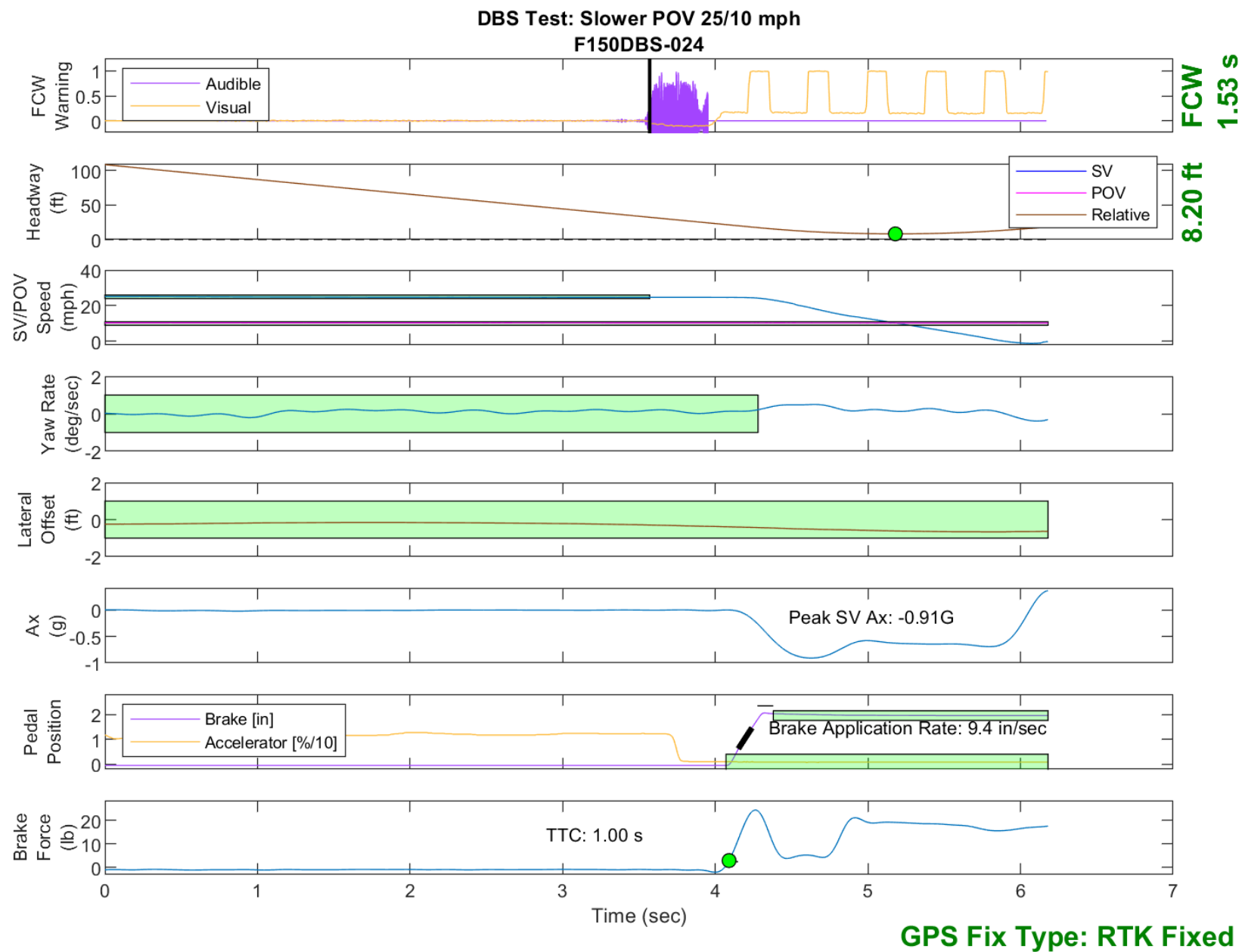


Figure E26. Time History for DBS Run 24, SV Encounters Slower POV, SV 25 mph, POV 10 mph

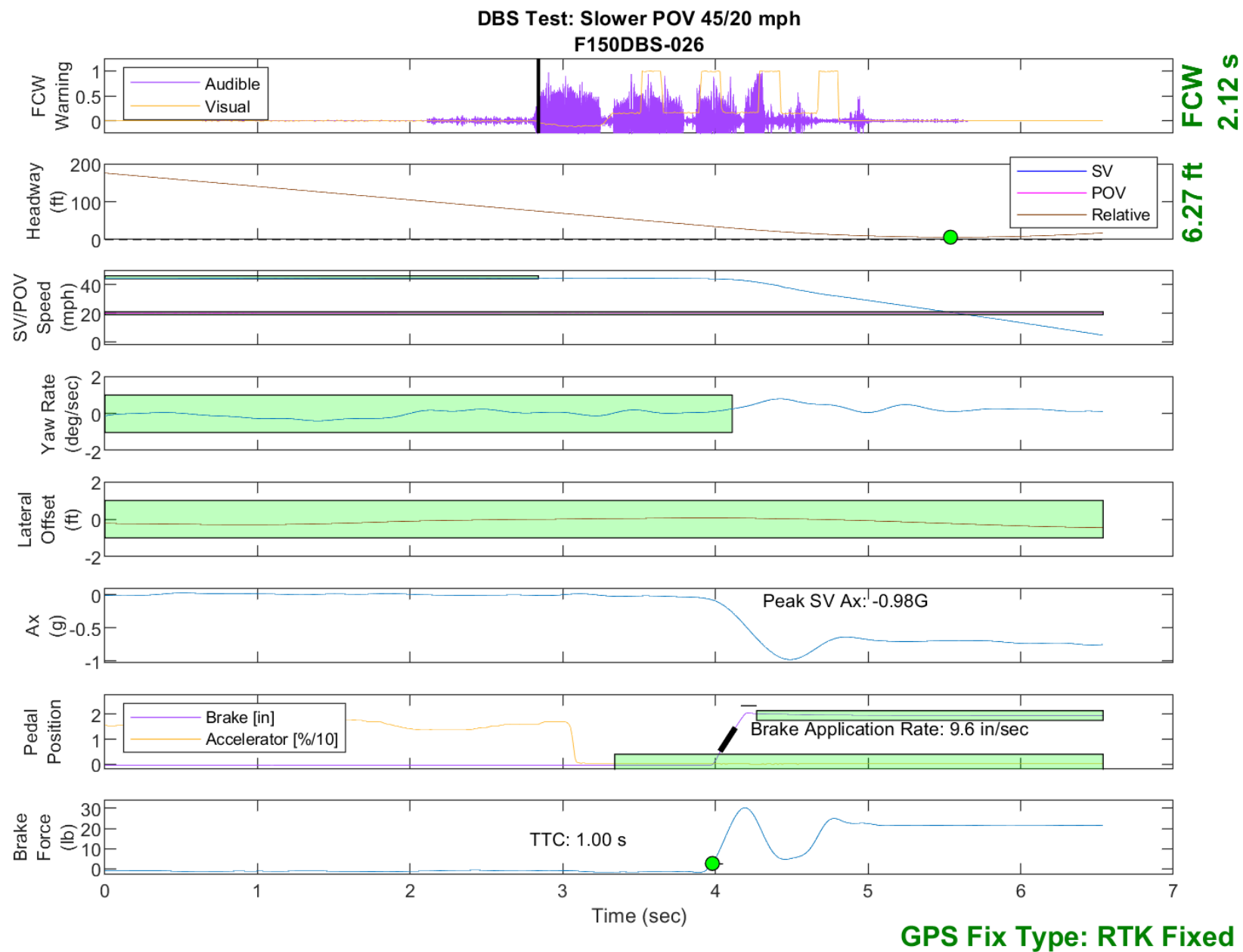


Figure E27. Time History for DBS Run 26, SV Encounters Slower POV, SV 45 mph, POV 20 mph

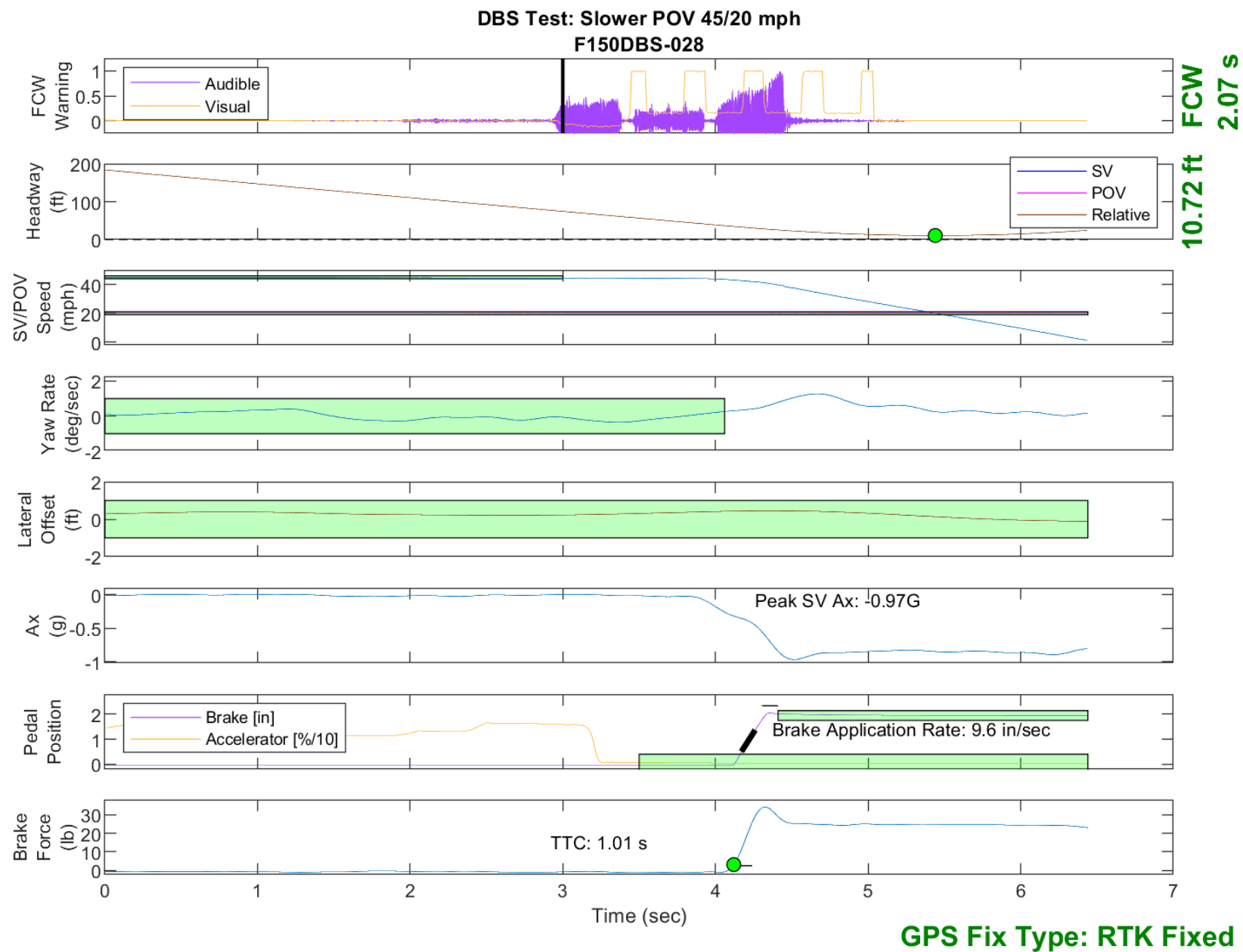


Figure E28. Time History for DBS Run 28, SV Encounters Slower POV, SV 45 mph, POV 20 mph

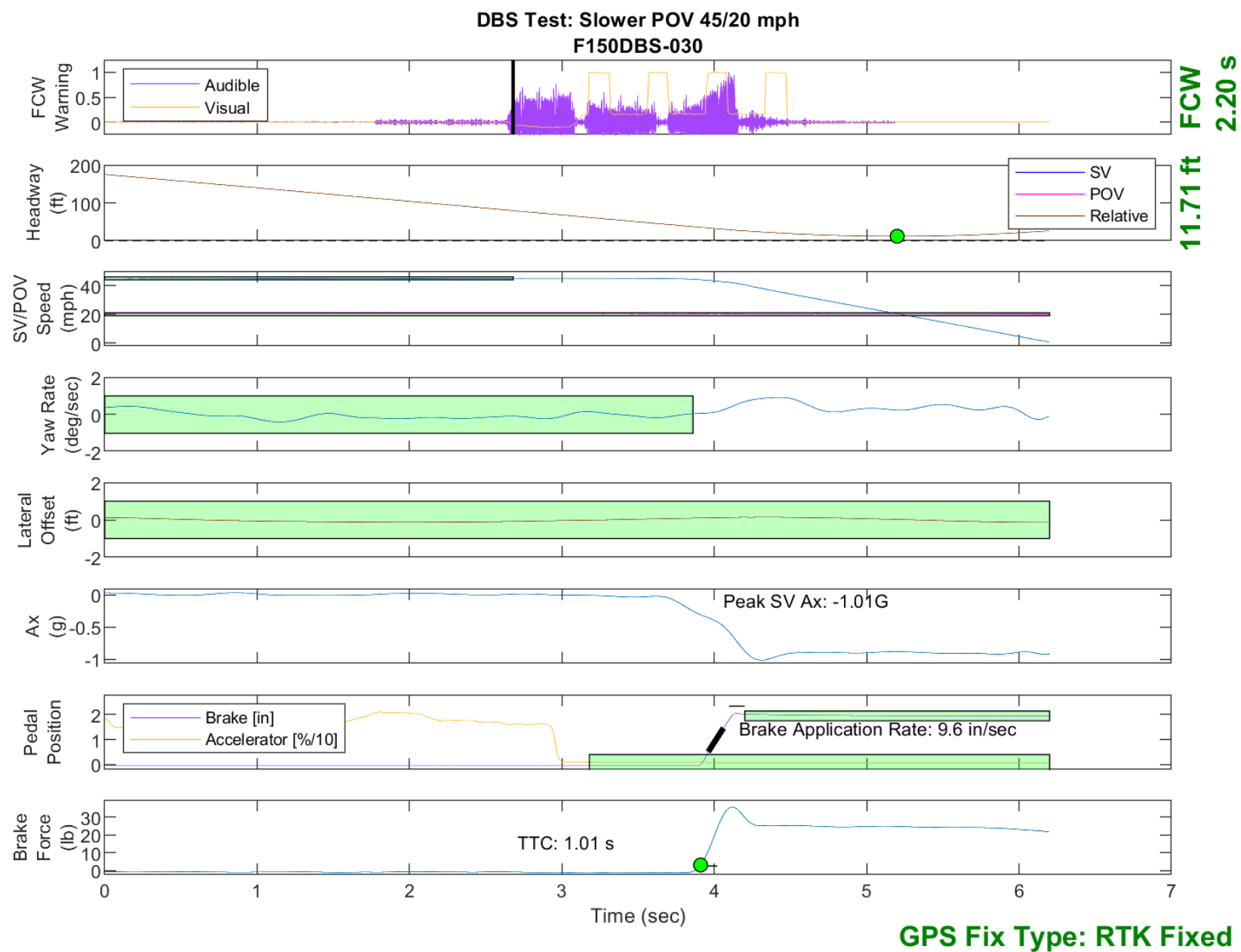


Figure E29. Time History for DBS Run 30, SV Encounters Slower POV, SV 45 mph, POV 20 mph

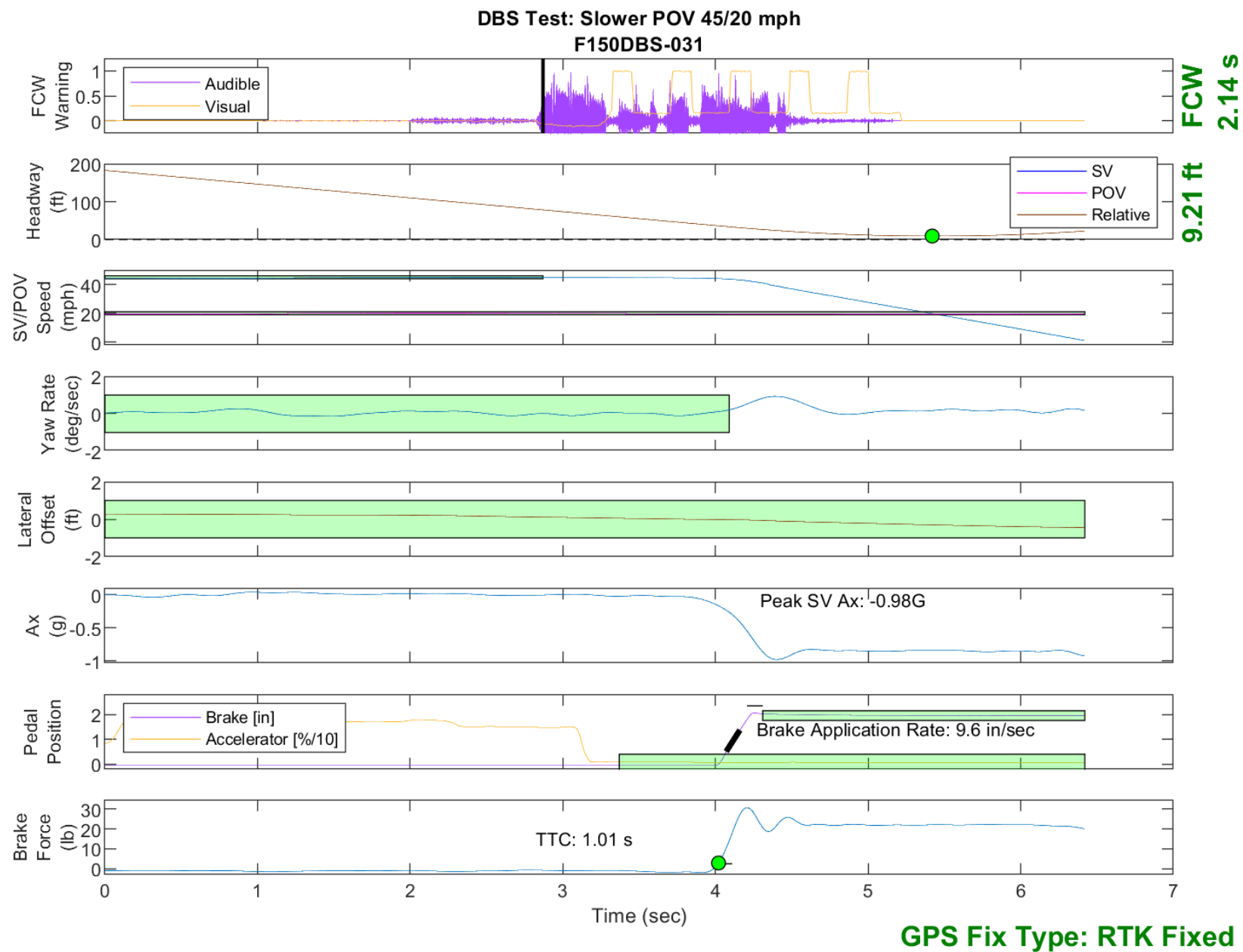


Figure E30. Time History for DBS Run 31, SV Encounters Slower POV, SV 45 mph, POV 20 mph

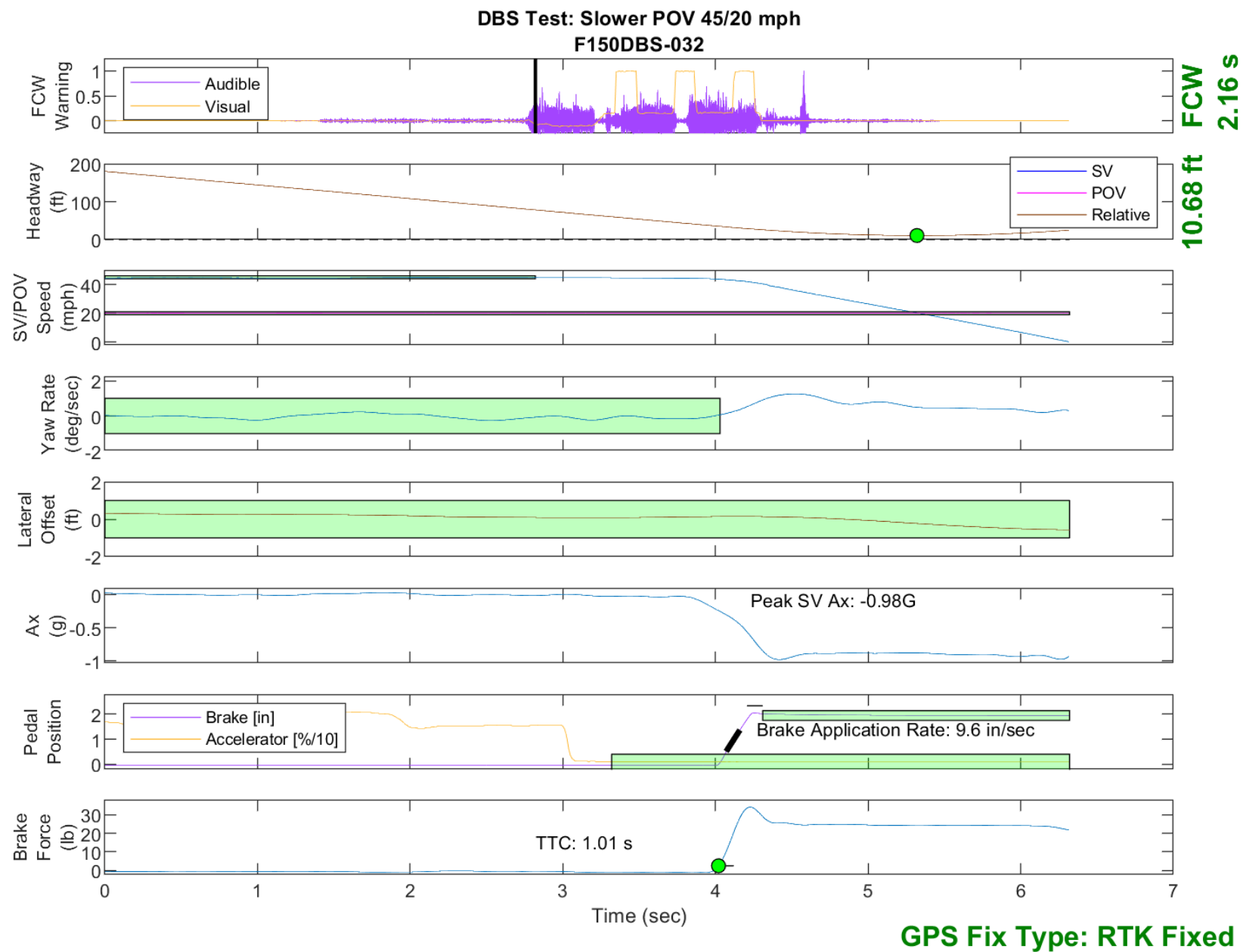


Figure E31. Time History for DBS Run 32, SV Encounters Slower POV, SV 45 mph, POV 20 mph

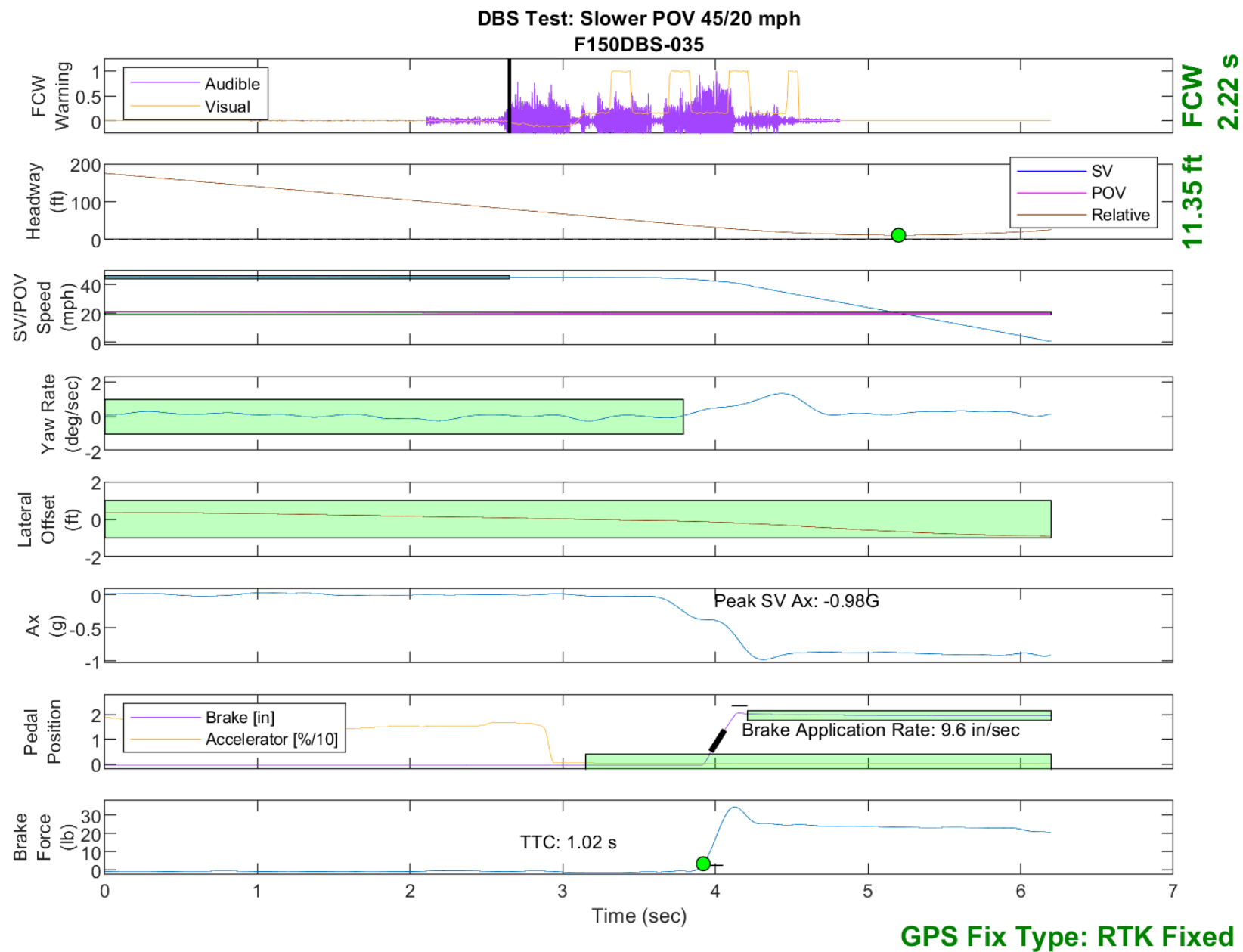


Figure E32. Time History for DBS Run 35, SV Encounters Slower POV, SV 45 mph, POV 20 mph

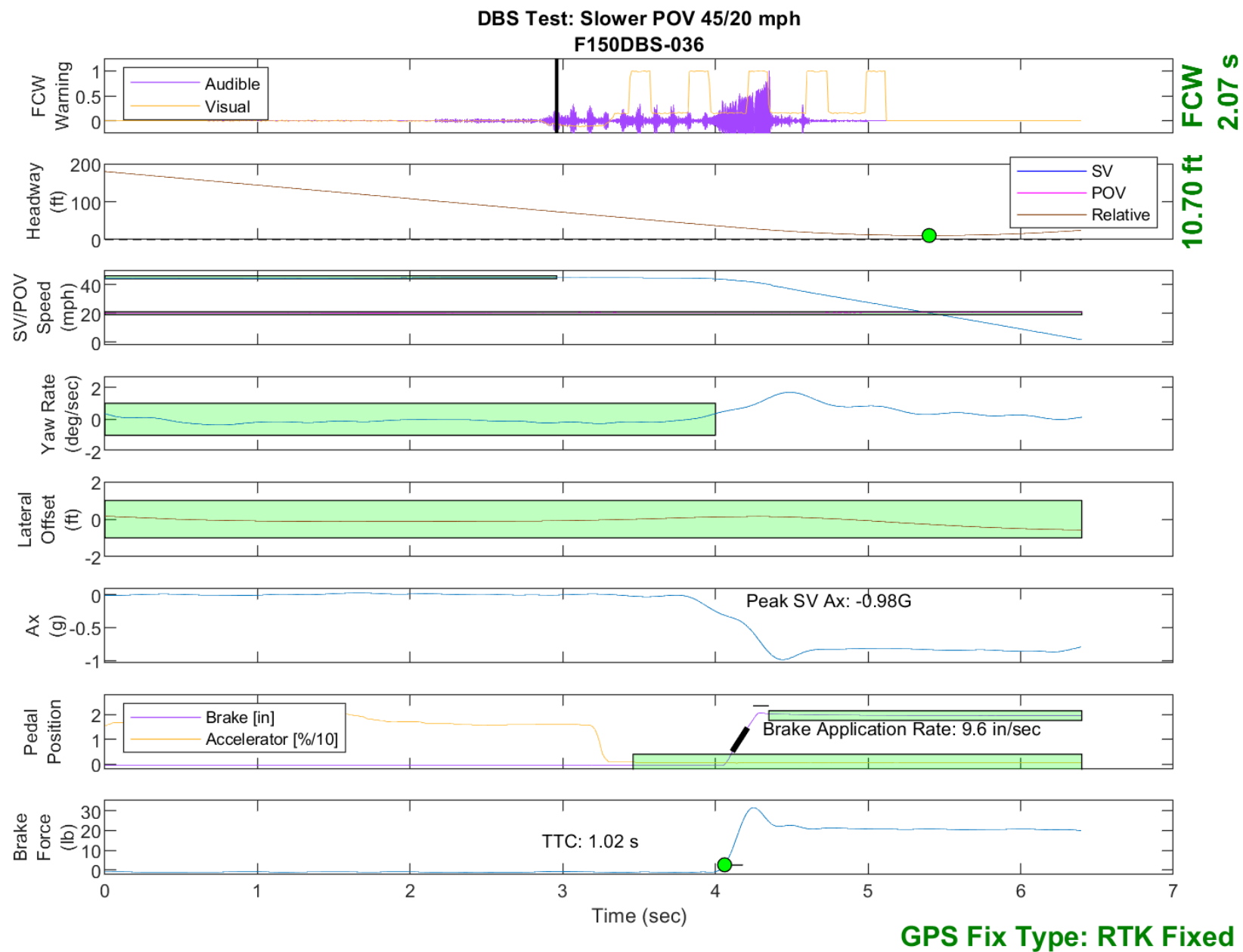


Figure E33. Time History for DBS Run 36, SV Encounters Slower POV, SV 45 mph, POV 20 mph

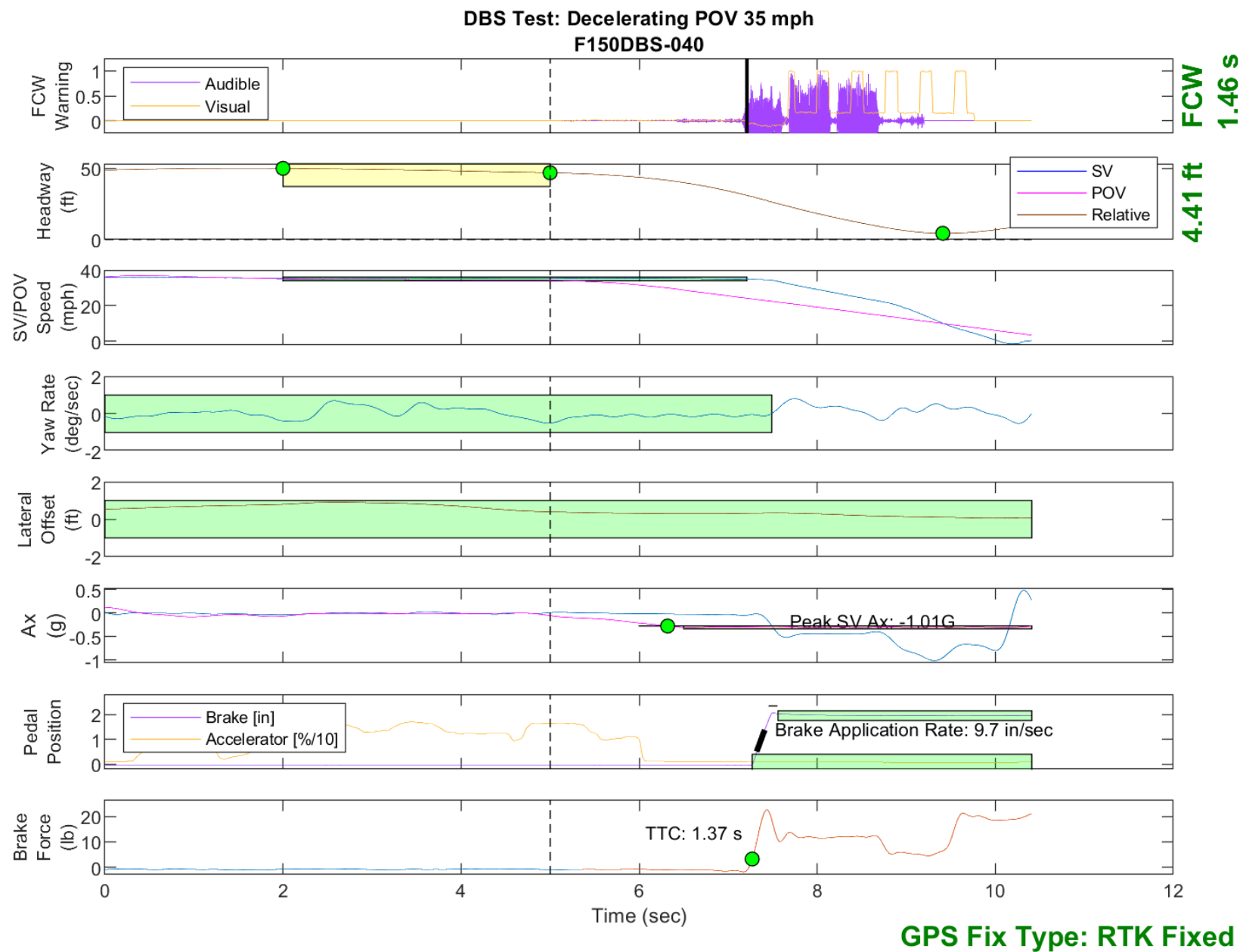


Figure E34. Time History for DBS Run 40, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

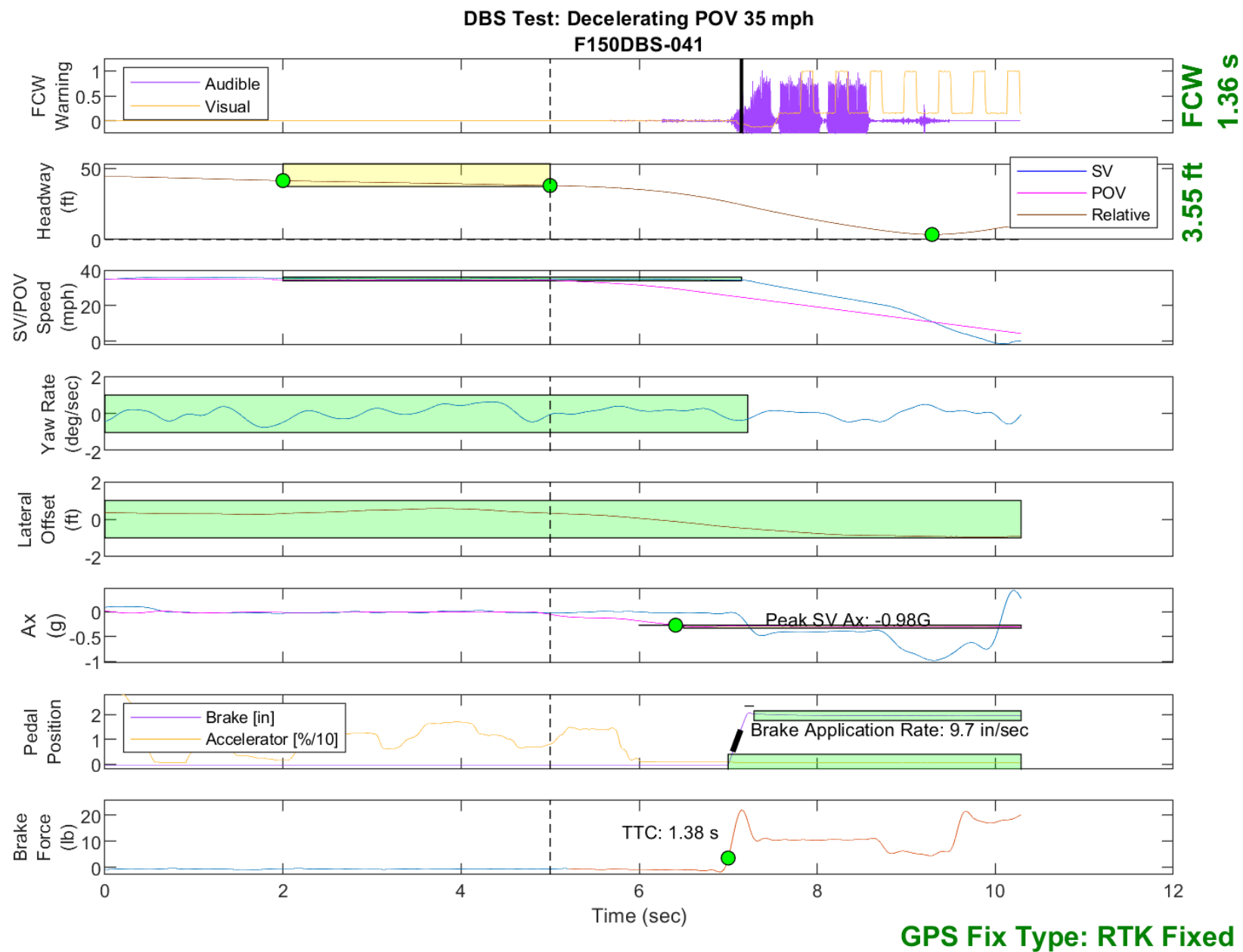


Figure E35. Time History for DBS Run 41, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

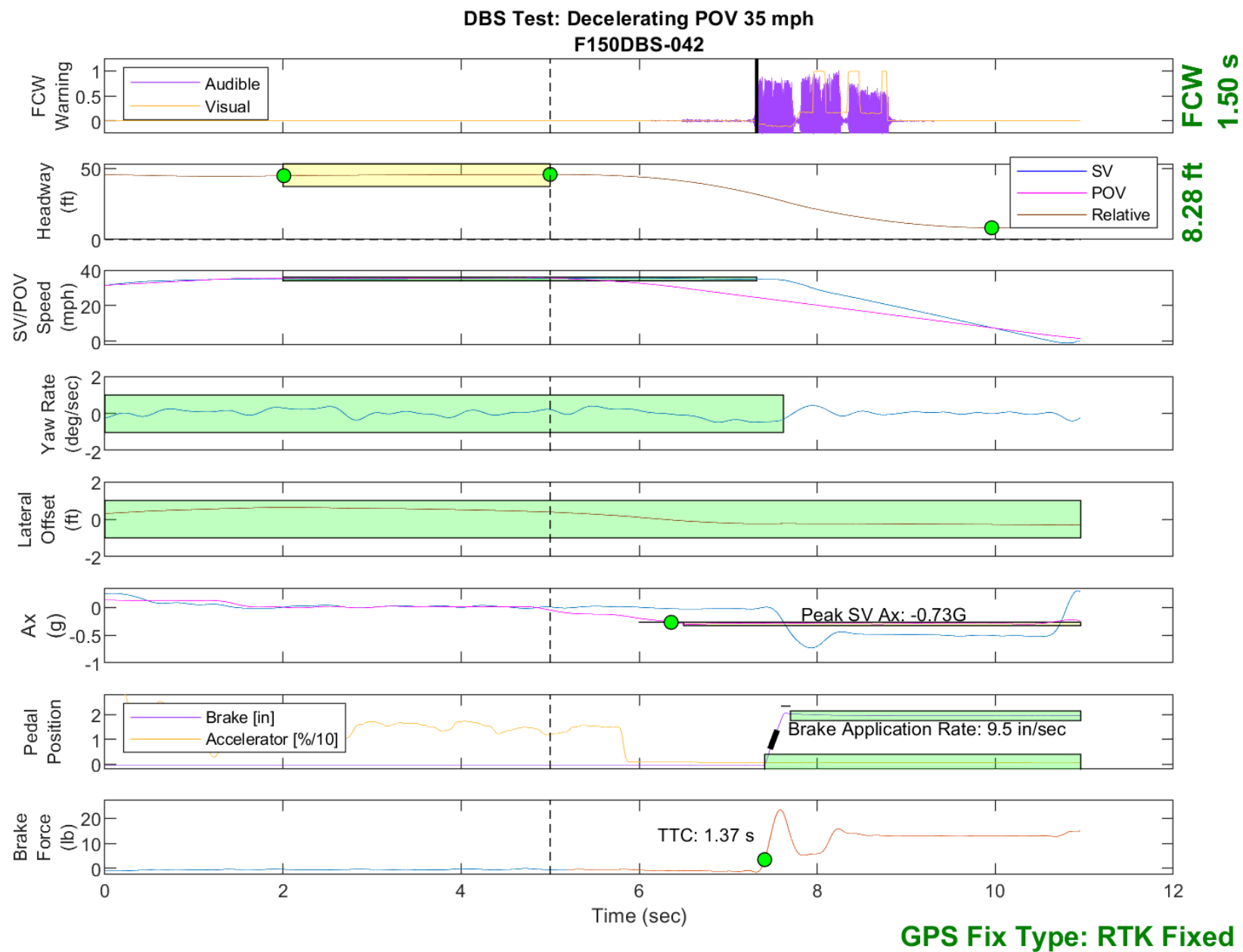


Figure E36. Time History for DBS Run 42, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

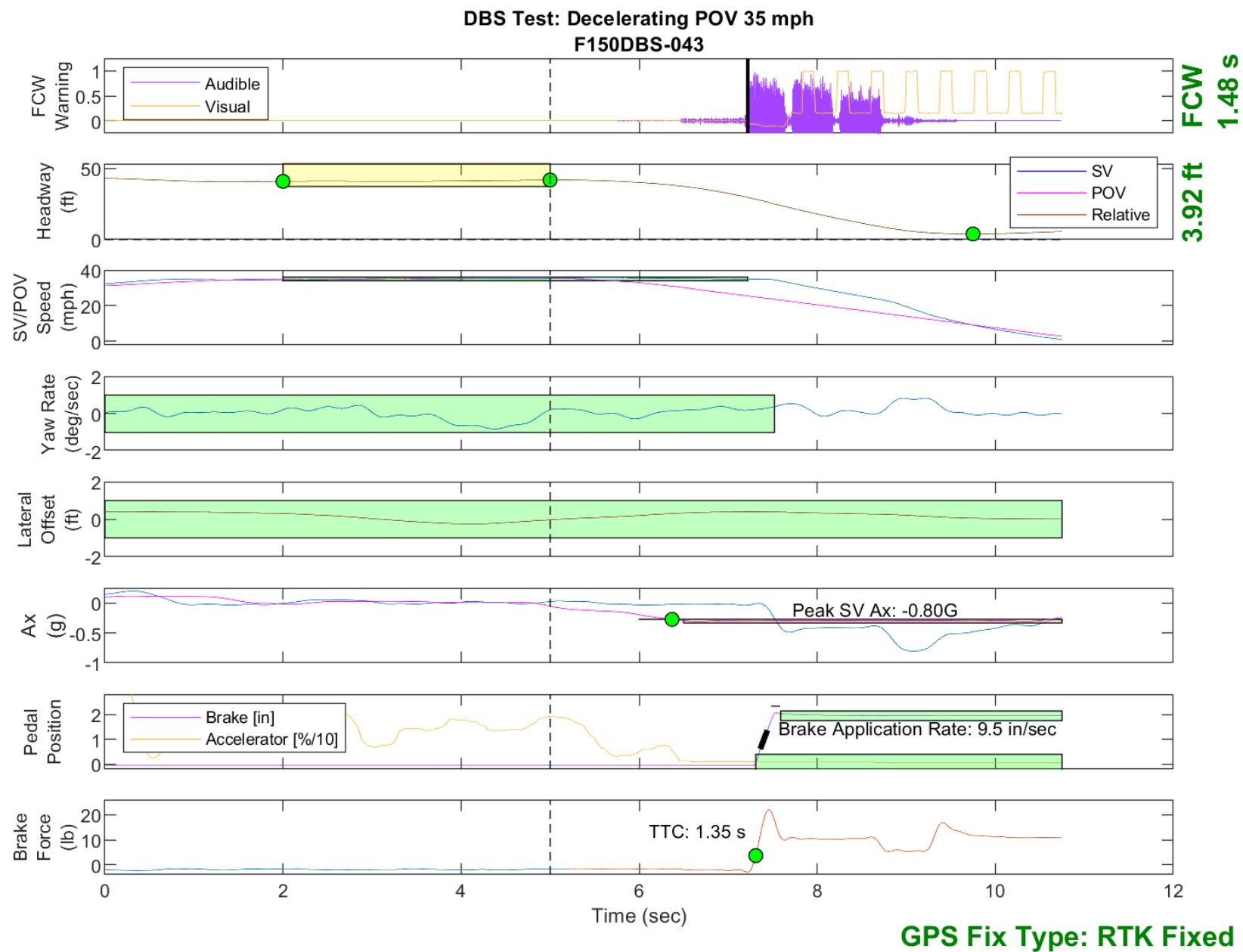


Figure E37. Time History for DBS Run 43, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

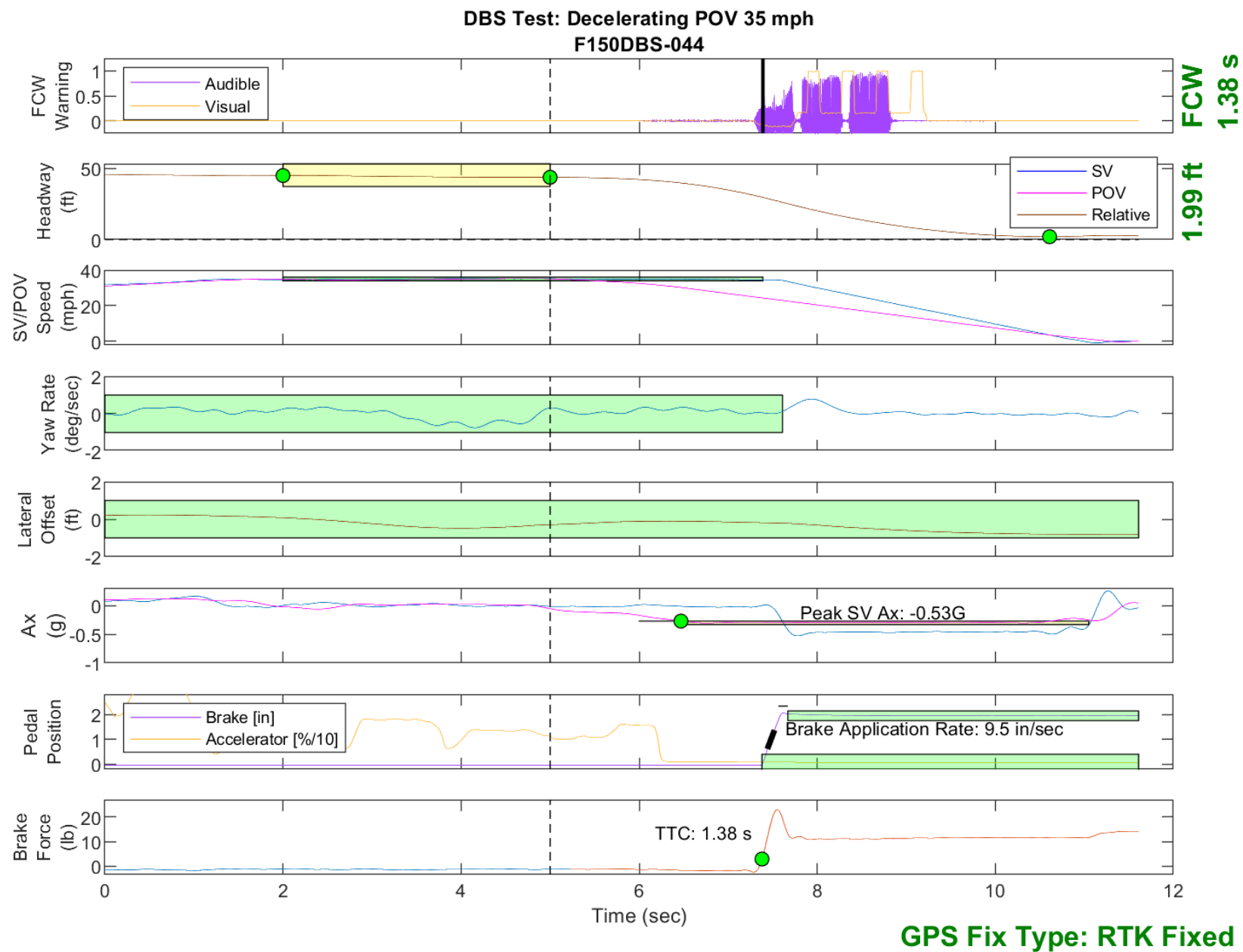


Figure E38. Time History for DBS Run 44, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

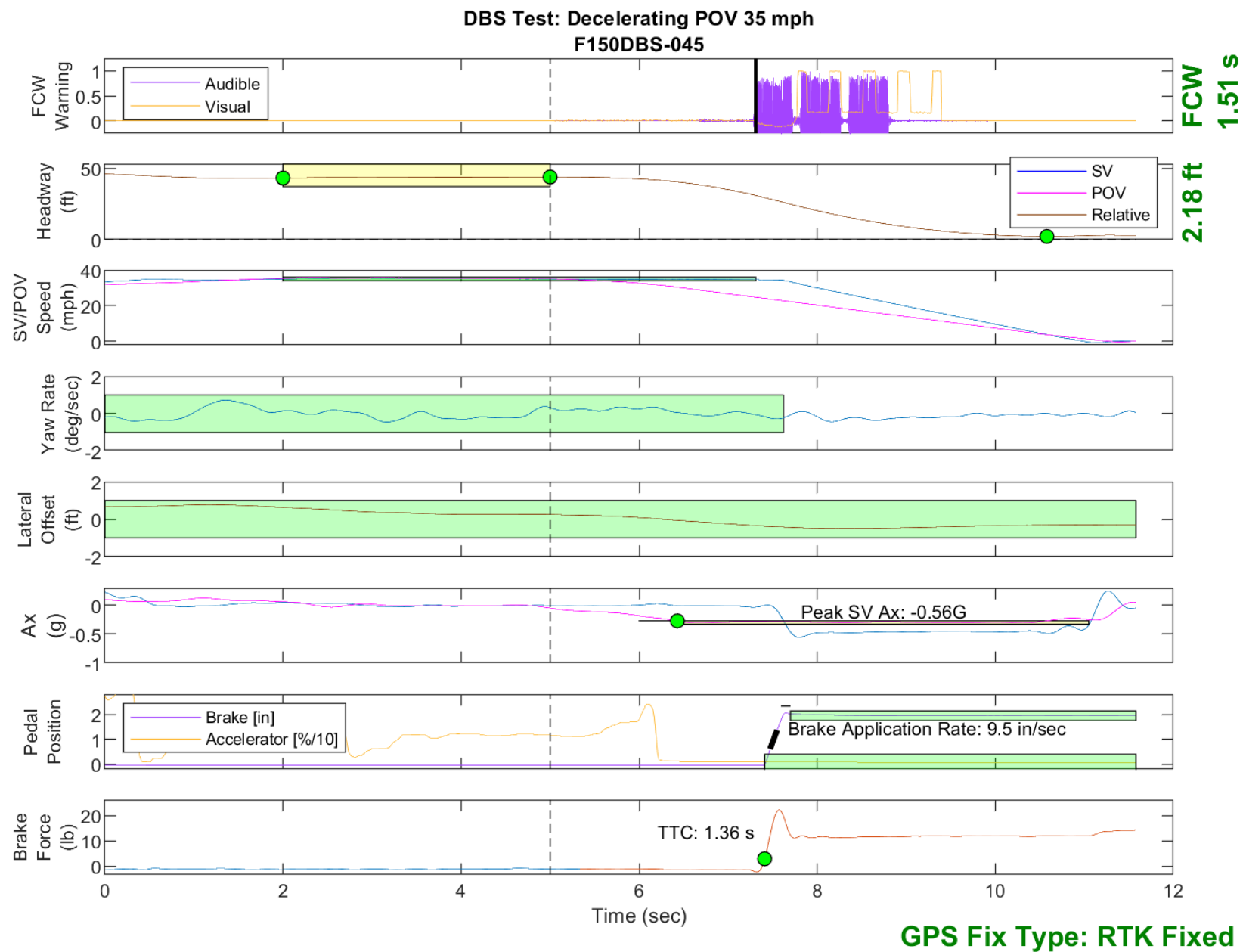


Figure E39. Time History for DBS Run 45, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph

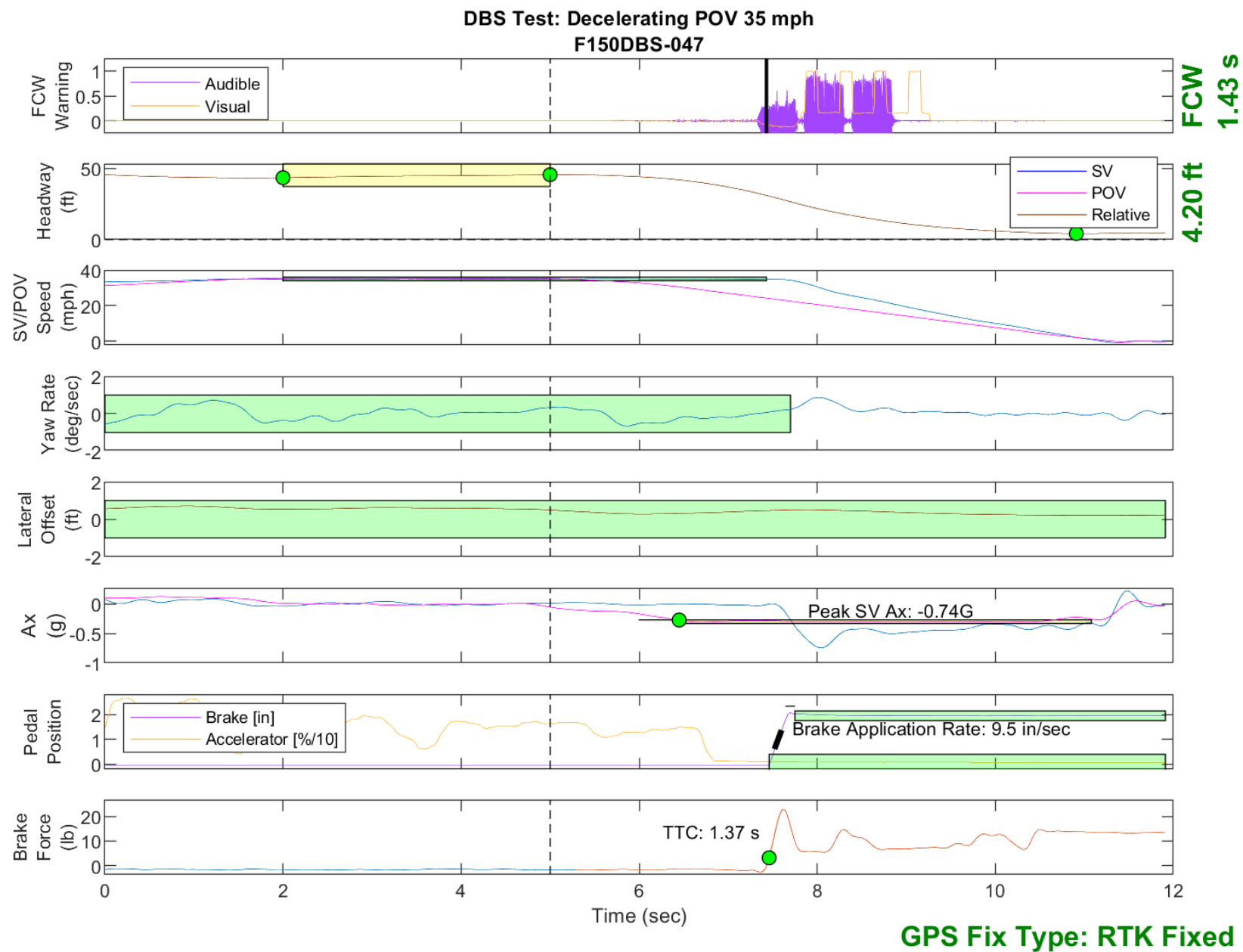


Figure E40. Time History for DBS Run 47, SV Encounters Decelerating POV, SV 35 mph, POV 35 mph



Figure E41. Time History for DBS Run 51, False Positive Baseline, SV 25 mph

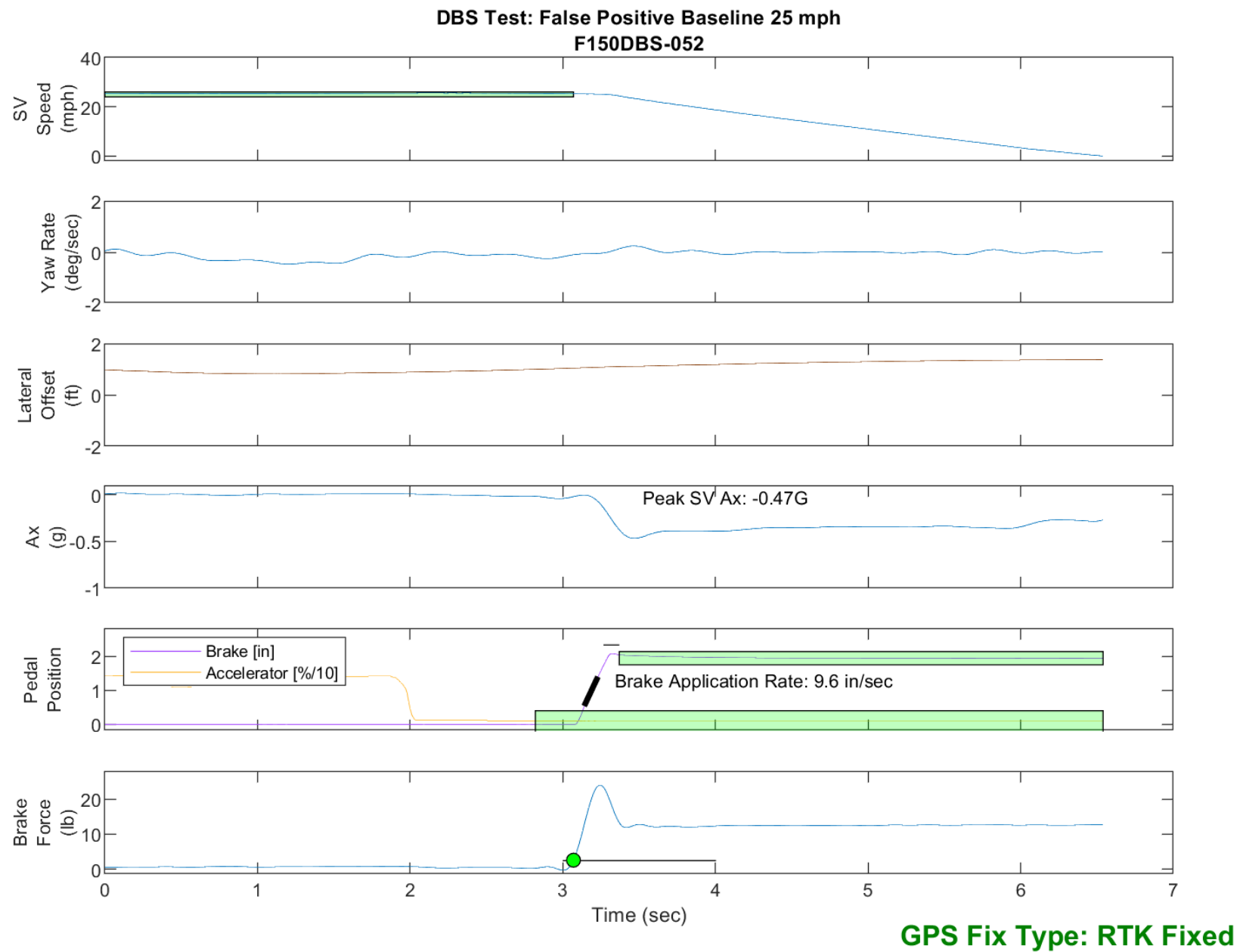


Figure E42. Time History for DBS Run 52, False Positive Baseline, SV 25 mph

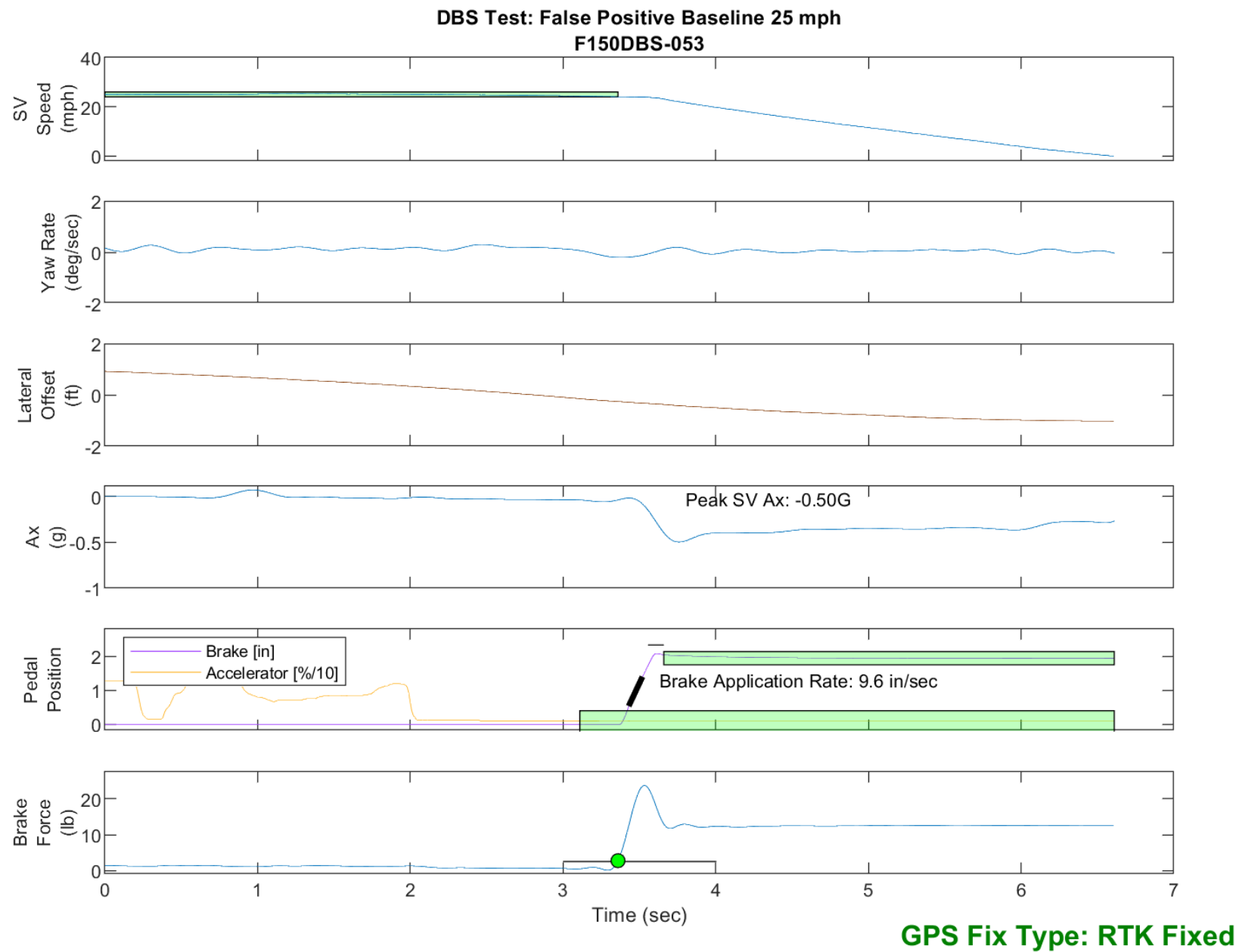


Figure E43. Time History for DBS Run 53, False Positive Baseline, SV 25 mph

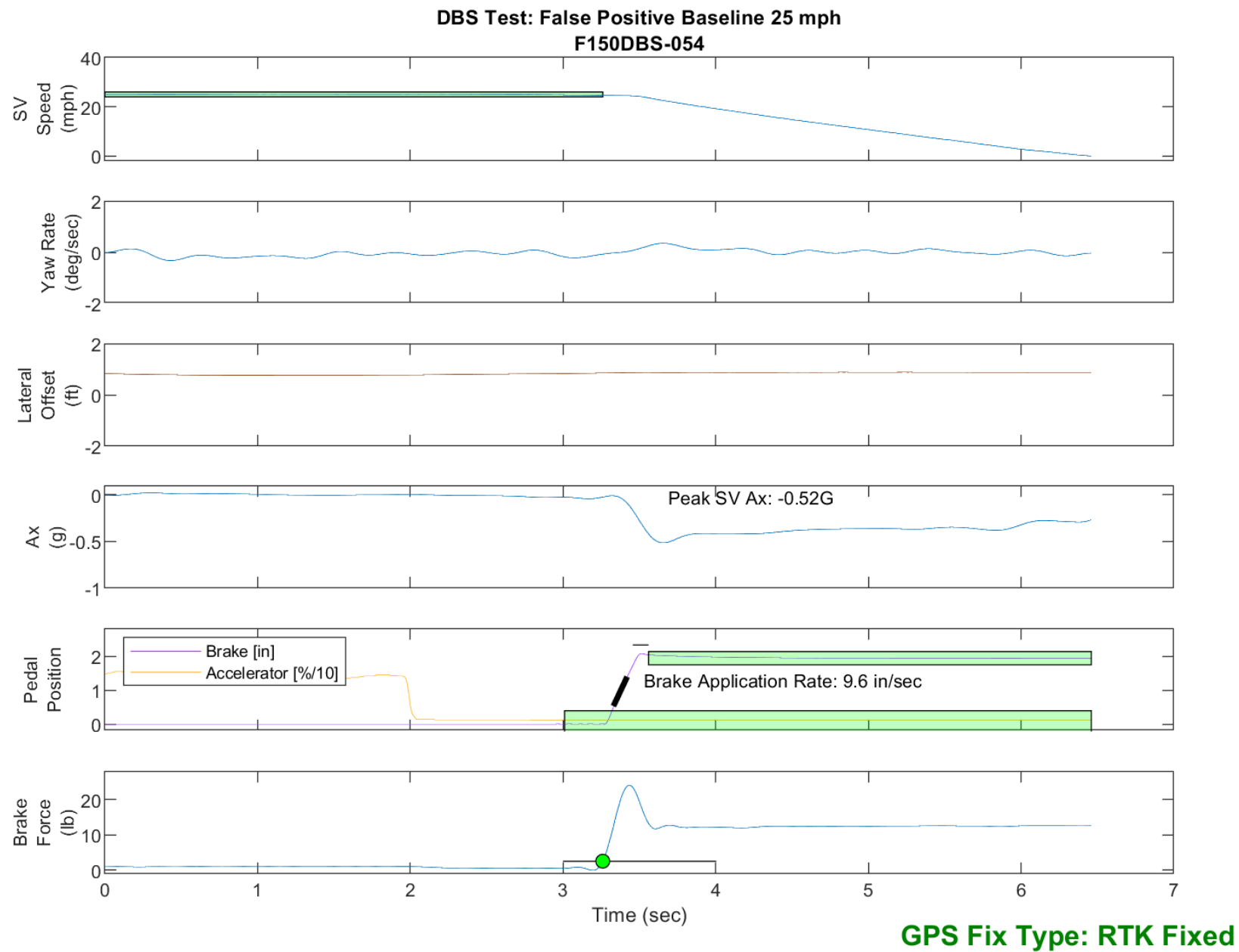


Figure E44. Time History for DBS Run 54, False Positive Baseline, SV 25 mph

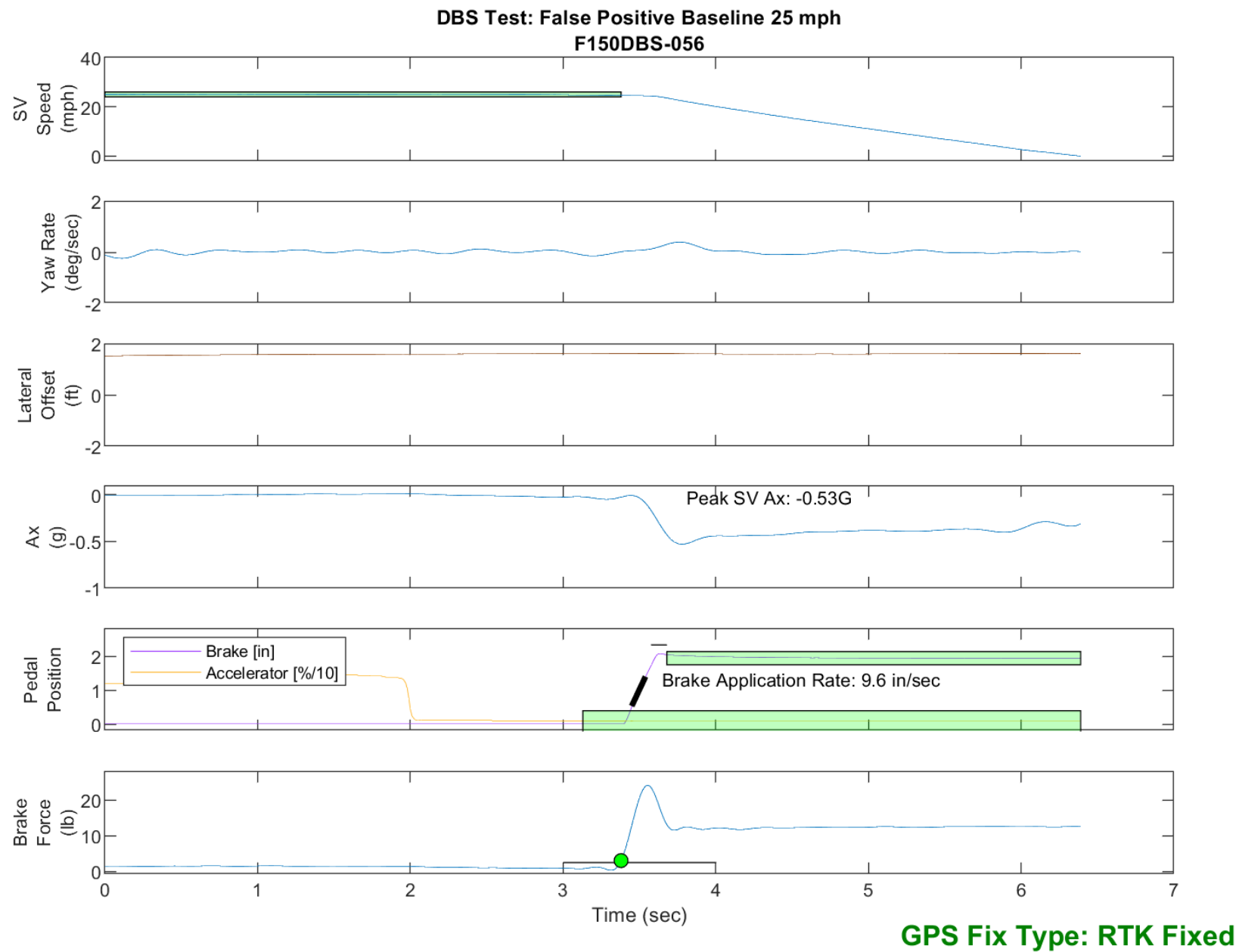


Figure E45. Time History for DBS Run 56, False Positive Baseline, SV 25 mph

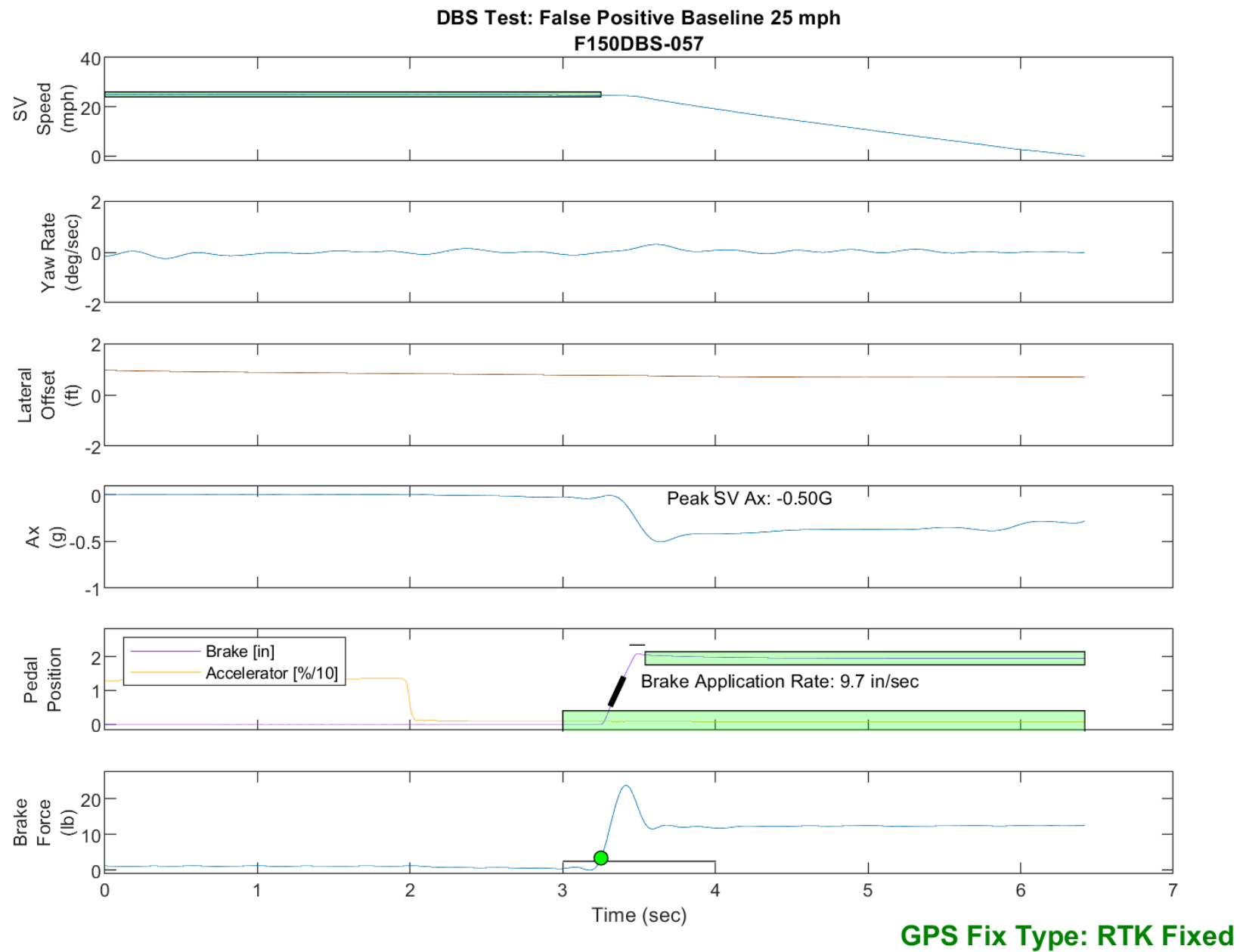


Figure E46. Time History for DBS Run 57, False Positive Baseline, SV 25 mph

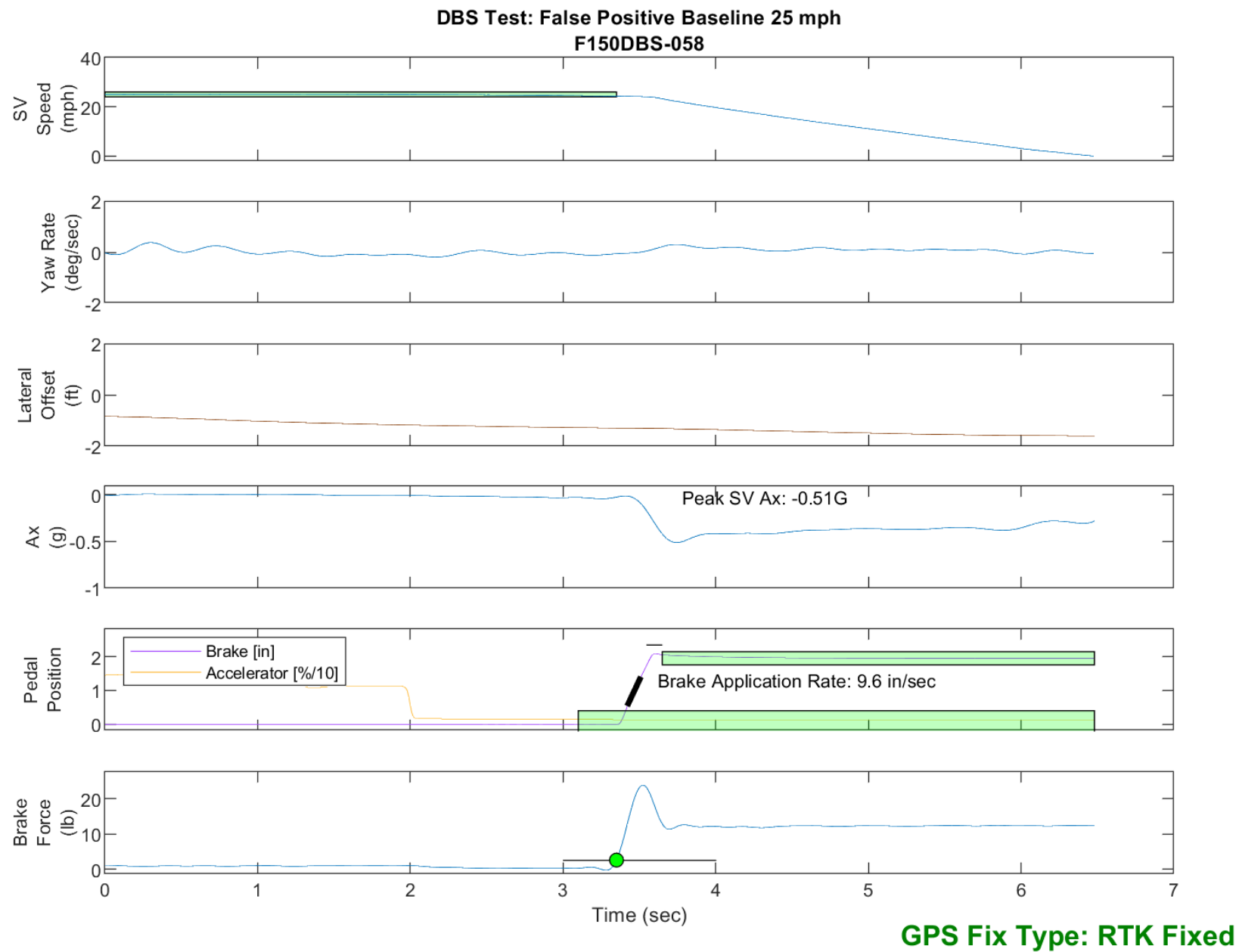


Figure E47. Time History for DBS Run 58, False Positive Baseline, SV 25 mph

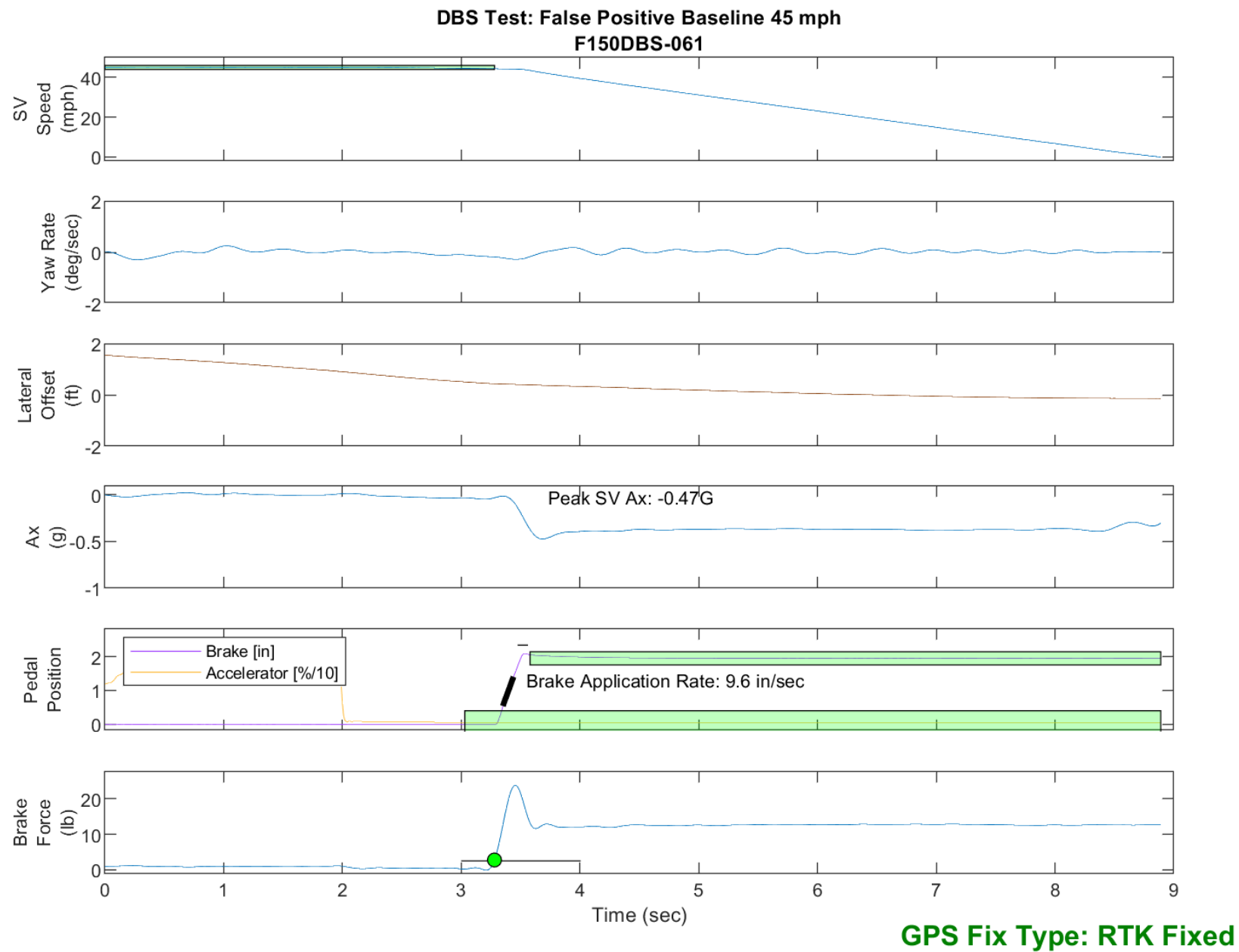


Figure E48. Time History for DBS Run 61, False Positive Baseline, SV 45 mph

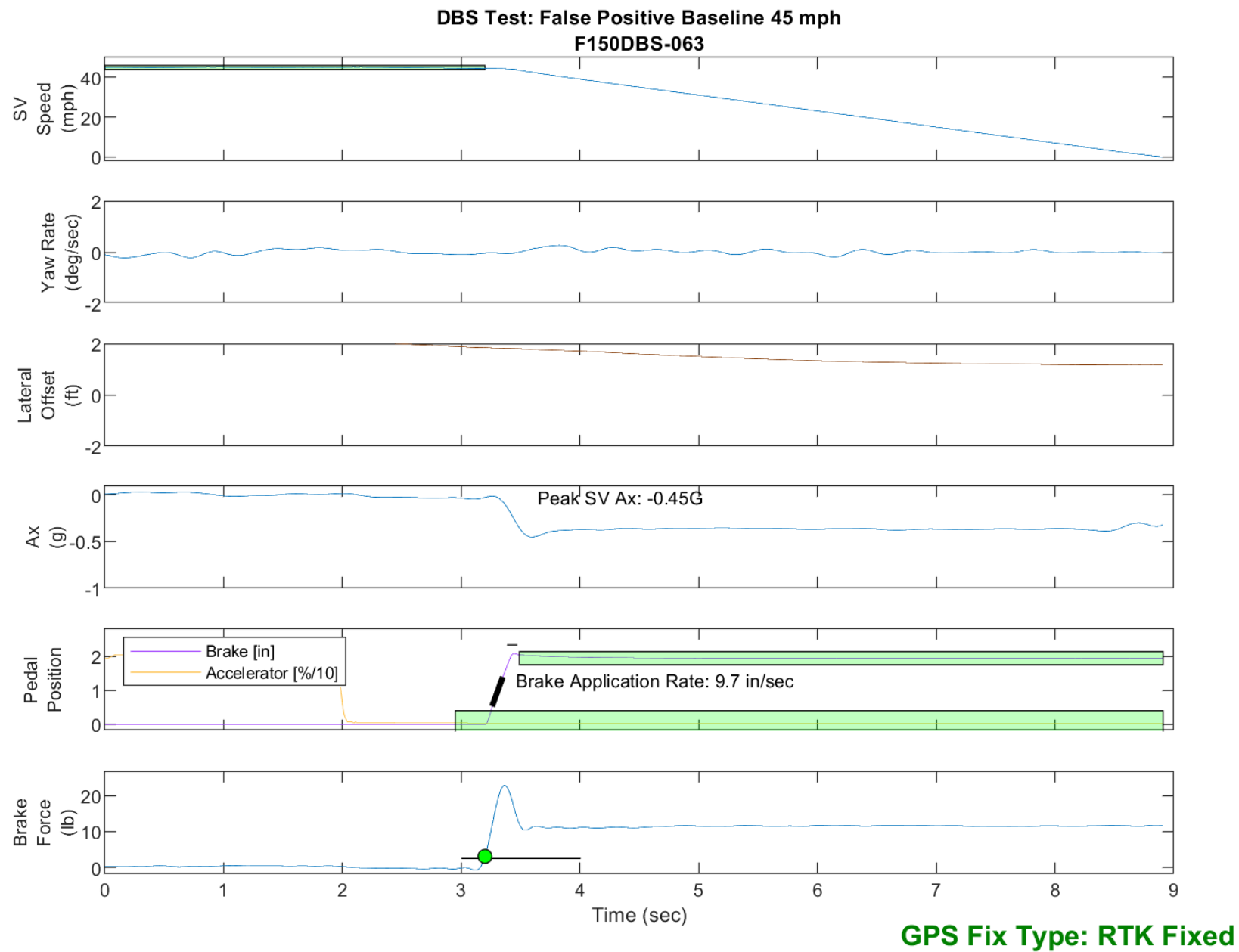


Figure E49. Time History for DBS Run 63, False Positive Baseline, SV 45 mph

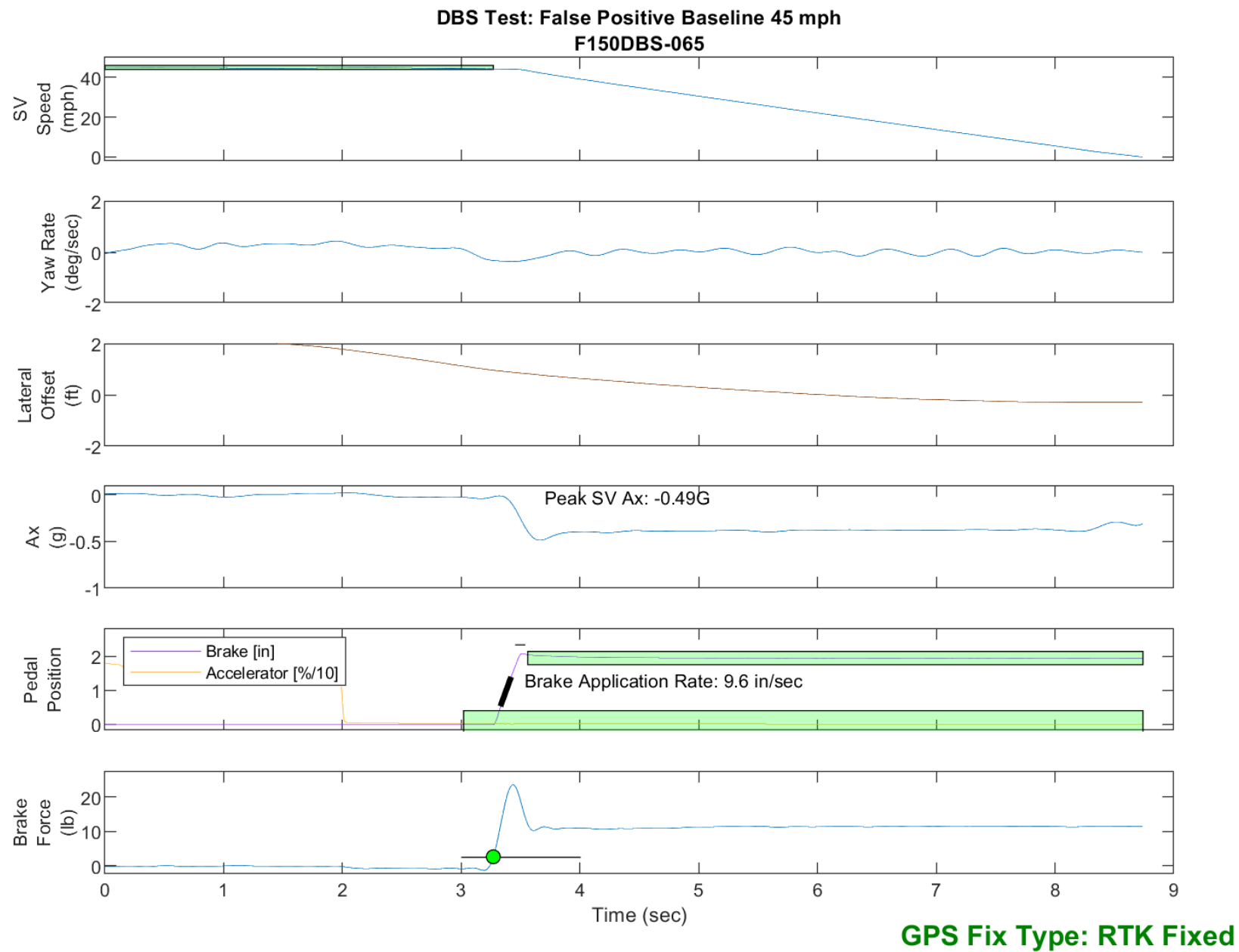


Figure E50. Time History for DBS Run 65, False Positive Baseline, SV 45 mph

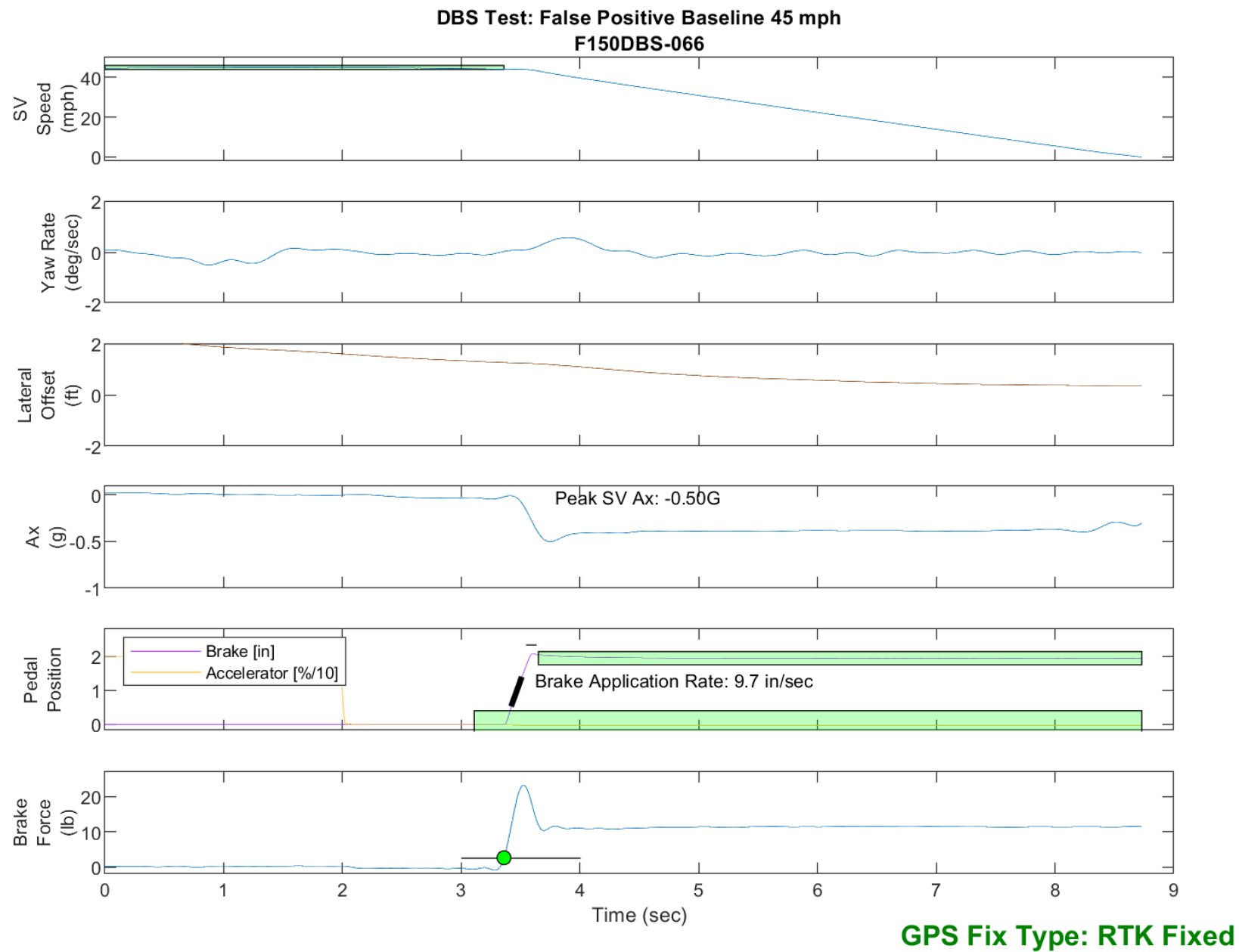


Figure E51. Time History for DBS Run 66, False Positive Baseline, SV 45 mph

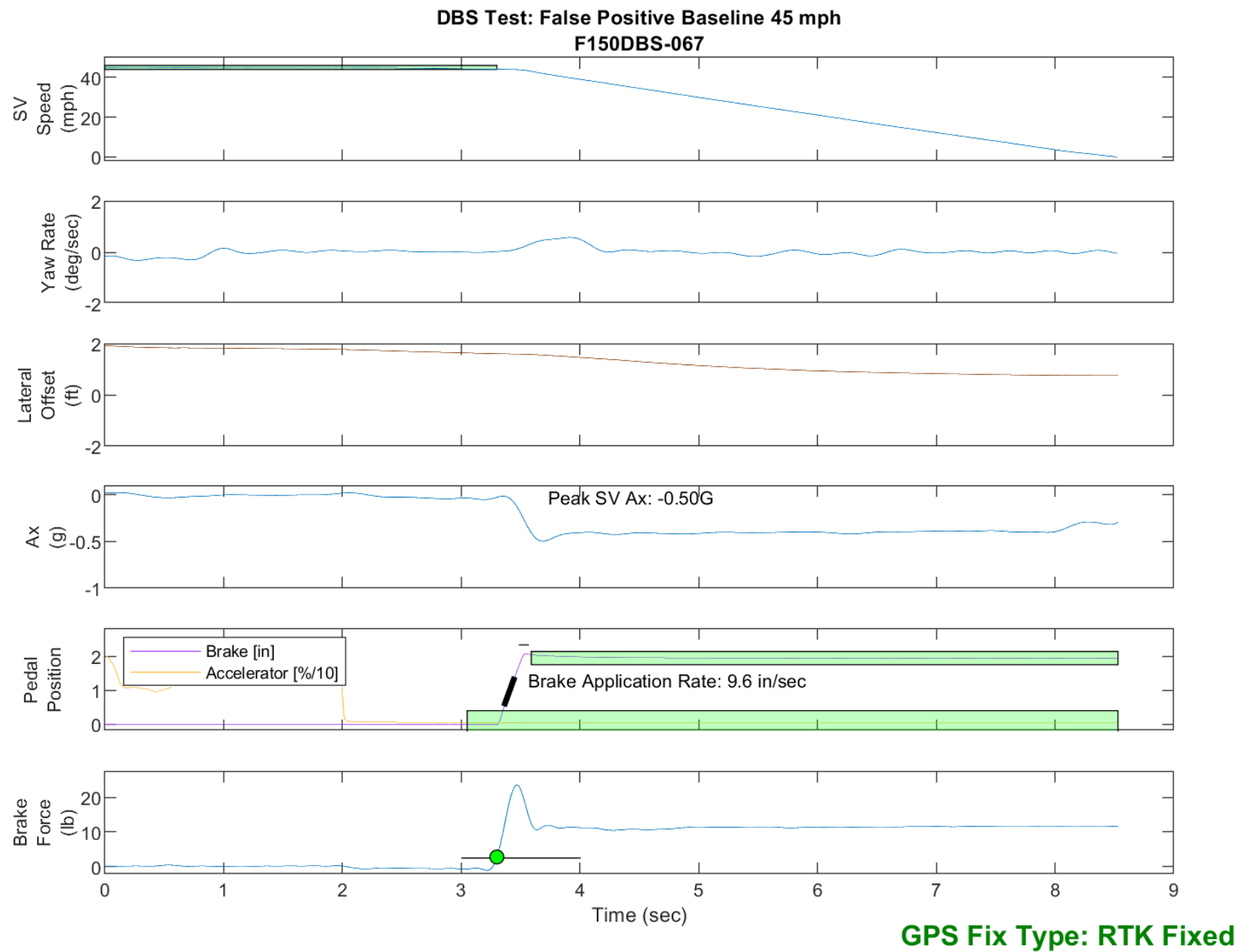


Figure E52. Time History for DBS Run 67, False Positive Baseline, SV 45 mph

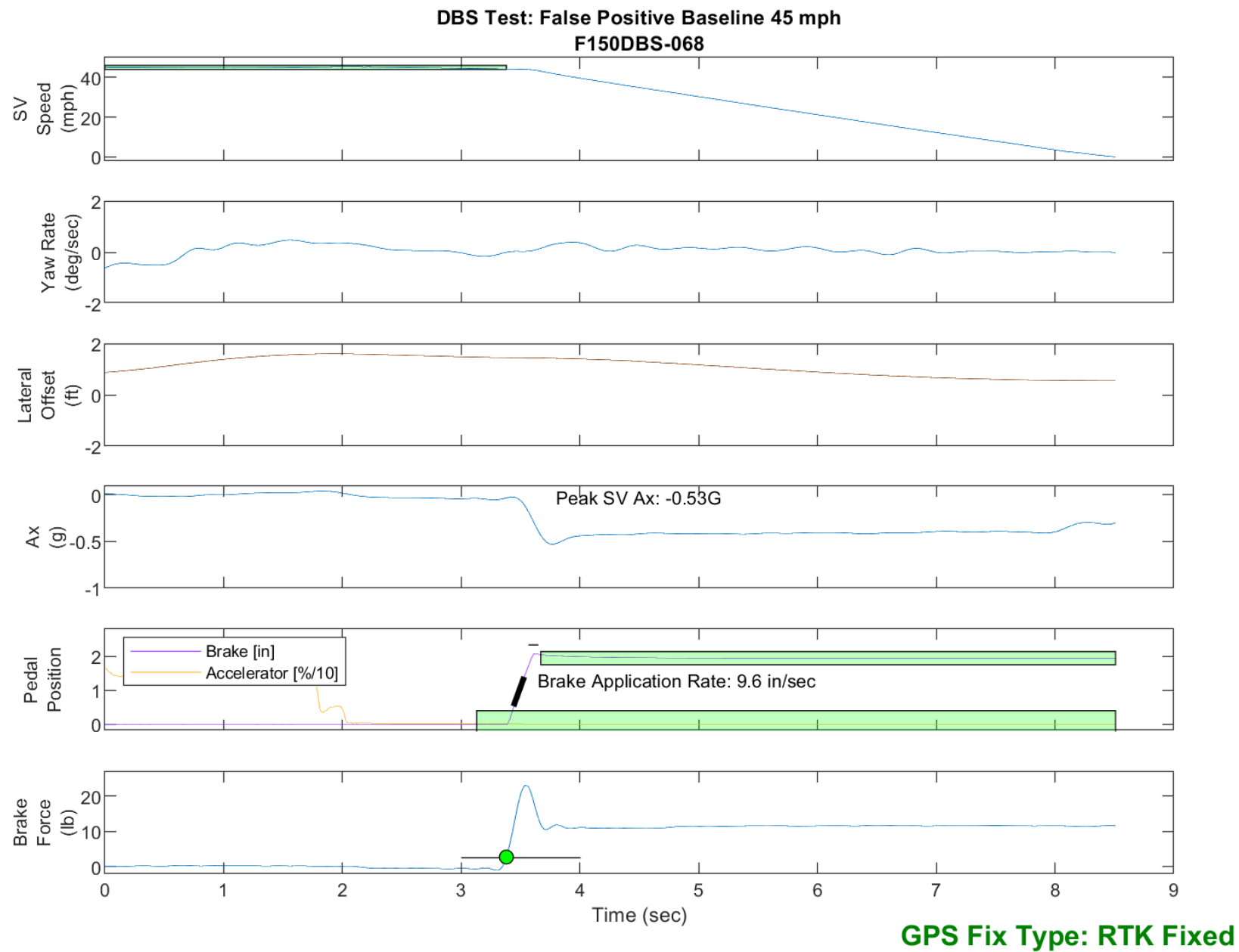


Figure E53. Time History for DBS Run 68, False Positive Baseline, SV 45 mph

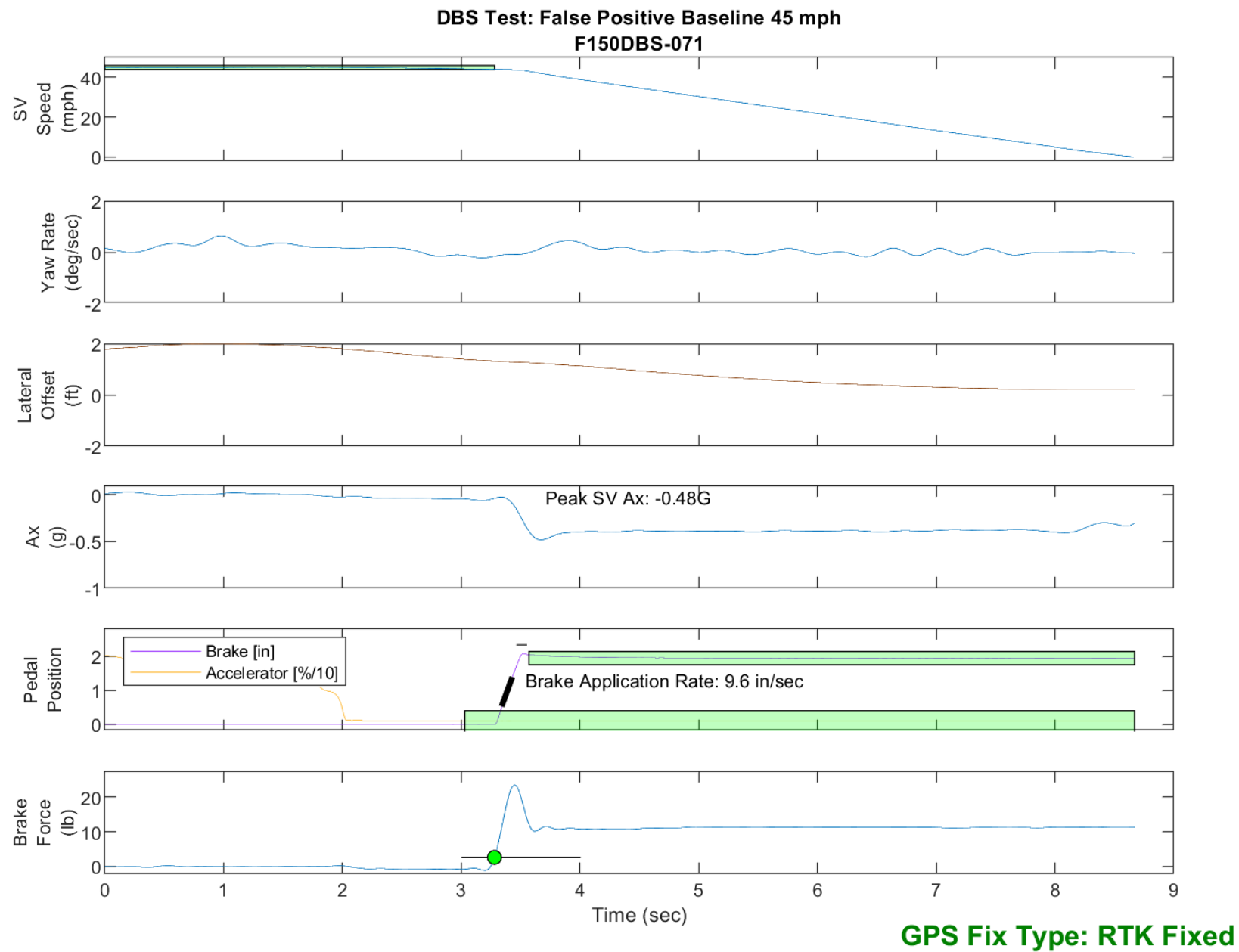


Figure E54. Time History for DBS Run 71, False Positive Baseline, SV 45 mph

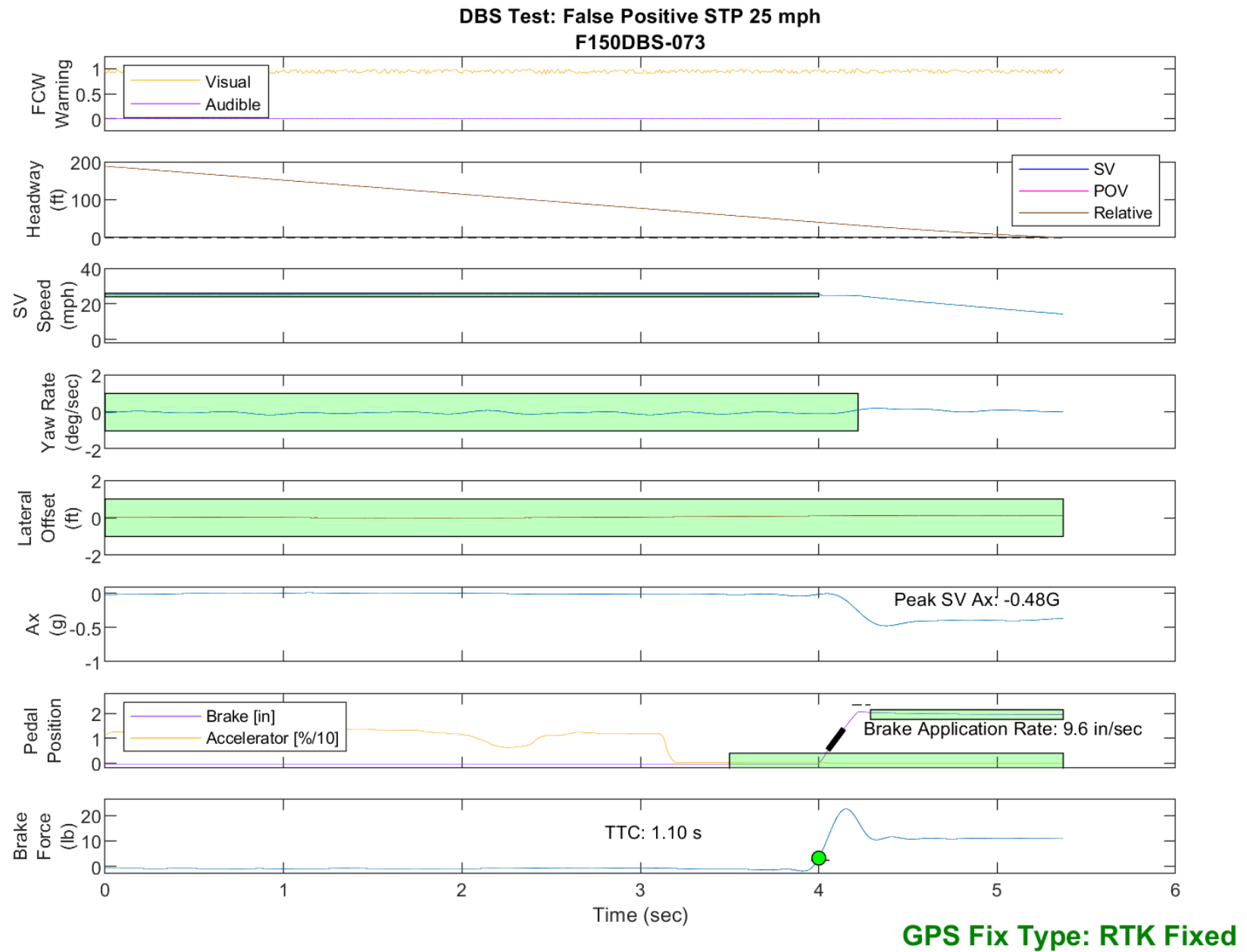


Figure E55. Time History for DBS Run 73, SV Encounters Steel Trench Plate, SV 25 mph

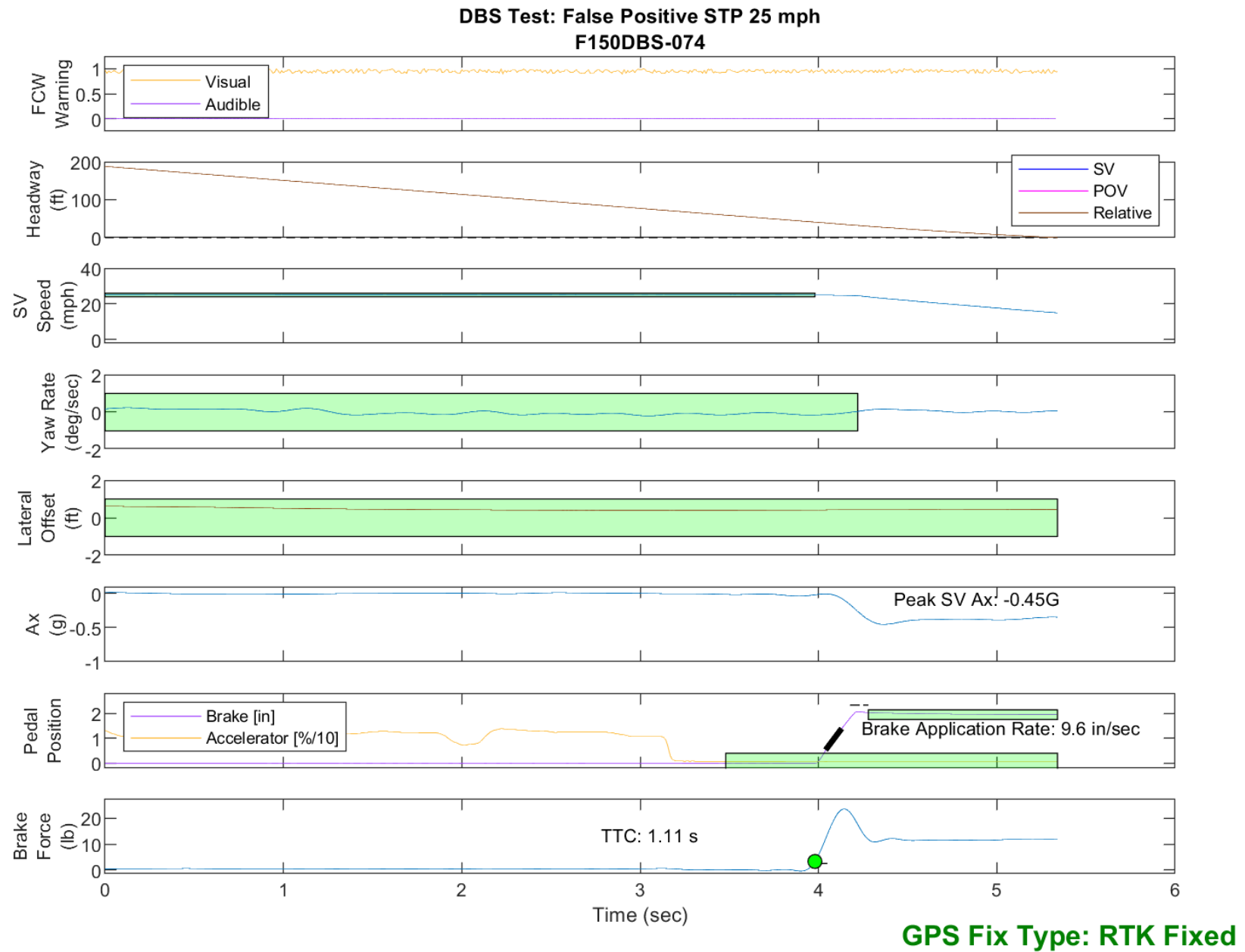


Figure E56. Time History for DBS Run 74, SV Encounters Steel Trench Plate, SV 25 mph

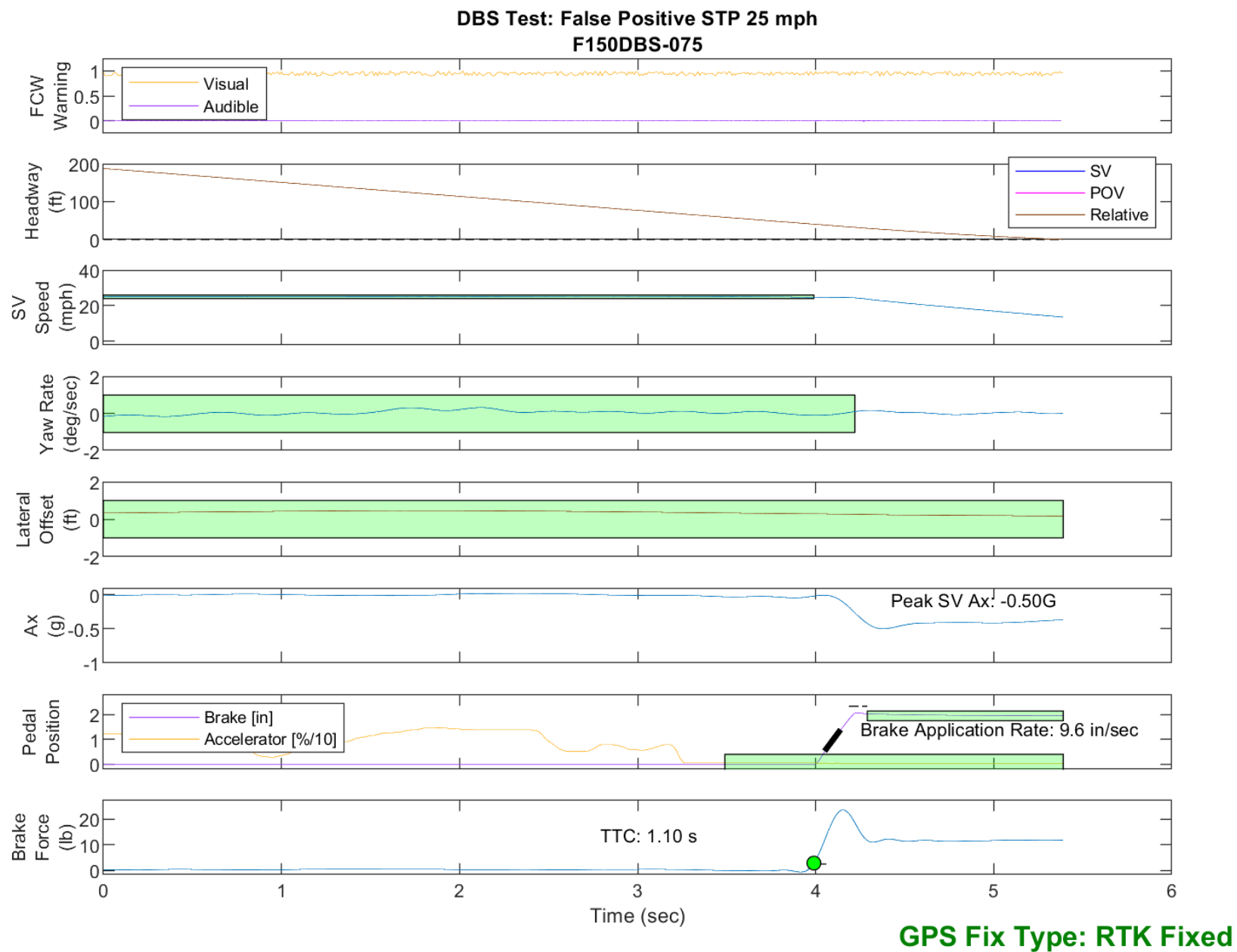


Figure E57. Time History for DBS Run 75, SV Encounters Steel Trench Plate, SV 25 mph

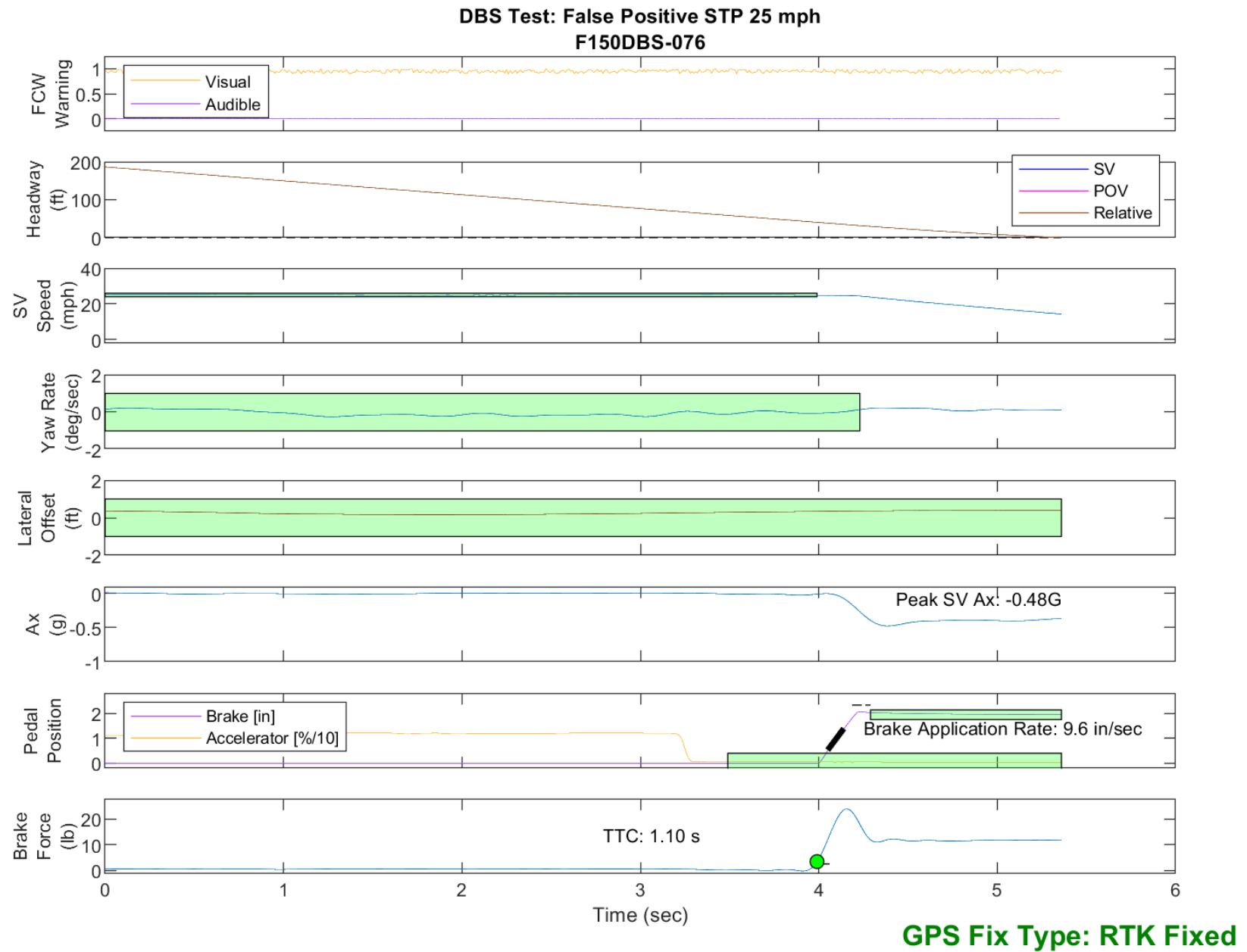


Figure E58. Time History for DBS Run 76, SV Encounters Steel Trench Plate, SV 25 mph

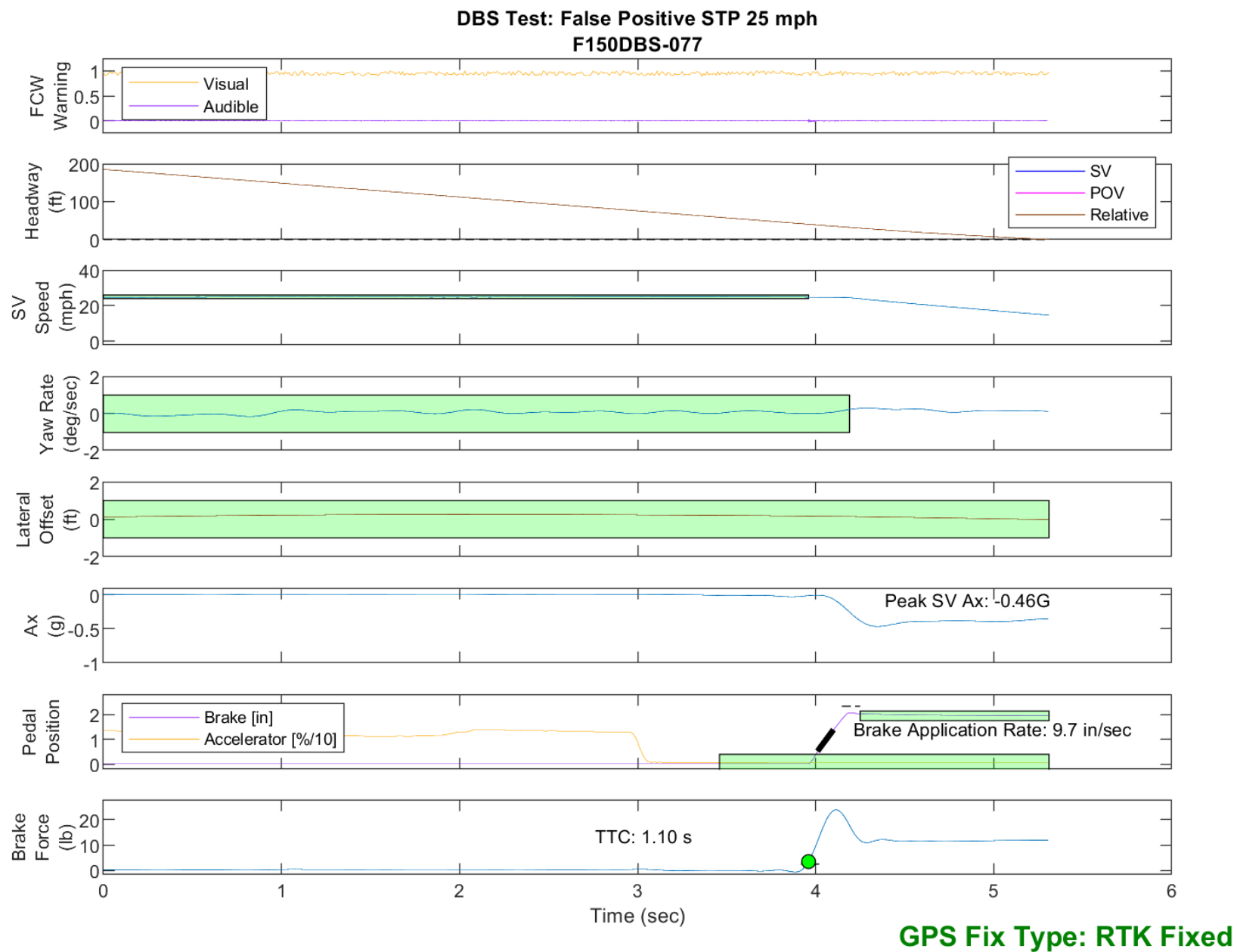


Figure E59. Time History for DBS Run 77, SV Encounters Steel Trench Plate, SV 25 mph

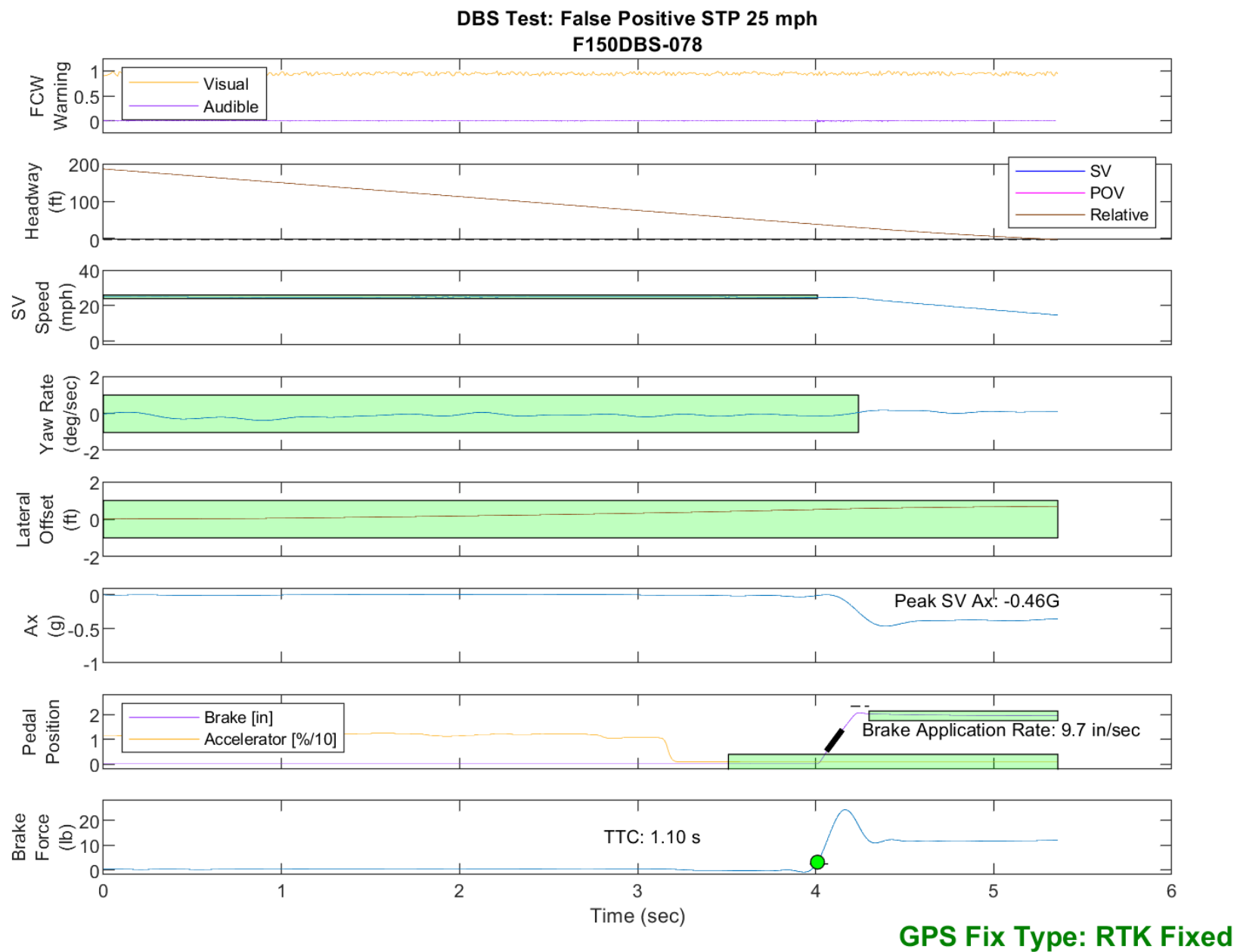


Figure E60. Time History for DBS Run 78, SV Encounters Steel Trench Plate, SV 25 mph

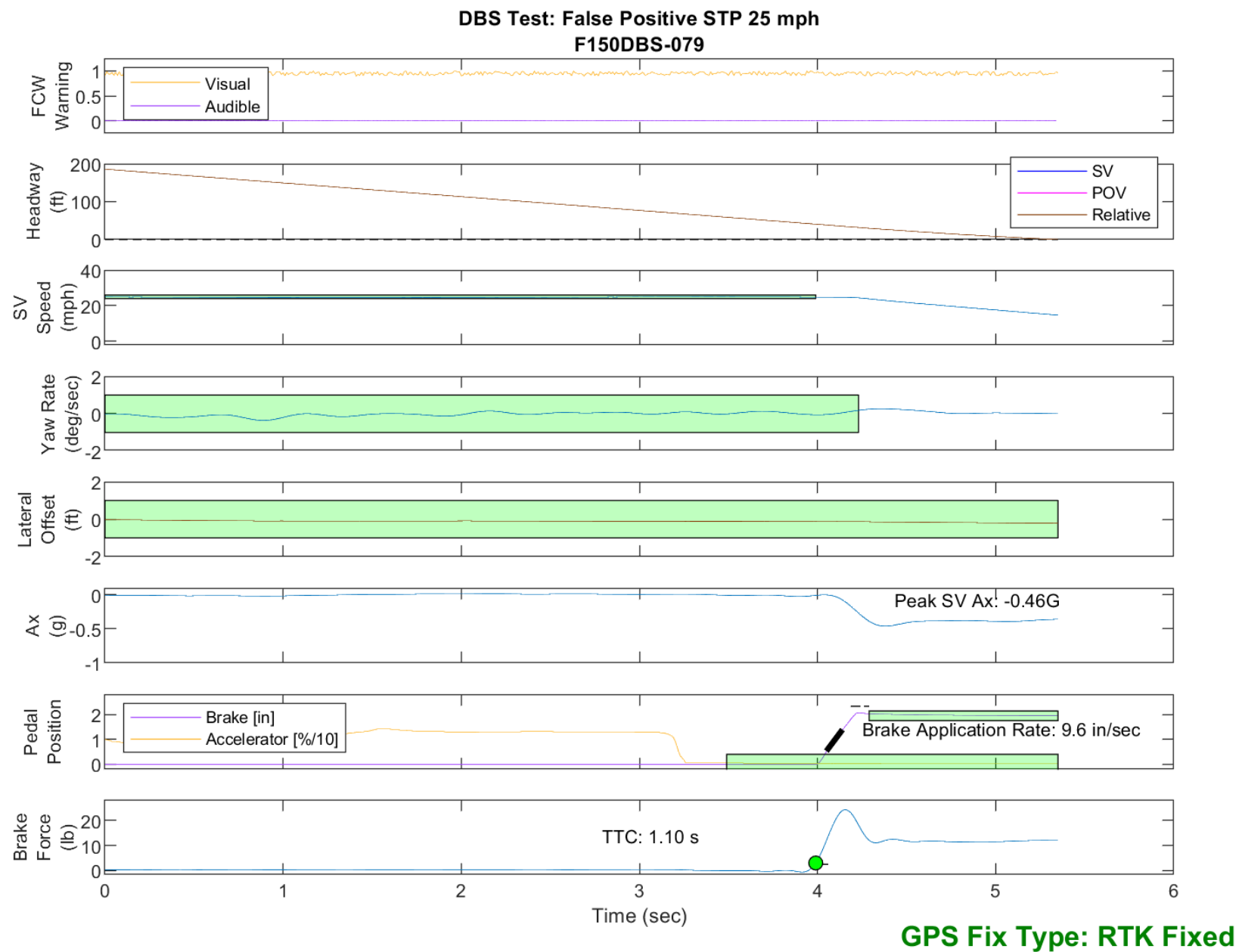


Figure E61. Time History for DBS Run 79, SV Encounters Steel Trench Plate, SV 25 mph

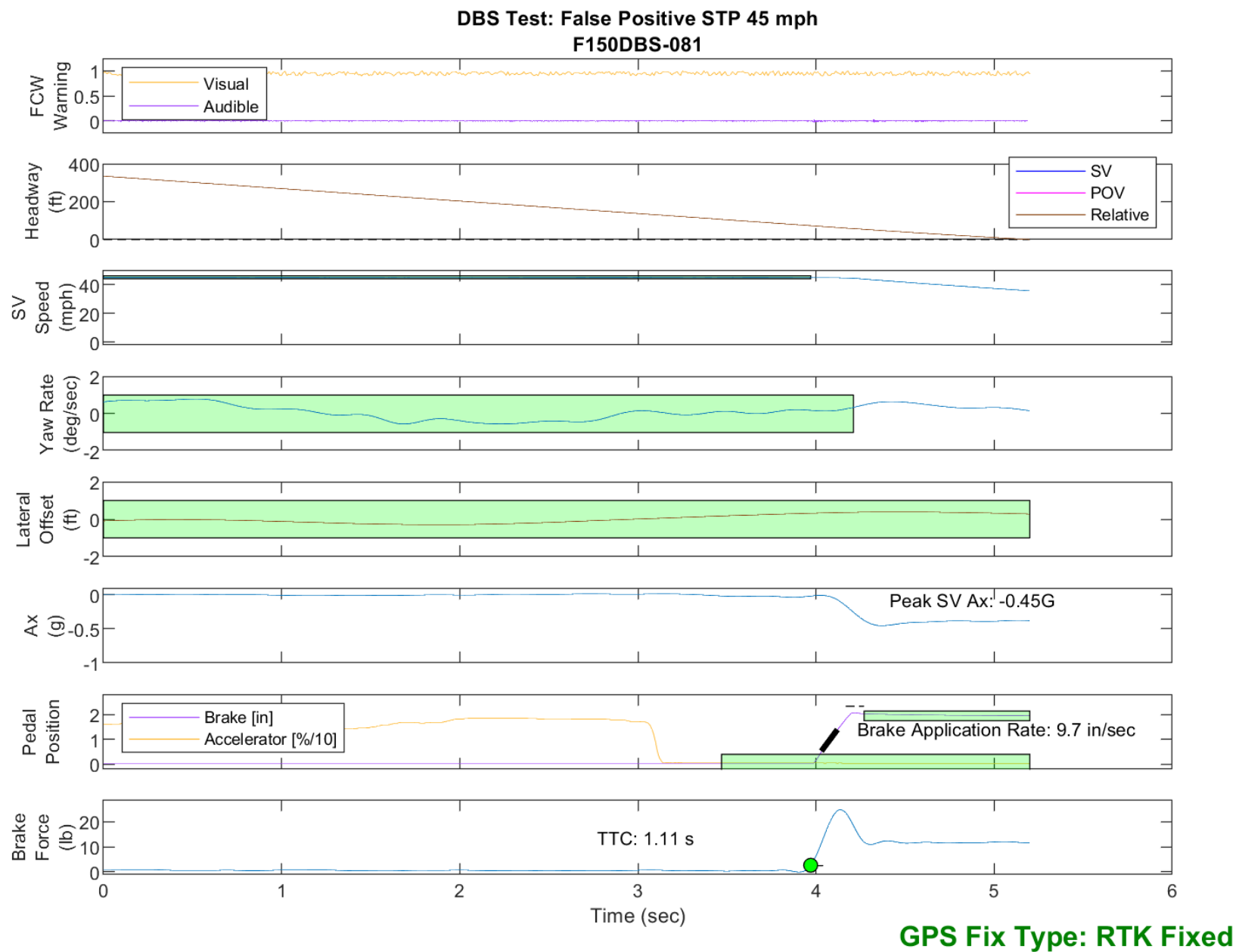


Figure E62. Time History for DBS Run 81, SV Encounters Steel Trench Plate, SV 45 mph

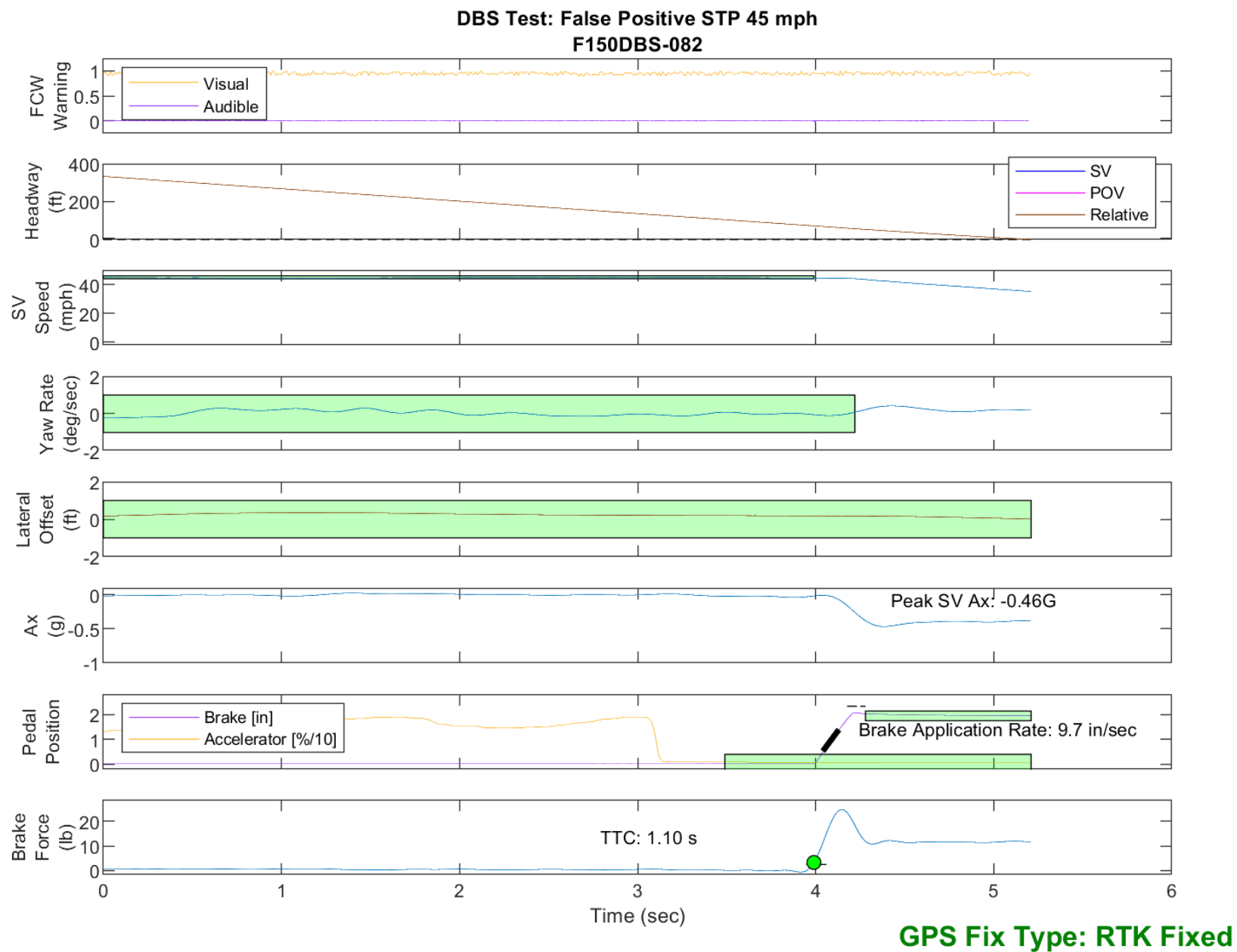


Figure E63. Time History for DBS Run 82, SV Encounters Steel Trench Plate, SV 45 mph

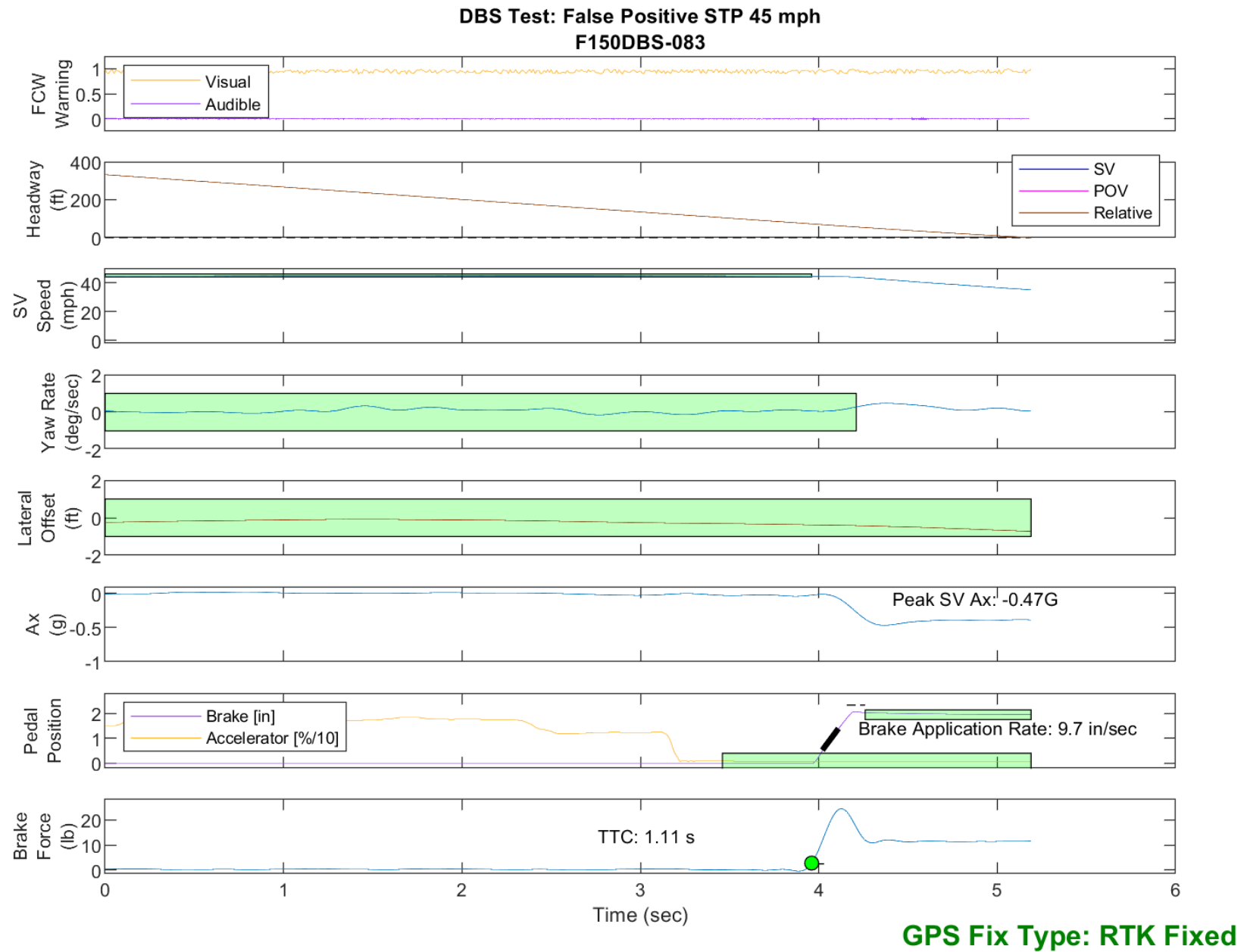


Figure E64. Time History for DBS Run 83, SV Encounters Steel Trench Plate, SV 45 mph

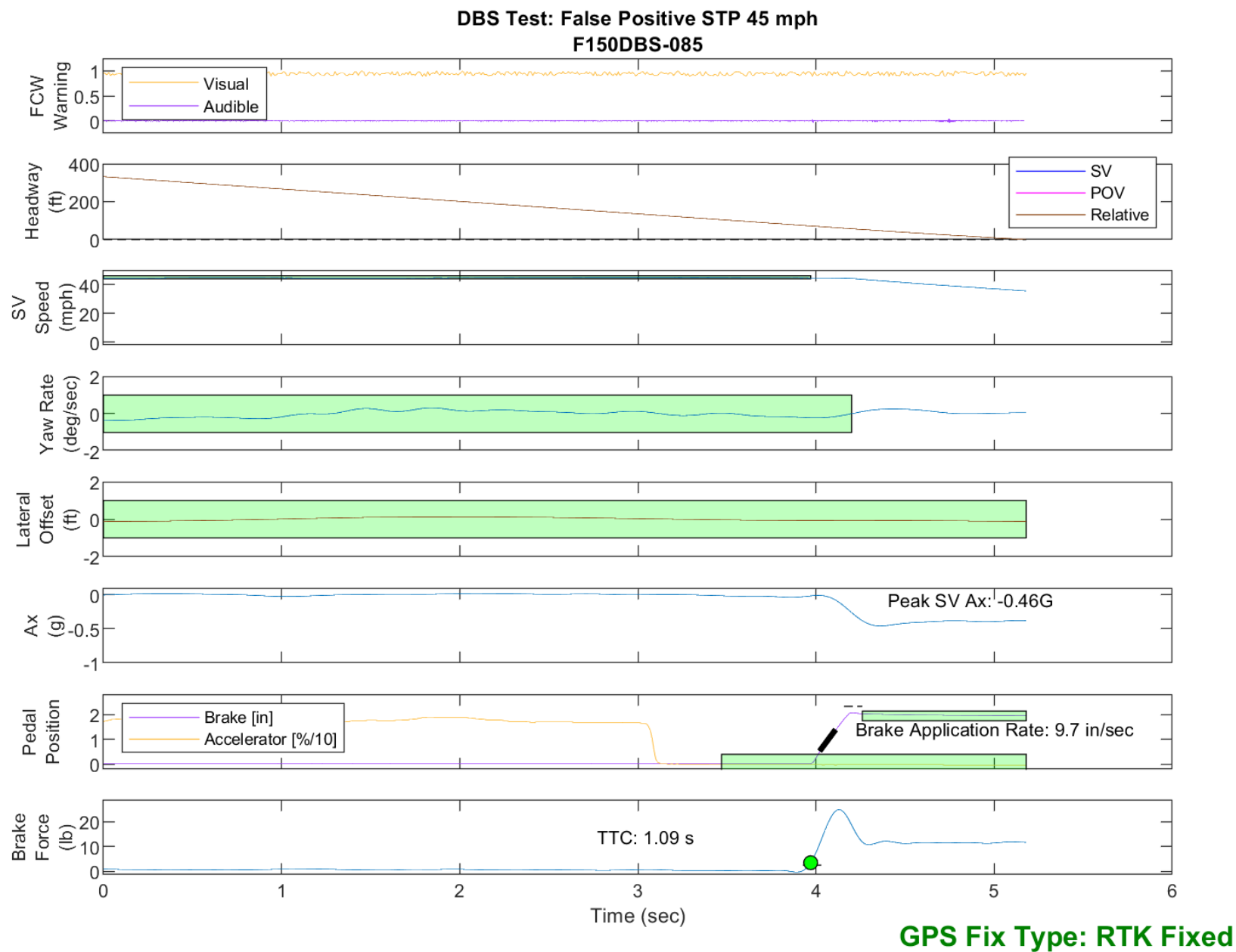


Figure E65. Time History for DBS Run 85, SV Encounters Steel Trench Plate, SV 45 mph

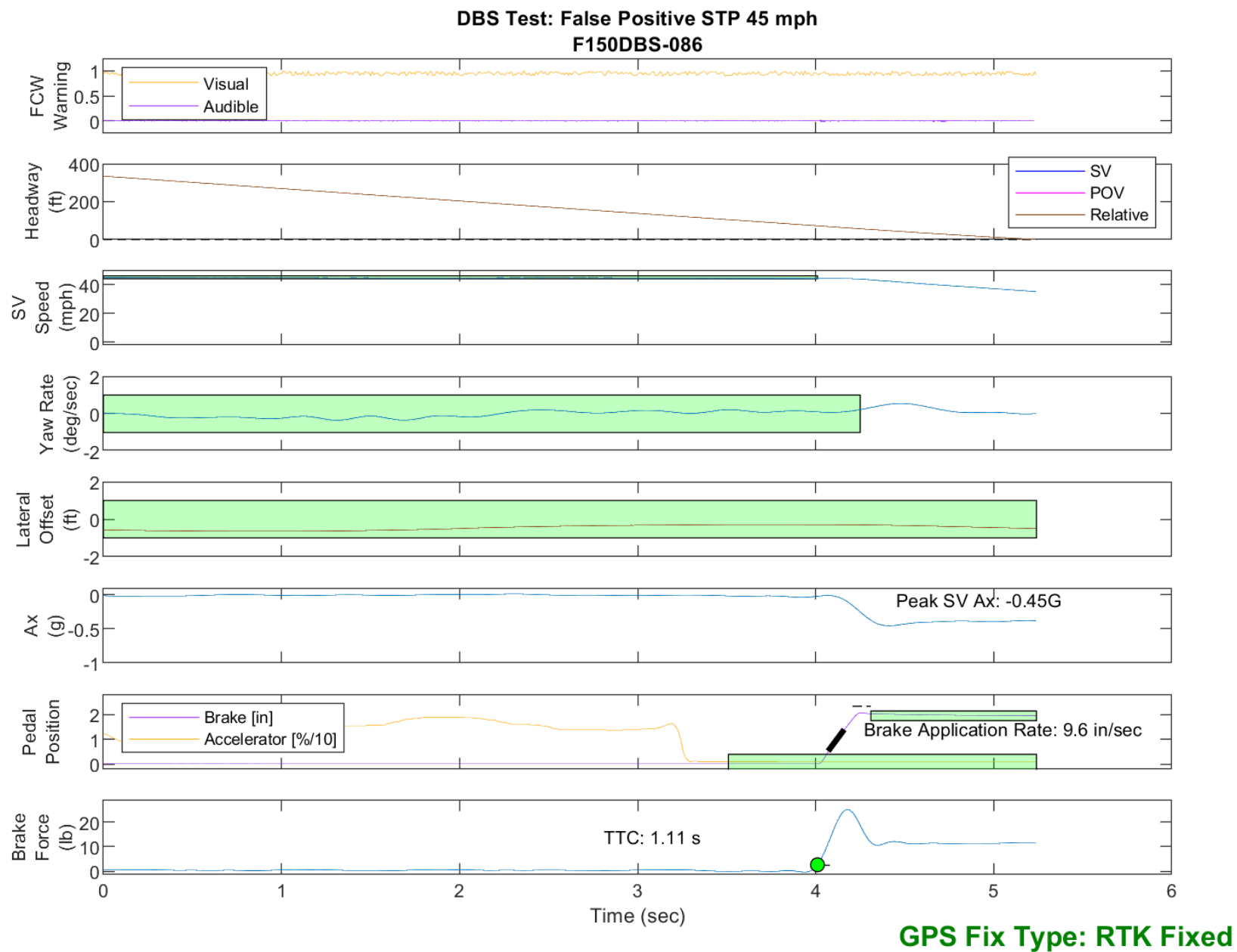


Figure E66. Time History for DBS Run 86, SV Encounters Steel Trench Plate, SV 45 mph

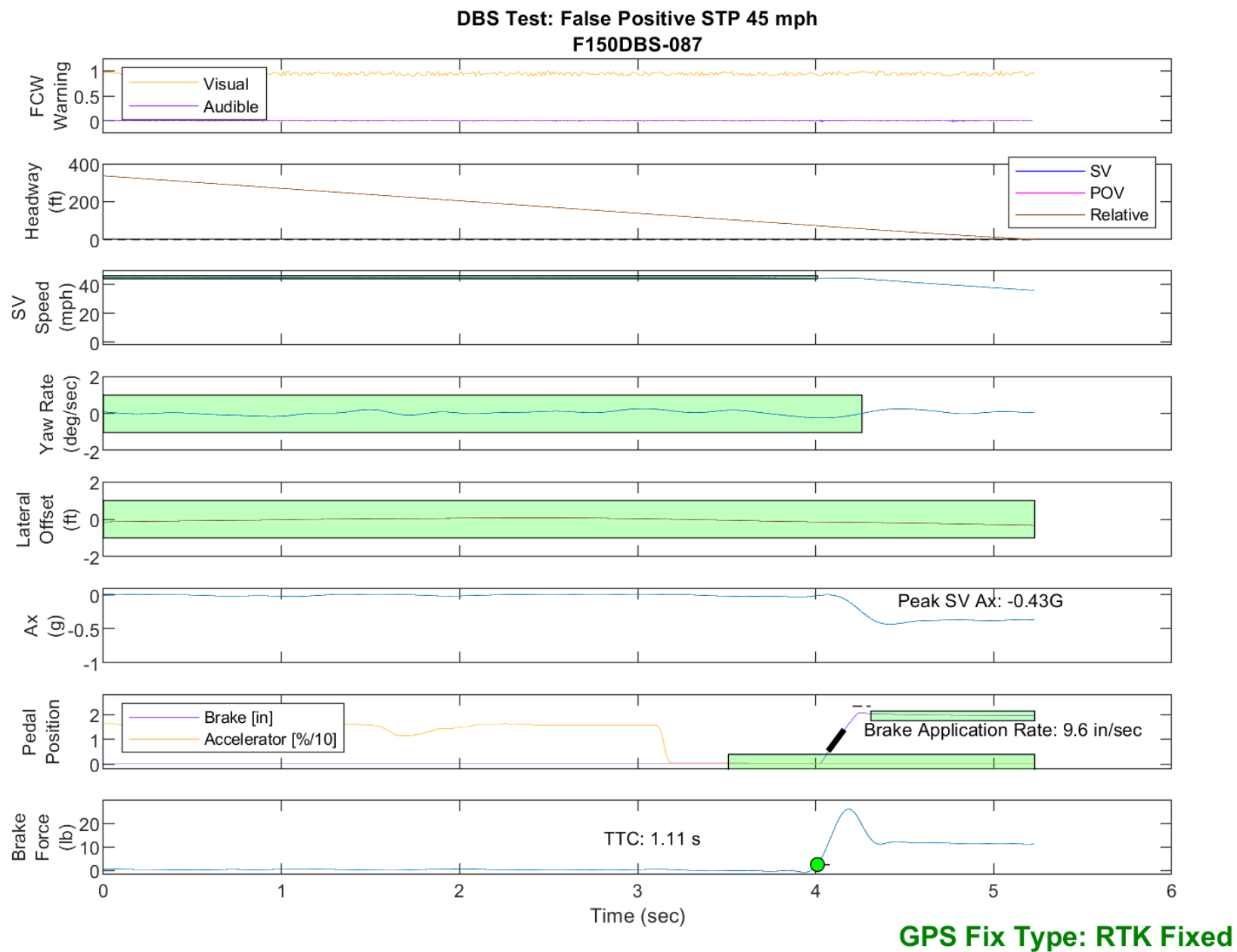


Figure E67. Time History for DBS Run 87, SV Encounters Steel Trench Plate, SV 45 mph

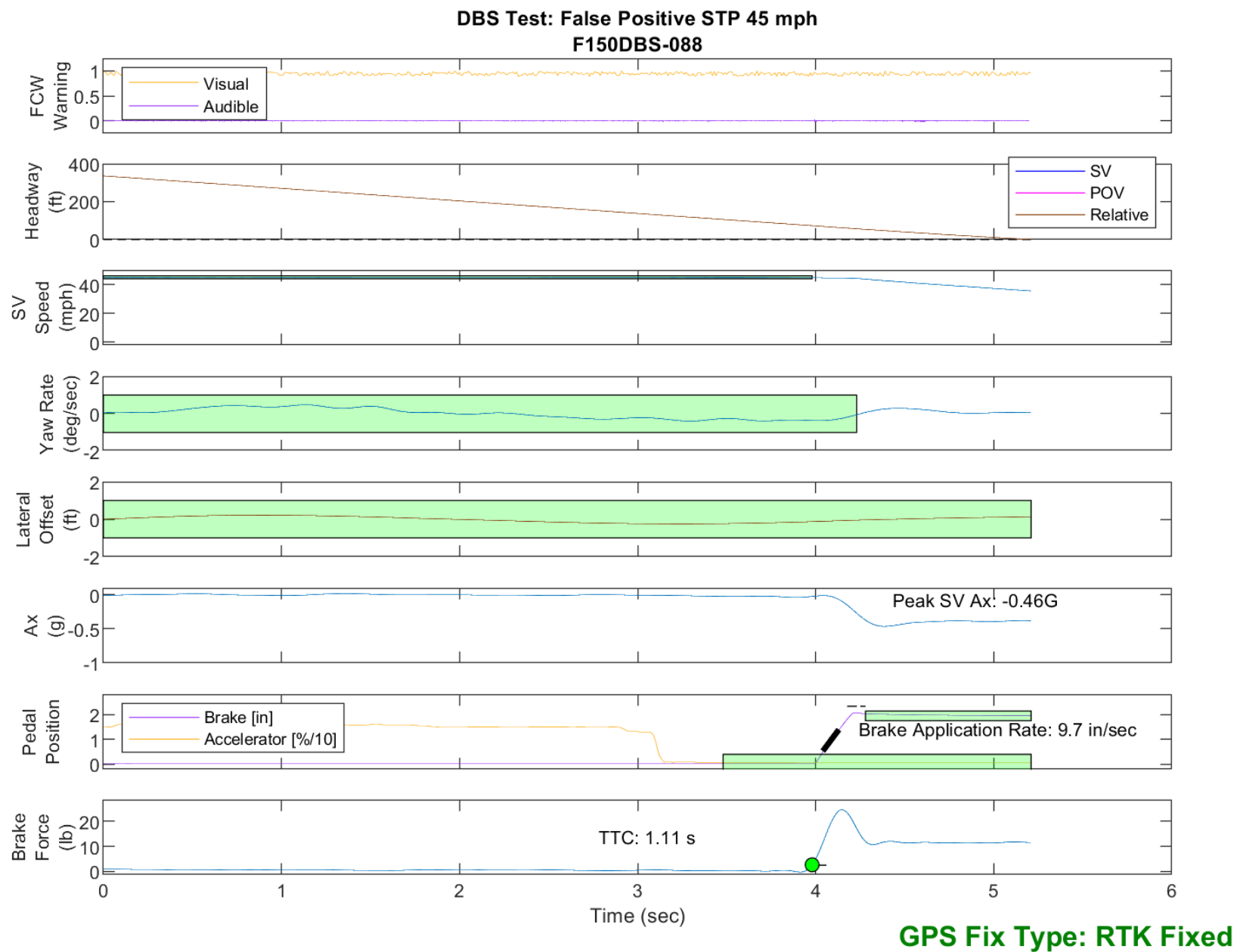


Figure E68. Time History for DBS Run 88, SV Encounters Steel Trench Plate, SV 45 mph

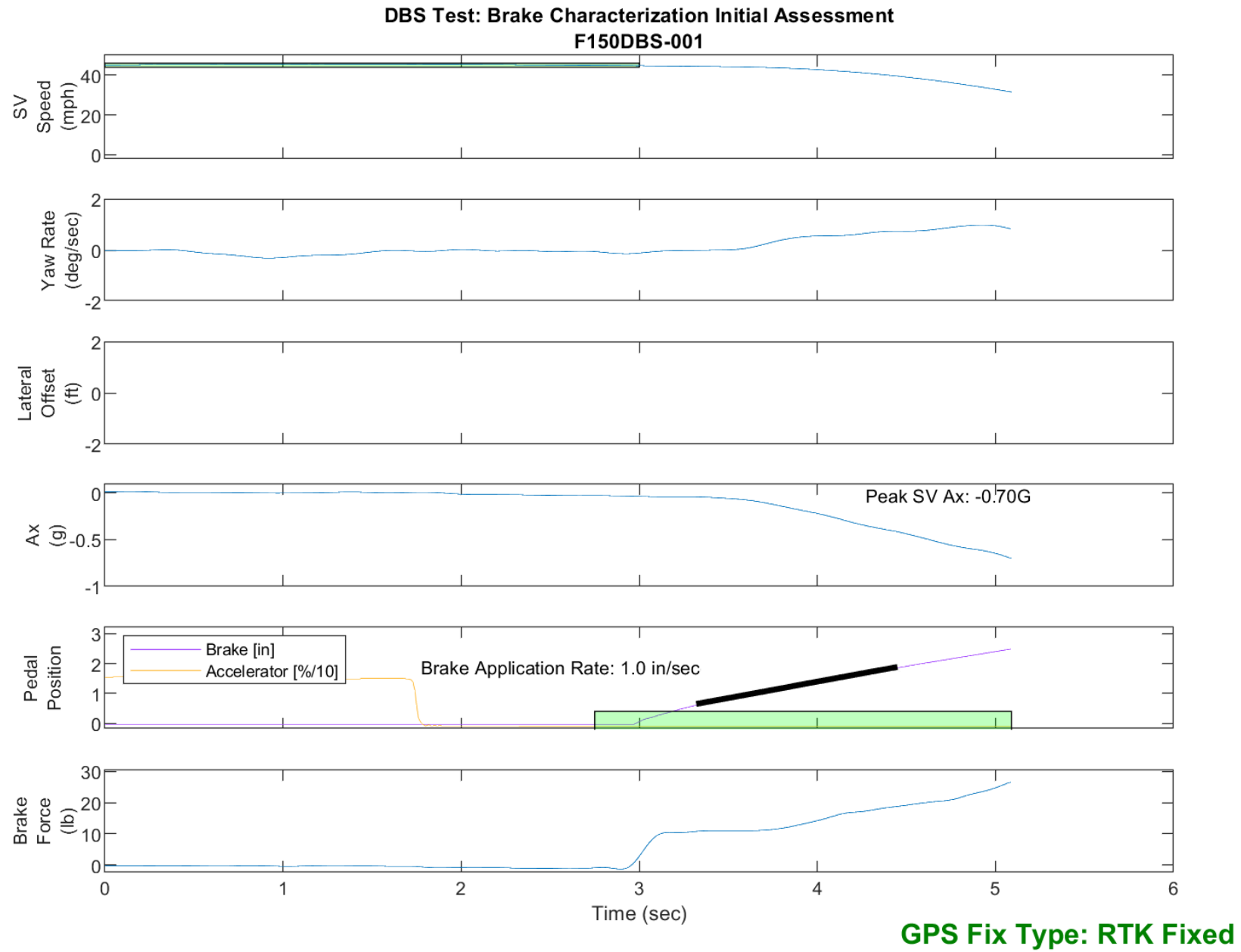


Figure E69. Time History for DBS Run 1, Brake Characterization Initial

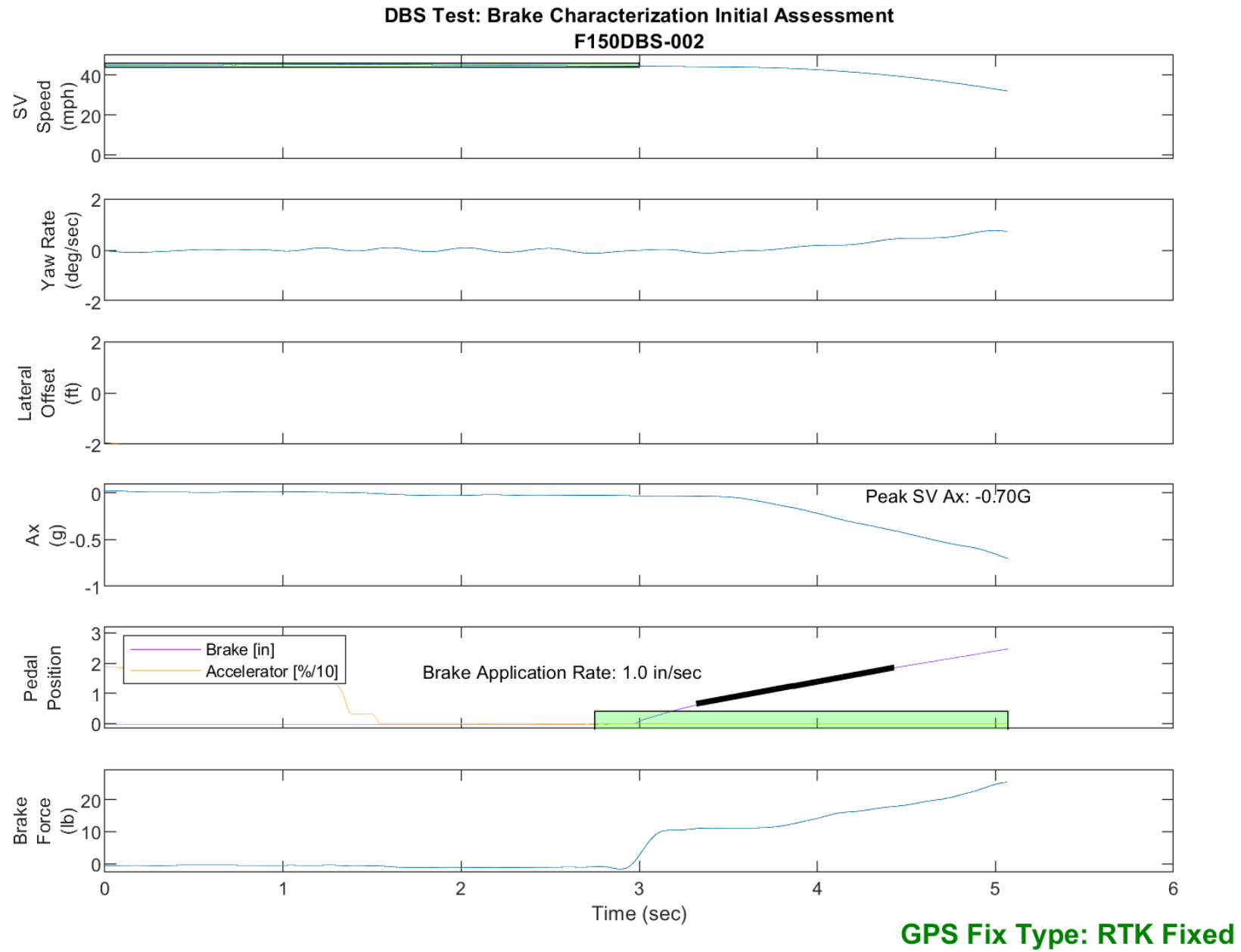


Figure E70. Time History for DBS Run 2, Brake Characterization Initial

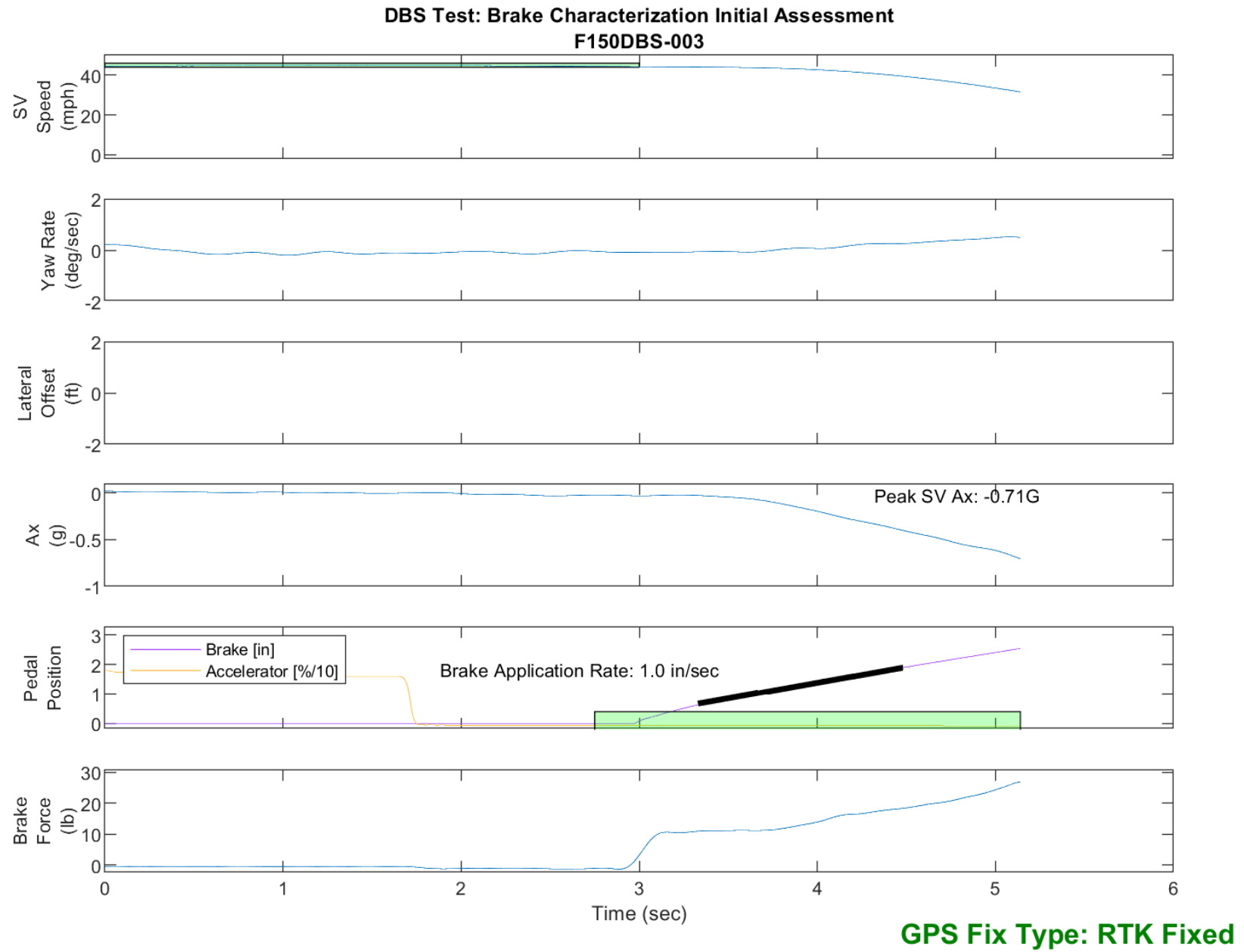


Figure E71. Time History for DBS Run 3, Brake Characterization Initial

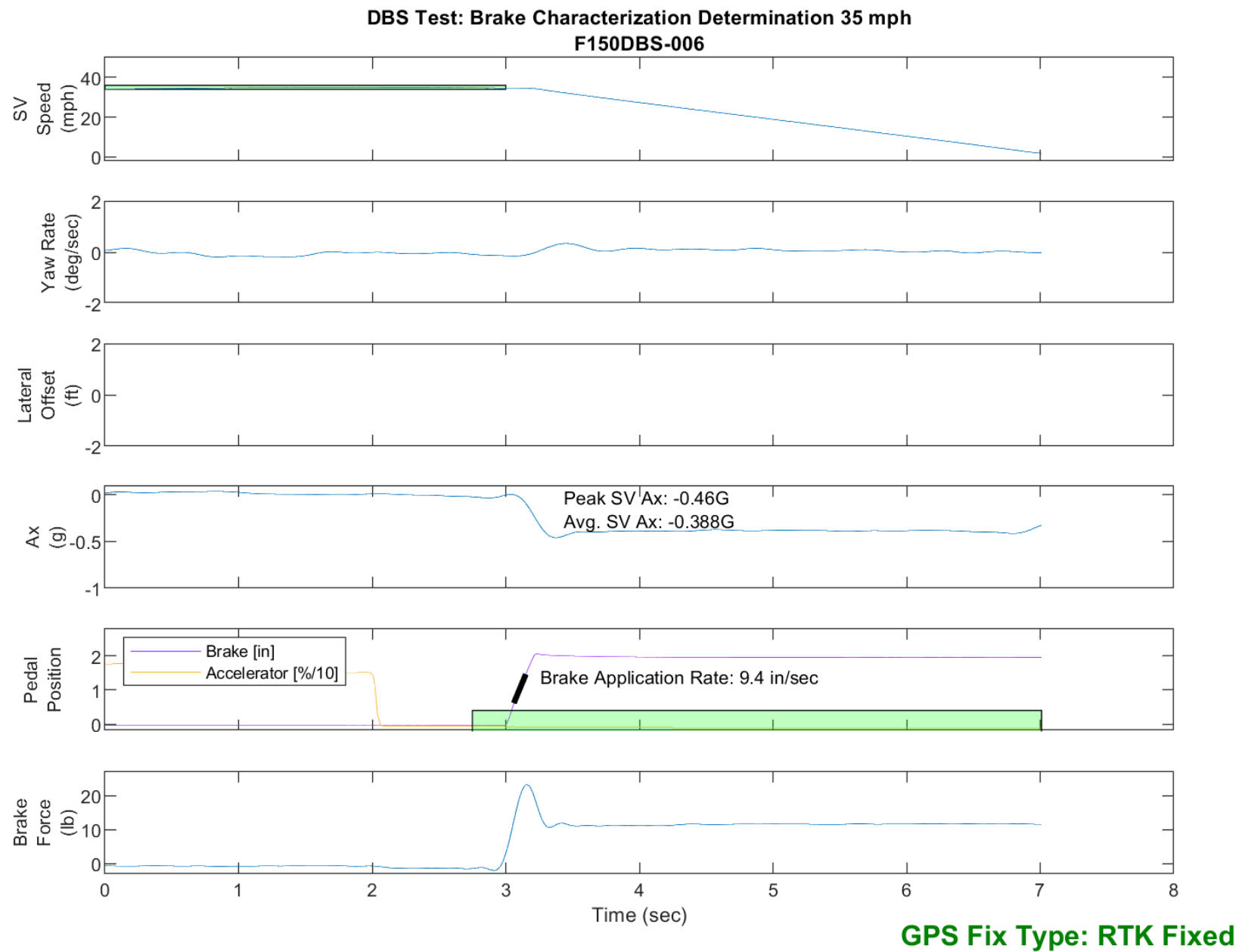


Figure E72. Time History for DBS Run 6, Brake Characterization Determination 35 mph

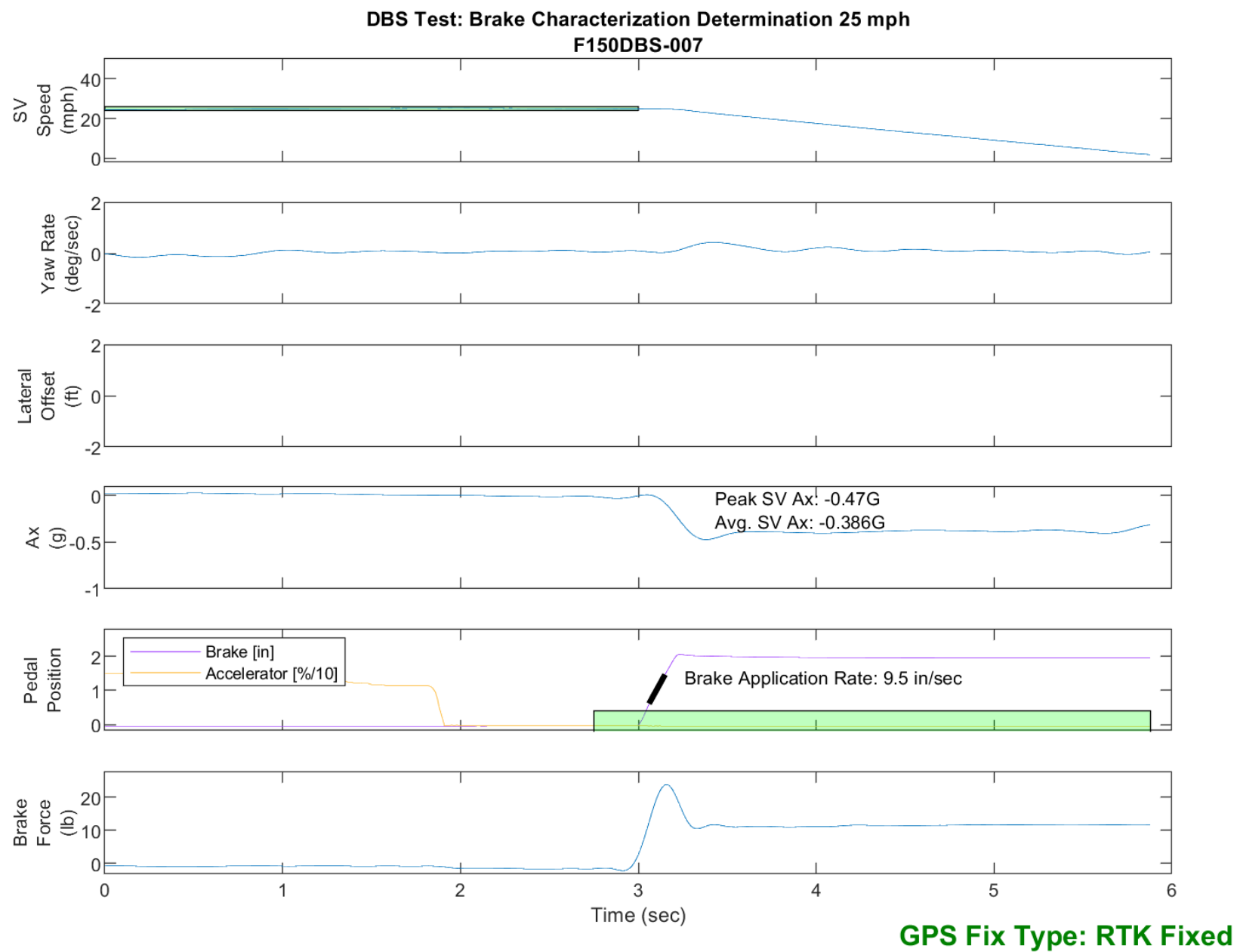


Figure E73. Time History for DBS Run 7, Brake Characterization Determination 25 mph

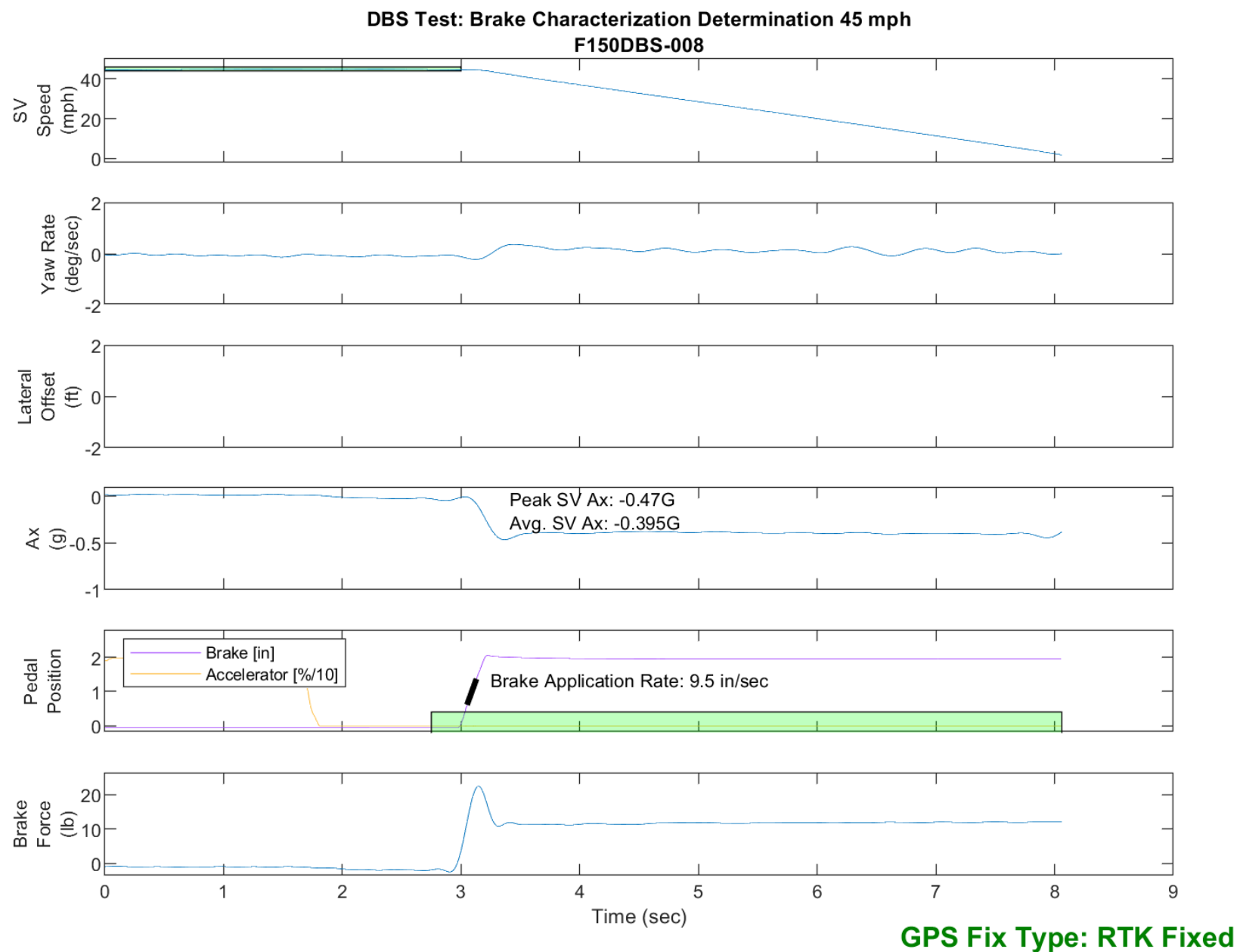


Figure E74. Time History for DBS Run 8, Brake Characterization Determination 45 mph