NEW CAR ASSESSMENT PROGRAM (NCAP) DYNAMIC ROLLOVER RESISTANCE TEST

KIA MOTORS CORPORATION

2021 Kia Seltos S FWD

TEST NUMBER: NCAP-DRI-RR-21-01

Final Report 12 June 2020



Prepared by:

Dynamic Research, Inc. 355 Van Ness Ave. #200 Torrance, CA 90501

Prepared for:

National Highway Traffic Safety Administration New Car Assessment Program 1200 New Jersey Avenue S.E. Washington, DC 20590 The United States Government assumes no liability for the contents of this report or use thereof. If trade or manufacturers' names or products are mentioned, it is only because they are considered essential to the object of the publication and should not be construed as an endorsement. The United States Government does not endorse products or manufacturers.

Dynamic Research, Inc. does not endorse or certify products of manufacturers. The manufacturer's name appears solely to identify the test article. Dynamic Research, Inc. assumes no liability for the report or use thereof. It is responsible for the facts and the accuracy of the data presented herein. This report does not constitute a standard, specification, or regulation.

Report Prepared by:

John Lenkeit, Program Manager Date: <u>12 June 2020</u>

Jonathan Robel, Test Engineer

			Te	chnical Report Docum	entation Page
1. Report No. NCAP-DRI-RR-21-01	2. Government	Accession No.	3.	Recipient's Catalog N	lo.
4. Title and Subtitle	•		5.	Report Date	
NCAP Dynamic Rollover Resistance			12 June 2020		
Maneuver (Fishhook) T		ia Seltos	6	Performing Organiza	tion Code
			0.	DRI	
S FWD					
7. Author(s)			8.	Performing Organiza	tion Report No.
John Lenkeit, Progra	am Manager			DRI-TM-20-90	
Jonathan Robel, Te	st Engineer				
9. Performing Organization Name			10.	Work Unit No. (TRAI	S)
Dynamic Research, Inc				Contract or Grant No	
355 Van Ness Ave. #20				DTNH22-14-D-(00332
	0				
Torrance, CA 90501			10		
12. Sponsoring Agency Name a	ind Address		13.	Type of Report and F	Period Covered
				Final Report	
National Highway Traffi	c Safety Admir	nistration		April 2020 to Ju	ne 2020
New Car Assessment F	Program			•	
1200 New Jersey Aven	•				
Washington, DC 20590					
			1/	Sponsoring Agency (Codo
			14.	Sponsoning Agency (Joue
				NRM-110	
				_	
15. Supplemental Notes					
16. Abstract					
An NCAP Dynamic Rollov	or Monouvor (Fishbook) T	oct	was conducted	on a 2021 Kia
Seltos S FWD at Dynam					
experience two-wheel lift.	The vehicle's s	teering angle	e at	0.3 g lateral acc	eleration at 50
mph was 24.6 degrees.					
17. Key Words		18. Distributio	n Sta	itement	
New Car Assessment F	Program	-		nis report are ava	ailable from:
	logiani	Copies	UI U	iis report are ave	
Rollover			-		D
		NHTSA	ιГе	chnical Referenc	e Division
		Nationa	tional Highway Traffic Safety		
	Admini			0 /	-
		New Jersey Avenue, SE			
			n, DC 20590		
	00 0		<u> </u>	-	00 Drie
19. Security Classif. (of this	20. Security Class		<u> </u>	Number of Pages	22. Price
19. Security Classif. (of this report) Unclassified	20. Security Class page) Unclassifie	if. (of this	<u> </u>	-	22. Price

Form DOT F 1700.7 (8-72)

Reproduction of completed page authorized

TABLE OF CONTENTS

			Pa	age
I.	INTF	RODUC	CTION	1
II.	VEH	IICLE F	PREPARATION	. 2
	A.	Test V	/ehicle	.2
	В.	Tires.		2
	C.	Vehicl	le Loading	.2
	D.	Steeri	ng Controller	5
	E.	Real-1	Time Controller and Data Acquisition	5
	F.	Equip	ment Weight	.5
	G.	Senso	ors	6
	Н.	Other	Vehicle Preparation	6
III.	TES	T PRO	CEDURES	. 9
	A.	Test F	Procedure Overview	. 9
	В.	Test C	Conditions 1	10
IV.	RES	ULTS.		13
APP	END	IX A	PhotographsA	-1
APP	END	IX B	Test Run LogB	-1
APP	END	IX C	Slowly Increasing Steer Test WorksheetC.	-1
APP	END	IX D	Time History PlotsD	-1

LIST OF FIGURES

		Page
1.	Nominal Position of Video Cameras for Fishhook Tests	8
2.	DRI-Minter Vehicle Dynamics Area	12

LIST OF TABLES

Page

1.	Test Vehicle Data	3
2.	Tire Information	4
3.	Vehicle Loading	4
	Weight of In-Cab Test equipment	
5.	Sensors	7
6.	Surface Friction	10
7.	Handwheel Angles	10
8.	Weather Conditions	11

Section I

INTRODUCTION

Beginning with the 2006 fiscal year, the National Highway Traffic Safety Administration (NHTSA) has engaged Dynamic Research, Inc. (DRI) of Torrance, CA to conduct dynamic rollover testing and gather data from that testing as part of NHTSA's New Car Assessment Program (NCAP).

The purpose of the testing reported herein was to determine if a typical 2021 Kia Seltos S FWD would experience tip-up, defined as simultaneous two-wheel lift of two inches or more at an entry speed of 50 mph or less in the Fishhook Procedure developed by NHTSA. This procedure may be found at www.regulations.gov, docket item NHTSA-2006-26555-0136.

The testing reported herein was accomplished under contract DTNH22-14-D-00332. The task order is entitled, "NCAP Dynamic Rollover Testing."

Section II VEHICLE PREPARATION

A. Test Vehicle

The test vehicle was new or in as-new condition, meaning the vehicle had been driven no more than 500 miles prior to the start of dynamic rollover testing. It was acquired through a commercial rental/leasing company. Details of the test vehicle are given in Table 1.

B. Tires

All tires used were new, and of the same make, model, size, and DOT specification of those installed on the vehicle when purchased new. Tire inflation pressures were in accordance with the recommendations indicated on each vehicle's identification placard. To further reduce the possibility of tire debeading, the tires were mounted to the rims without the use of tire mounting lubricant. Tire specifications are listed in Table 2.

C. Vehicle Loading

The multi-passenger load, described in the Fishhook Procedure, was used for all tests. The load and positioning of the load in the vehicle are listed in Table 3.

In addition to water dummies, the loading included instrumentation, a steering machine, and outriggers. Test vehicle bumper assemblies were removed for outrigger installation. The reduction in vehicle weight due to the removal of the bumpers was offset by the additional weight of the outriggers and their mounting system. The outrigger system typically outweighs the bumper assemblies.

General Data					
Model year, make, model	2021 Kia	Seltos S FV	/D		
VIN	KNDEU2A	KNDEU2AA0M705xxxx			
Vehicle type/Body style	MPV/SUV	/			
Number of doors	4				
Trim level	S FWD				
Seating positions	Front:	2 nd row	3 rd row	4 th row	5 th row
	2	3	0	0	0
Electronic stability control	Yes			I	1
4-Wheel ABS (Yes/No)	Yes				
Power steering (Yes/No)	Yes				
Major optional equipment					
Odometer at start of testing	15 miles				
	Drivetra	ain			
Engine cylinder arrangement	Inline 4				
Engine displacement	2 L				
Transmission type	IVT				
Drive arrangement 2WD (FWD)					
	Chass	is			
Track width	F: 61.5 in	(1562.1 mn	n), R: 61.75	in (1568.4	mm)
Wheelbase	104 in (2641.6 mm)				
Curb weight					
Certification Data from Vehicle's Label					
Vehicle manufactured by	Vehicle manufactured by KIA MOTORS CORPORATION				
Date of manufacture	02/20				
GVWR	/WR 3881 lb (1760 kg)				
GAWR Front	AWR Front 2293 lb (1040 kg)				
GAWR Rear	2062 lb (9	935 kg)			

Table 1. Test Vehicle Data

Tire Manufacturer	Kumho
Tire Model	Solus TA31+
Tire Size	Front: 215/55R17 Rear: 215/55R17
Load rating	Front: 94 Rear: 94
Speed rating	Front: V Rear: V
Treadwear grade	Front: 600 Rear: 600
Traction grade	Front: A Rear: A
Temperature grade	Front: A Rear: A
Location of "Recommended Tire Pressure" label	Driver's door jamb
Recommended cold tire pressure	Front: 35 psi, (240 kPa) Rear: 33 psi, (230 kPa)
First 8 digits of DOT code	Front: 1Y0 99YAY1 Rear: 1Y0 99YAY1

Table 2. Tire Information

Table 3. Vehicle Loading

Water dummy and other loading	Drained water from dummy to reduce to 150 lbs.3 water dummies in second row		
Water dummy weight	150 lb (68 kg)		
Fuel level	Full		
Weight as Tested			
Left front	1071 lb (485.8 kg)		
Right front	1022 lb (463.6 kg)		
Left rear	913 lb (414.1 kg)		
Right rear	875 lb (396.9 kg)		

D. Steering Controller

Precise controlled steering is accomplished using a steering machine designed and constructed by DRI. DRI has used its Automated Vehicle Controller (AVC) steering machine for many vehicle tests including FMVSS 126 tests. It can provide up to 65 ft-lb torque and rates over 1300 deg/sec. The integrated angle encoder has an unlimited range with a resolution of 0.045 degrees and an accuracy of ±0.045 degrees. The steering motor is controlled by a MicroAutoBox II from dSPACE, which also acts as the data acquisition system.

E. Real-Time Controller and Data Acquisition

Data acquisition is achieved using a MicroAutoBox II from dSPACE, which also serves as the real-time system for the steering controller. Data from the Oxford IMU, including Longitudinal, Lateral, and Vertical Acceleration, Roll, Yaw, and Pitch Rate, Forward and Lateral Velocity, Roll and Pitch Angle, are sent over Ethernet to the Micro AutoBox. The Oxford IMUs are calibrated per the manufacturer's recommended schedule (Table 5). The MicroAutoBox II specifications are:

Model: dSPACE Micro-Autobox II 1401/1513 Base Board SN 549068 I/O Board SN 588523

Two video cameras were used to record the Fishhook runs. They were positioned nominally as shown in Figure 1. The recorded videotapes were reviewed after the Fishhook runs to check for any two-wheel lift. If any two-wheel lift was observed, eight infrared distance-measuring sensors for measurement of wheel lift (two sensors at each wheel) were then mounted for use in subsequent confirmation Fishhook tests.

F. Equipment Weight

Table 4 lists the equipment and associated weights outlined in the NHTSA Laboratory Test Procedure for Dynamic Rollover and the equipment at DRI used for this specific test program. The equipment used at DRI for this test program differs slightly from the equipment that was previously used by NHTSA for rollover testing. Because DRI's equipment is lighter than NHTSA's equipment, DRI uses ballast to maintain a consistent weight and weight distribution in the vehicle.

Equipment	Location	Equipment Weight (Ib)	
		NHTSA*	DRI
Data Acquisition System	Front passenger seat	58	
Steering Machine	Handwheel	31	31
Steering Machine Electronics Box	Passenger row foot well behind the front passenger seat. If vehicle does not have a rear passenger row foot well, the Electronics Box should be placed in the front passenger seat foot well.	39	
MABX, and laptop	Front passenger seat		21
Motor control and power supply	Front passenger footwell		26
Ballast	Front passenger footwell		50
	Total	128	128

Table 4. Weight of In-Cab Test Equipment

* Table A.1 from US DOT NHTSA - Laboratory Test Procedure for Dynamic Rollover - The Fishhook Maneuver Test Procedure - New Car Assessment Program (NCAP) - March 2013

G. Sensors

A list of the sensors is given in Table 5.

H. Other Vehicle Preparation

In addition to installation and preparation discussed above, the test vehicle was prepared as follows:

- Front and rear bumpers were removed
- Outrigger mounts were installed in the bumper locations and titanium outriggers were fastened to these mounts
- Airbags were removed or otherwise disabled
- Photographs of the vehicle tested are given in Appendix A.

Table 5. Sensors

Measured Variable	Sensor	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Vehicle Tire Pressure	Tire Pressure Gauge	0-100 psi 0-690 kPa	0.01 psi 6.89 kPa	< 1% error between 20 and 100 psi	Omega DPG8001	17042707002	By: DRI Date: 7/3/2019 Due: 7/3/2020
Vehicle Total,	Platform Scales (Minter)	1200 lb/platform 5338 N/platform	1 lb 4.4 N	0.5% of applied load	Intercomp SWI	1110M206352	By: DRI Date: 1/6/2020 Due: 1/6/2021
Wheel, and Axle Load	Platform Scales (Torrance)	1200 lb/platform 5338 N/platform	1 lb 4.4 N	0.5% of applied load	Intercomp SW500	0828MA19001	By: DRI Date: 9/12/2019 Due: 9/12/2020
Handwheel Angle	Steering Angle Encoder (Automated Steering Controller)	±800 deg	0.045 deg	±0.045 deg	DRI Automatic Vehicle Controller using dSPACE Micro- Autobox II	NA	Verified by DRI at installation ¹
Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate, Forward and Lateral Velocity, Roll and Pitch Angle	Multi-Axis Inertial Sensing System	Accels ± 5 g, Angular Rate ±300 deg/s, Angle >45 deg, Velocity >200 km/h	Accels .001 g, Angular Rate 0.01 deg/s, Angle 0.05 deg, Velocity 0.1 km/h	Accels .001g, Angular Rate 0.01 deg/s, Angle 0.05 deg, Velocity 0.1 km/h	Oxford xNav 550	015360	By: Oxford Technical Solutions Date: 2/10/2020 Due: 2/10/2022

¹The steering encoder is checked prior to beginning tests to verify that there are no faults. The steering controller is installed in the vehicle and the steering wheel is turned through two complete revolutions while recording data. The data are then reviewed for any dropouts or other nonlinearities that would indicate dust intrusion or faulty sectors.

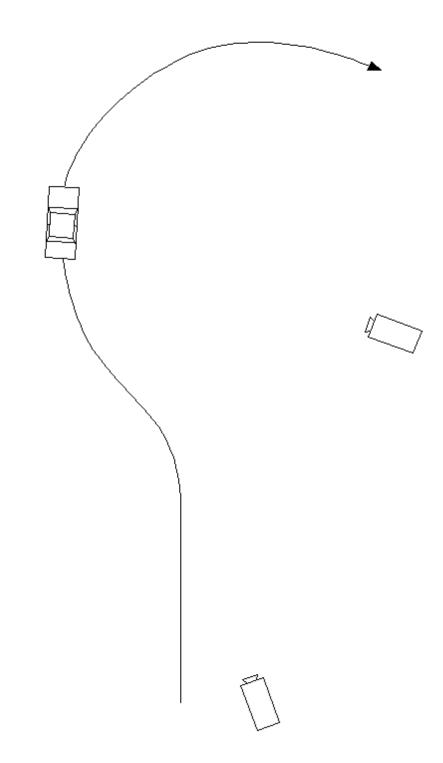


Figure 1. Nominal Position of Video Cameras for Fishhook Tests

Section III TEST PROCEDURES

This section includes a general overview of the test procedures and details of the particular test.

A. Test Procedure Overview

This test was conducted in accordance with NHTSA's NCAP Rollover Resistance Test Procedure (Fishhook) as described in the Federal Register (68 FR 59250). Detailed descriptions of the test procedure, pass/fail criteria, and data acquisition specifications may be found at docket NHTSA-2001-9663.

There are two major components of the test procedure, the Slowly Increasing Steer (SIS) pre-test and the Fishhook test.

The Slowly Increasing Steer (SIS) maneuver was used to characterize the steady state lateral dynamics of each vehicle, and is based on the "Constant Speed, Variable Steer" test defined in SAE J266. The maneuver is used to determine the handwheel angle that produces a lateral acceleration of 0.3 g at 50 mph. This handwheel angle is then used to determine the magnitude of steering to be used for the NHTSA Fishhook maneuver.

SIS tests were performed at a constant speed of 50 mph. Handwheel angle was input at a rate of 13.5 deg/sec, from 0 to an angle that provided at least 0.55 g. Three tests were conducted in each direction, and the data for the six runs were averaged to obtain the handwheel angle that produced 0.3 g at 50 mph.

The Fishhook test is a programmed steering maneuver that is implemented via the steering controller. The vehicle was initially steered in one direction and then the steering was reversed. The timing, magnitude, and rate of the steering were prescribed by the Fishhook Procedure.

To begin the maneuver, the vehicle was driven in a straight line at a speed slightly greater than the desired entrance speed. The driver then released the throttle. When the vehicle was at the target speed, the steering controller automatically initiated the steering maneuver. Following completion of the steering reversal, the handwheel position was maintained for three seconds and then returned to zero angle in 1 second.

The tests were conducted in both left-right and right-left directions. The "Default" test series used a handwheel angle equal to 6.5 times the handwheel angle that produced 0.3 g at 50 mph in the SIS tests, and initial vehicle speeds beginning at 35 mph and concluding up to 50 mph (if no two-wheel lift occurs). Supplemental tests were also done, as specified in the Fishhook Procedure.

B. Test Conditions

1. TEST SURFACE

The tests were conducted on the Vehicle Dynamics Area at DRI's Minter Field facility, located near Bakersfield, California, on 4/21/2020. The VDA has a smooth, flat (slope less than 0.5% throughout) asphaltic concrete surface. Its dimensions are as shown in Figure 2. It was built in the spring of 2005.

VDA surface friction measurements were accomplished using the DRI Mobile Tire Tester. Three runs were done, one at each of three previously determined locations. Each run provided for a minimum of 3 seconds of tire friction at constant normal load, slip angle, and speed in a free rolling condition. The test was accomplished using an ASTM E1136 tire with an inflation pressure of 35 (\pm 0.5) psi at a test speed of 40 (\pm 0.5) mph. The net slip angle of the test tire for each test run was 7.5 deg. The test tire was no older than 6 months from the date of manufacture. The surface friction measurement results are shown in Table 6.

Table 6. Surface Friction

Date of surface friction measurements	4/22/2020
Average normalized lateral force	0.786

2. FISHHOOK HANDWHEEL ANGLES

The 0.3 g handwheel angle obtained from the SIS tests and the handwheel angles used in the Fishhook tests are shown in Table 7.

Table 7. Handwheel Angles

0.3 g handwheel angle (from SIS tests at 50 mph)	24.6°
5.5 scalar handwheel angle for Fishhook Test	135°
6.5 scalar handwheel angle for Fishhook Test	160°

3. WEATHER CONDITIONS

The weather conditions, recorded at the end of testing, are shown in Table 8.

Table 8.	Weather	Conditions
----------	---------	------------

Ambient temperature	70° F (21.1° C)
Wind Speed	6.9 mph (2.7 m/s)
Wind Direction	NW

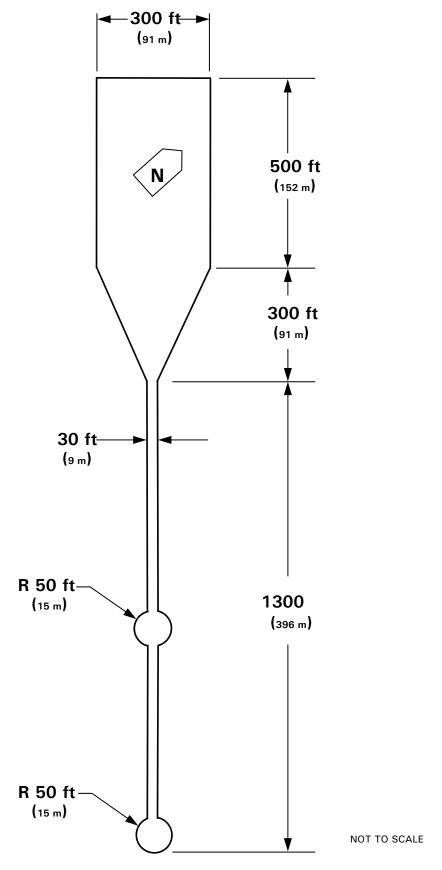


Figure 2. DRI-Minter Vehicle Dynamics Area

Section IV

RESULTS

The test run log is given in Appendix B. The Slowly Increasing Steer Test Worksheet is given in Appendix C. Appendix D contains time history plots for the 50 mph runs and any runs which resulted in two-wheel lift. There was no two-wheel lift at any test condition for the 2021 Kia Seltos S FWD.

APPENDIX A

Photographs

LIST OF FIGURES

		Page
A1.	Window Sticker	A-3
A2.	Front View, Test Vehicle as Delivered	A-4
A3.	Rear View, Test Vehicle as Delivered	A-5
A4.	Front View, Test Vehicle in Test Condition	A-6
A5.	Rear View, Test Vehicle in Test Condition	A-7
A6.	Certification Label	A-8
A7.	Tire Placard	A-9
A8.	Instrumentation in Test Vehicle	. A-10
A9.	Steering Controller and Computer	. A-11
A10.	Ballast Condition	. A-12

2021 SELTOS S FWD MODELIOPT.CODE: K2232 / 012 EXTERIOR COLOR: DARK OCEAN BLUE / WHITE ROOF INTERIOR COLOR: BLACK VEHICLE ID NUMBER: KNDEUZAA0M705 PORT OF ENTRY: HUENEME	Sold To: Ship To:		#1 MASS MARKET BRAND IN J.D. POWER INITIAL QUALITY, 5 YEARS IN A ROW. BIVE IT EVERYTHING ()	KIA
STANDARD FEATURES MECHANICAL 2.0L 4-Cylinder Engine w/ 145 Horsepower Intelligent Variable Transmission (IVT) Drive Mode Select (DMS) Idle Stop and Go System (ISG) KIA DRIVEWISE DRIVER-ASSIST TECHNOLOGY Forward Collision-Avoidance Assist-Ped (FCA-Ped) Lane Following Assist (LFA) Lane Departure Warning (LDW) Driver Attention Warning (DAW) High Beam Assist (HBA)	MANUFACTURER'S SUGGESTED RETAIL PRICE ► ADDITIONAL INSTALLED EQUIPMENT: (In addition to or in place of standard features) Dark Ocean Blue / White Roof Paint Glossy Black Door Garnish Package Carpeted Floor Mats Cargo Net, Floor Style Cargo Tray	\$21,990.00 \$345.00 Included \$130.00 \$50.00 \$80.00	Fuel Economy and Environment Fuel Economy MPG SMALL SUVS range from 18 to 120 MPG The best vehicle rates 141 MPG 29 34 highway 3.2 gallons per 100 miles	You Save \$1,000 in fuel costs over 5 years compared to the average new vehicle.
SAFETY Dual Front Advanced Airbags Dual Front Seat-Mounted Side & Full-Length Curtain Airbags Electronic Stability Control (ESC) Downhill Brake/Hill-start Assist Control (DBC/HAC) INTERIOR, COMFORT & CONVENIENCE 8' Touchscreen w/ Android Auto & Apple CarPlay Rear Camera with Dynamic Guidelines USB Multimedia Port Bluetooth* Wireless Technology Remote Keyless Entry Steering Wheel Controls (Bluetooth/Audio/Cruise) Till & Telescopic Steering Column 60/40 Split-Folding and Reclining Rear Seats Power Windows, Door Locks & Outside Mirrors Power Windows, Vintwirs One-Touch Auto-Down Combination Sofino Leatherette and Cloth Seat Trim			Annual fuel COSt \$1,3000 Fuel Economy & Greenhouse Gas Rating La	10 Boar Bo
Leather-Wrapped Steering Wheel and Shift Knob Sliding Front Ctr. Armrest, Rear Seat Ctr. Armrest Dual-Level Cargo Floor EXTERIOR 17" Alloy Wheels Roof Rails Digraded Grille with Integrated LED Light Bar LED Daytime Running Lights and Tail Lights Fog Lamps Power, Heated Outside Mirrors w/ LED Turn Signal Indicators Compact Spare Tire	MSRP INCLUDING OPTIONS	\$ 22,595.00	Based on the combined rating of frontal, side and rollover. Should ONLY be compared to other vehicles of similar size and weight. Frontal Driver Not Rated Crash Passenger Not Rated Based on the risk of injury in a frontal impact. Should ONLY be compared to other vehicles of similar size and weight. Side Front seat Not Rated Crash Rear seat Not Rated Star ratings based on the risk of injury in a side impact.	LINE U.S./CANADIA PARTS CONTENT: C MAJOR SOURCES OF FOREIGN PARTS KORE/ OTHEF NOTE: PARTS CONTENT DC NOT INCLUDE FINAL ASSE DISTRIBUTION, OR OTHER NON-PARTS COSTS.
WARRANTY 10 Year/100,000 Mile Limited Powertrain Warranty 5 Year/60,000 Mile Limited Basic Warranty 5 Year/60,000 Mile Roadside Assistance	INLAND FREIGHT AND HANDLING	\$ 1,120.00 \$ 23,715.00	Rollover Not Rated Star ratings based on the risk of rollover in a single-vehicle crash. Star ratings range from 1 to 5 stars (******) with 5 being the higher Source: National Highway Traffic Satety Administration (******). Www.safercar.gov or 1-888-327-4236 Manufacturer's suggested relations in head in state installed options and scesseries are not included in the manufacturer's suggested relation price.	ENGINE: K

Figure A1. Window Sticker



Figure A2. Front View, Test Vehicle as Delivered



Figure A3. Rear View, Test Vehicle as Delivered



Figure A4. Front View, Test Vehicle in Test Condition



Figure A5. Rear View, Test Vehicle in Test Condition



Figure A6. Certification Label

	T RENSEIGNE	TIRE AND LO MENTS SUF					ENT	
	SEATING CAR NOMBRE DE		TOTAL 5	an arrented	ONT 2	REAR ARRIÈRE	3	
The combined the poids total des d	weight of occupant occupants et du cha	s and cargo she argement ne do	ould never exco bit jamais dépas	eed sser	340	g or g ou 860	lbs. Ib.	
TIRE PNEU	SIZE DIMENSIONS	PRESS	e pressure Sion des S à froid	14	MAN ADD	OWNER'S UAL FOR		
FRONT	215/55R17	240ki	Pa, 35psi			RMATION E MANUE		0
REAR ARRIÈRE	215/55R17	230kl	Pa, 33psi		DEL			30
SPARE DE SECOURS	T125/80D16	420kl	Pa, 60psi		and the second se	IGNEMEN	and the second se	

Figure A7. Tire Placard



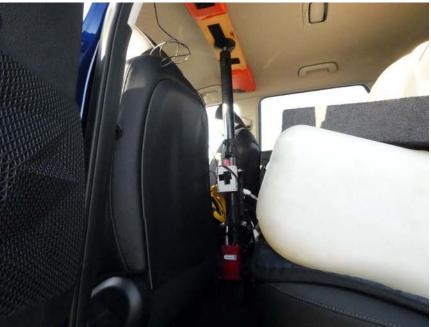


Figure A8. Instrumentation in Test Vehicle



Figure A9. Steering Controller and Computer



Figure A10. Ballast Condition

APPENDIX B

Test Run Log

Vehicle: 2021 Kia Seltos S FWD

Run Number	Test Type	Speed Handwheel (mph) Angle (deg)		Dir. of First Steer	2 Wheel Lift	Notes
1	Tire Warm-Up	35	60	NA	NA	
2	"	"	"	"	"	
3	"	"	"	"	"	
4	"	"	"	"	"	
5	2x SWA last cycle	"	"	"	"	
6	Static	0	0			
7	Steady State	50	0			
8	Slowly Increasing Steer	50	40	Left	NA	
9	"	"	"	Left	"	
10	"	"	"	Left	"	
11	"	"	"	Right	"	
12	"	"	"	Right	"	
13	"	"	"	Right	"	
14	Fishhook 6.5 Scalar	35	160	Left	No	
15	II	40	"	"	"	
16	"	45	"	"	"	
17	"	47.5	"	"	"	
18	"	50	11	"	"	

Run Number	Test Type	Speed (mph)	Handwheel Angle (deg)	Dir. of First Steer	2 Wheel Lift	Notes
19	Fishhook 5.5 Scalar	45	135	Left	No	
20	"	47.5	"	"	"	
21	"	50	"	"	"	
22	Fishhook 6.5 Scalar	35	160	Right	"	
23	"	40	"	"	No	
24	"	45	"	"	"	
25	"	47.5	"	"	"	
26	"	50	"	"	"	
27	Fishhook 5.5 Scalar	45	135	Right	No	
28	"	47.5	"	"	"	
29	"	50	"	"	"	

APPENDIX C

Slowly Increasing Steer Test Worksheet

NCAP, 2021 Kia Seltos S FWD, Multi-Passenger Load,

Test Date: 4/21/2020

SIS_out_v2

Run	Dir of Steer	Start Speed (mph)	End Speed (mph)	Speed Red. (%)	Index of ay @ 0.3g	HW Angle (deg) at 0.3g	ay (g) @ 0.3g index	6.5x HW Angle (deg)	Ramp Time (sec) at 6.5x	5.5x HW Angle (deg)	Ramp Time (sec) at 5.5x	R2	Zero Begin Index	Zero End Index
8	L	49.8	0.2	99.6	1173	-24.7	-0.299	-160.4	-0.2228	-135.7	-0.1885	0.998	600	800
9	L	50.0	2.0	96.0	1174	-24.7	-0.306	-160.6	-0.2231	-135.9	-0.1888	0.9982	600	800
10	L	50.0	4.6	90.9	1173	-24.6	-0.299	-160.1	-0.2223	-135.4	-0.1881	0.9992	600	800
11	R	49.4	1.4	97.2	1173	24.8	0.300	160.9	0.2235	136.2	0.1891	0.9940	600	800
12	R	50.1	0.1	99.9	1167	24.4	0.308	158.5	0.2202	134.2	0.1863	0.9932	600	800
13	R	49.7	2.5	94.9	1172	24.7	0.300	160.6	0.2230	135.9	0.1887	0.9941	600	800

Mean: 24.6

0.302 160

0.222

136 0.188

Steering Controller Input Values

Scalar 6.5 values:		
Initial HW angle:	160	deg
Initial time:	0.222	S
Reversal HW angle:	-160	deg
Reversal time:	0.445	S
Scalar 5.5 values:		
Initial HW angle:	136	deg
Initial time:	0.188	S
Reversal HW angle:	-136	deg
Reversal time:	0.377	S

APPENDIX D

Time History Plots

LIST OF FIGURES

		Page
D1.	Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots	
	for Default Test Series, L-R, 50 mph	D-3
D2.	Steering Machine Operation Time History Plots for Default	
	Test Series, L-R, 50 mph	D-4
D3.	Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for	
	Default Test Series, L-R, 50 mph	D-5
D4.	Pitch Rate and Longitudinal Acceleration Time History Plots for	
	Default Test Series, L-R, 50 mph	D-6
D5.	Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots	
	for Default Test Series, R-L, 50 mph	D-7
D6.	Steering Machine Operation Time History Plots for	
	Default Test Series, R-L, 50 mph	D-8
D7.	Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for	
	Default Test Series, R-L, 50 mph	D-9
D8.	Pitch Rate and Longitudinal Acceleration Time History Plots for	
	Default Test Series, R-L, 50 mph	D-10
D9.	Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots	
	for Supplemental 2 Test Series, L-R, 50 mph	D-11
D10.	Steering Machine Operation Time History Plots for	
	Supplemental 2 Test Series, L-R, 50 mph	D-12
D11.	Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for	
	Supplemental 2 Test Series, L-R, 50 mph	D-13
D12.	Pitch Rate and Longitudinal Acceleration Time History Plots for	
	Supplemental 2 Test Series, L-R, 50 mph	D-14
D13.	Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots	
	for Supplemental 2 Test Series, R-L, 50 mph	D-15
D14.	Steering Machine Operation Time History Plots for	
	Supplemental 2 Test Series, R-L, 50 mph	D-16
D15.	Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for	
	Supplemental 2 Test Series, R-L, 50 mph	D-17
D16.	Pitch Rate and Longitudinal Acceleration Time History Plots for	
	Supplemental 2 Test Series, R-L, 50 mph	D-18

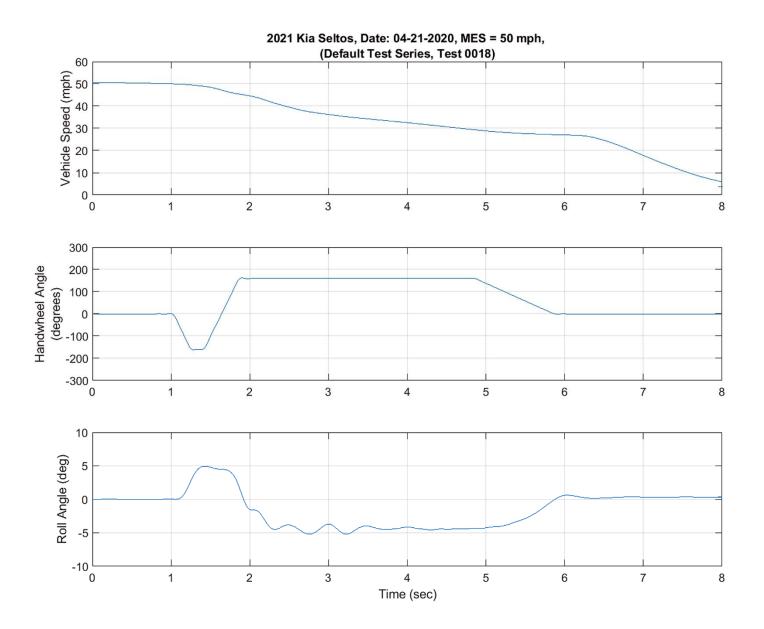


Figure D1. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, L-R, 50 mph

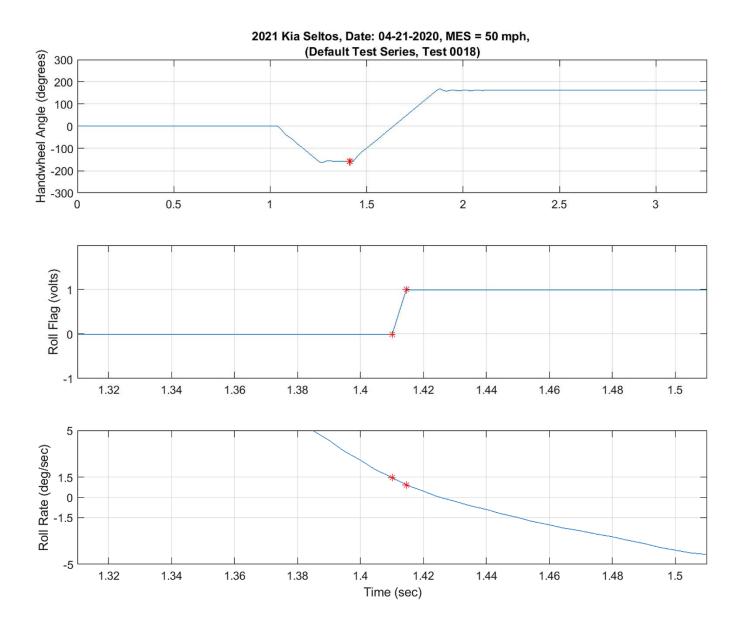


Figure D2. Steering Machine Operation Time History Plots for Default Test Series, L-R, 50 mph

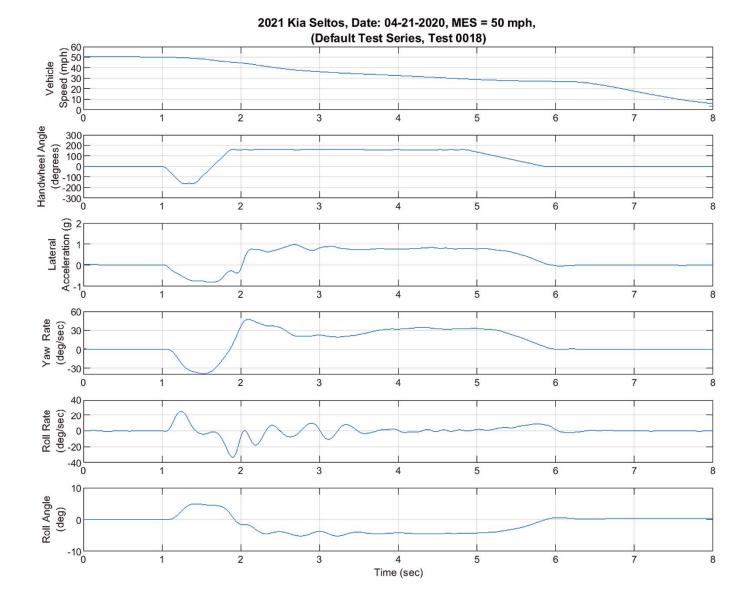


Figure D3. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots For Default Test Series, L-R, 50 mph

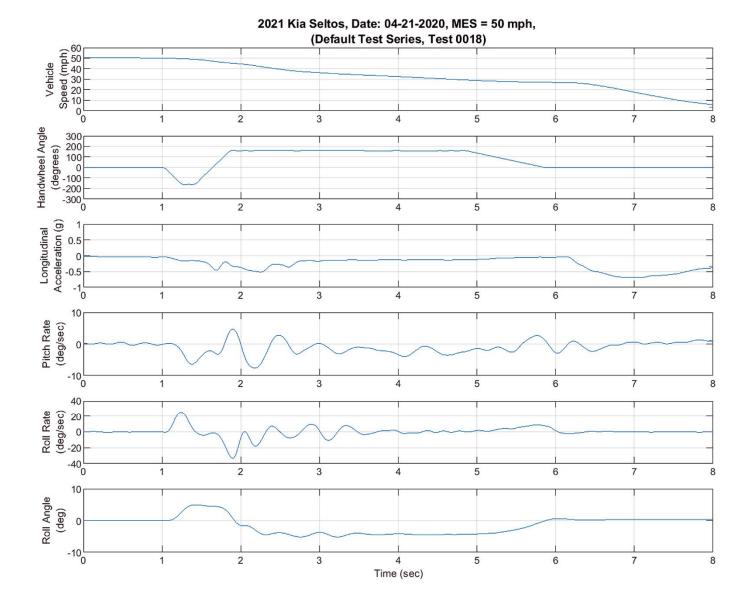


Figure D4. Pitch Rate and Longitudinal Acceleration Time History Plots for Default Test Series, L-R, 50 mph

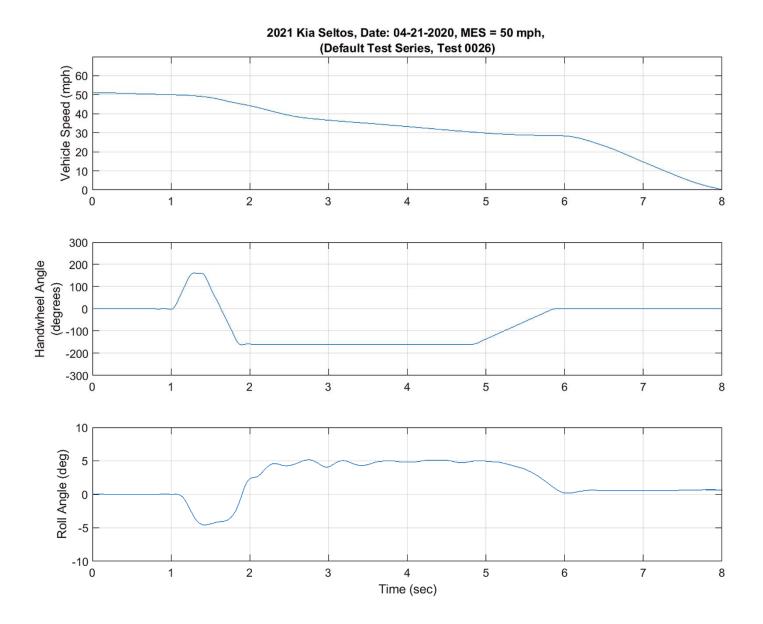


Figure D5. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Default Test Series, R-L, 50 mph

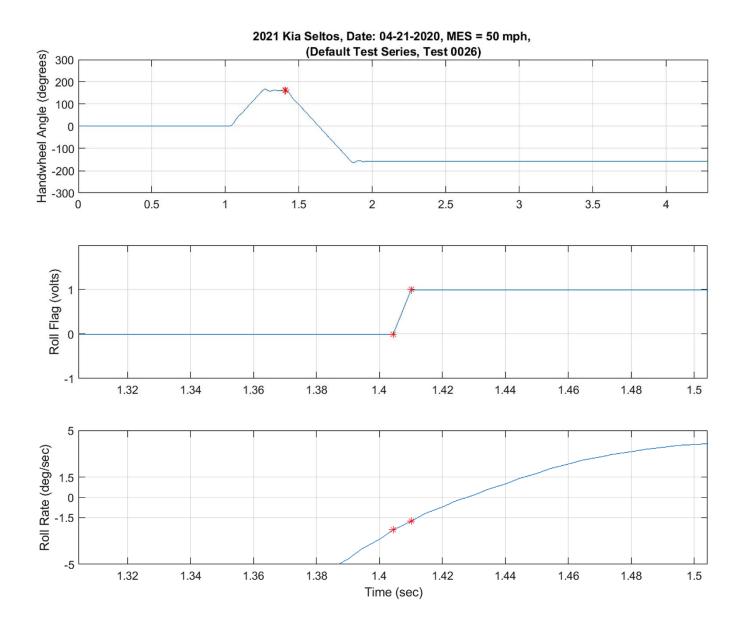


Figure D6. Steering Machine Operation Time History Plots for Default Test Series, R-L, 50 mph

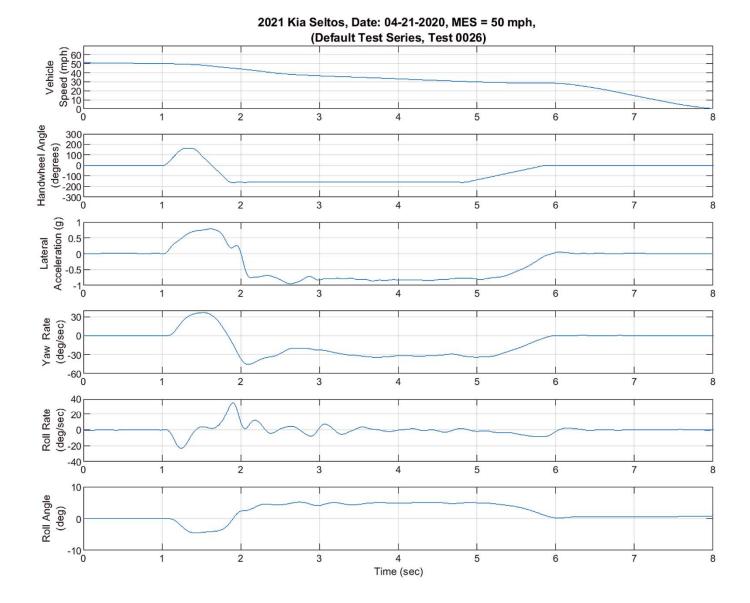


Figure D7. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Default Test Series, R-L, 50 mph

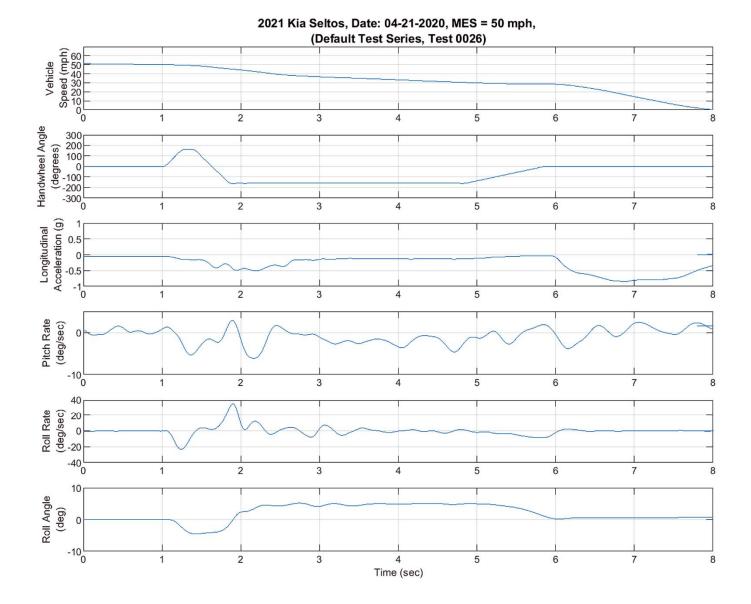


Figure D8. Pitch Rate and Longitudinal Acceleration Time History Plots or Default Test Series, R-L, 50 mph

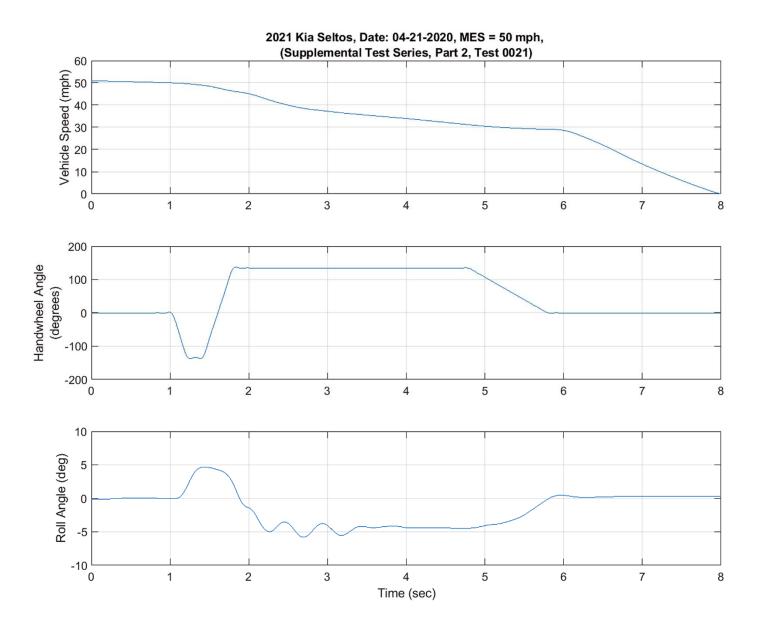


Figure D9. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

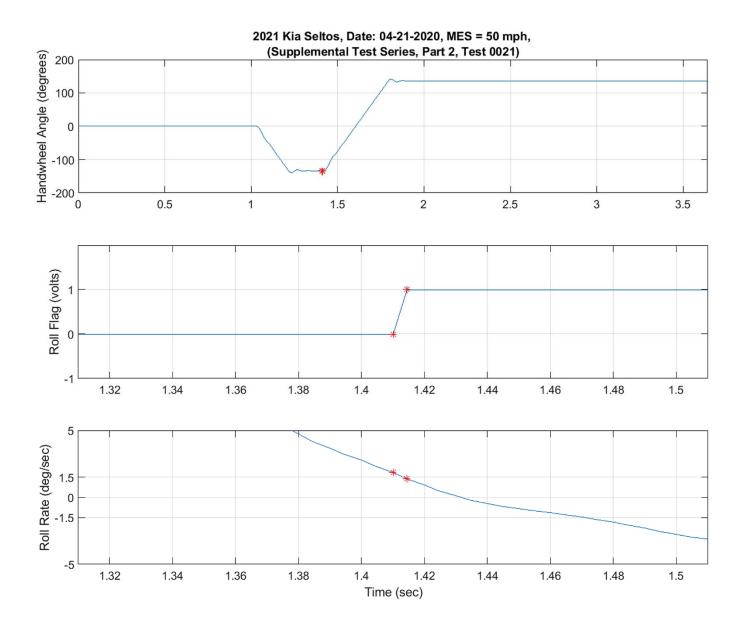


Figure D10. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

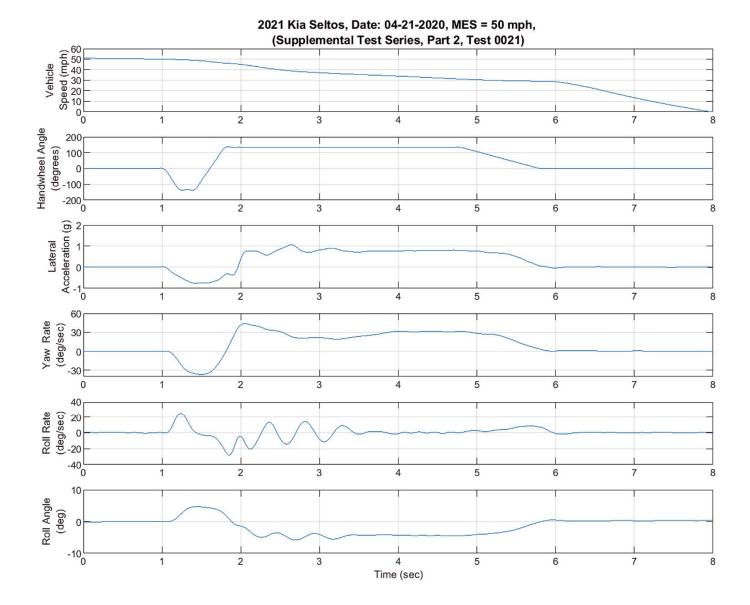


Figure D11. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

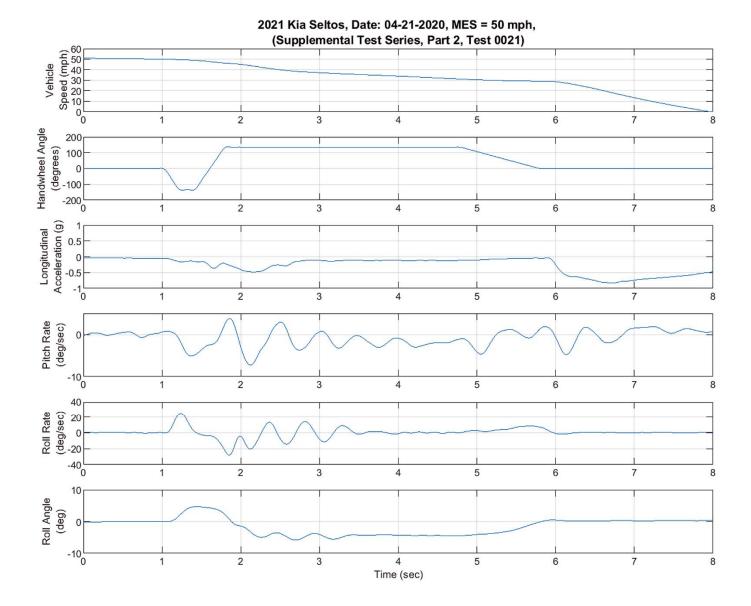


Figure D12. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, L-R, 50 mph

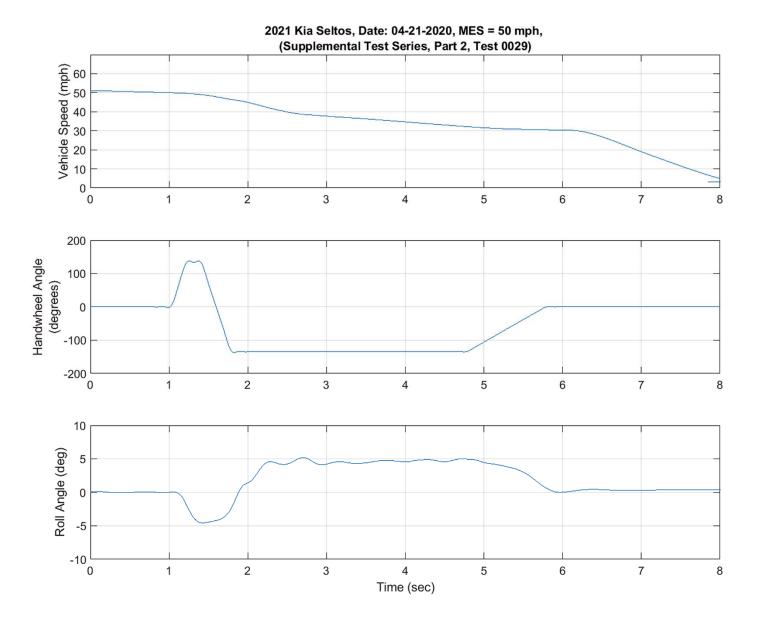


Figure D13. Vehicle Speed, Handwheel Angle, and Roll Angle Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

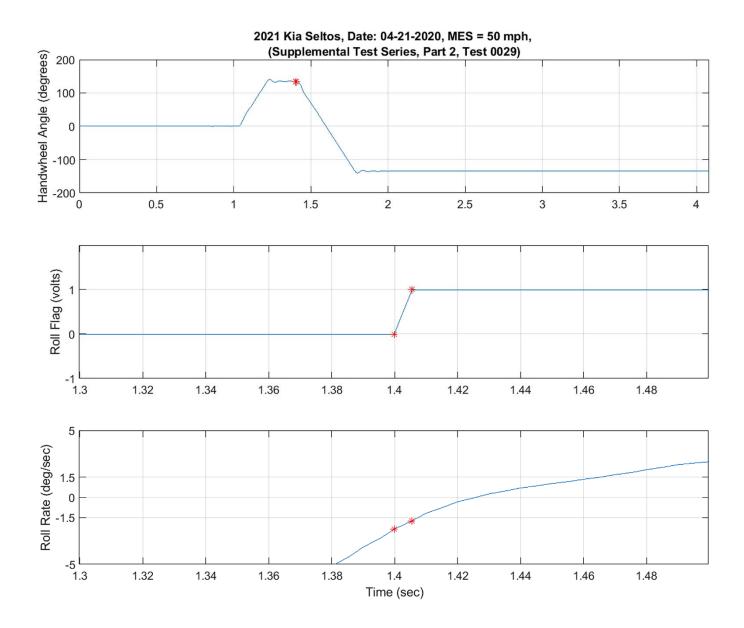


Figure D14. Steering Machine Operation Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

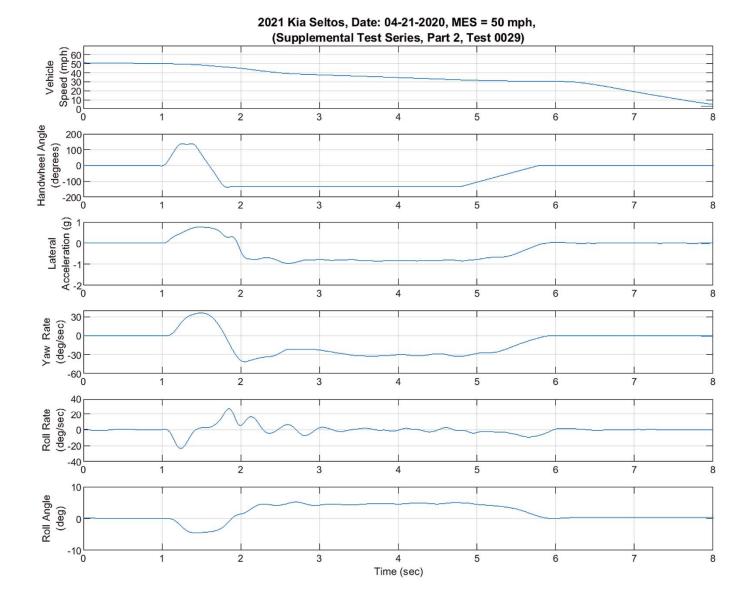


Figure D15. Yaw Rate, Roll Rate, and Lateral Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph

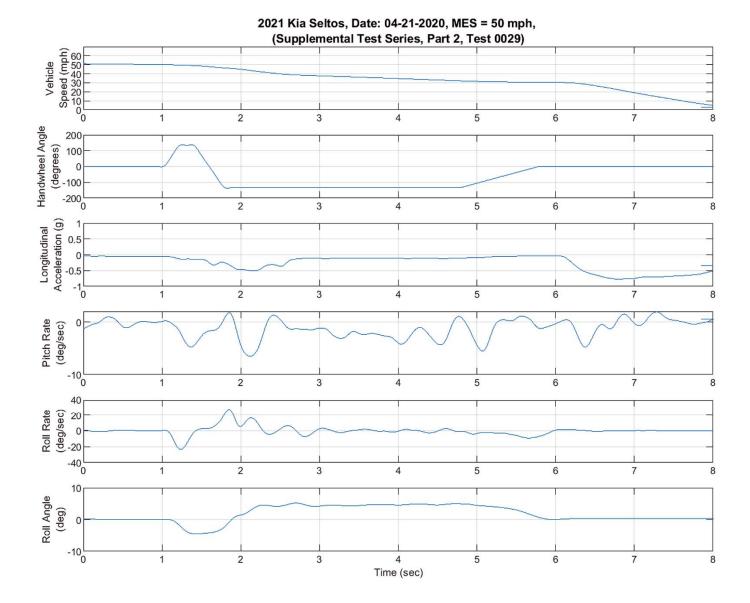


Figure D16. Pitch Rate and Longitudinal Acceleration Time History Plots for Supplemental 2 Test Series, R-L, 50 mph